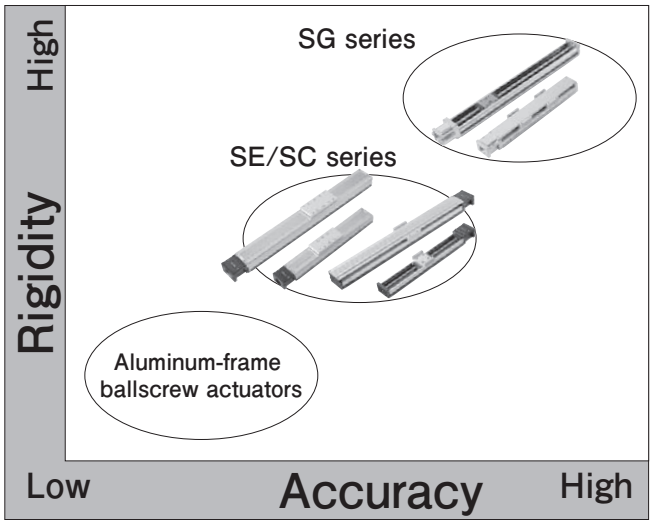
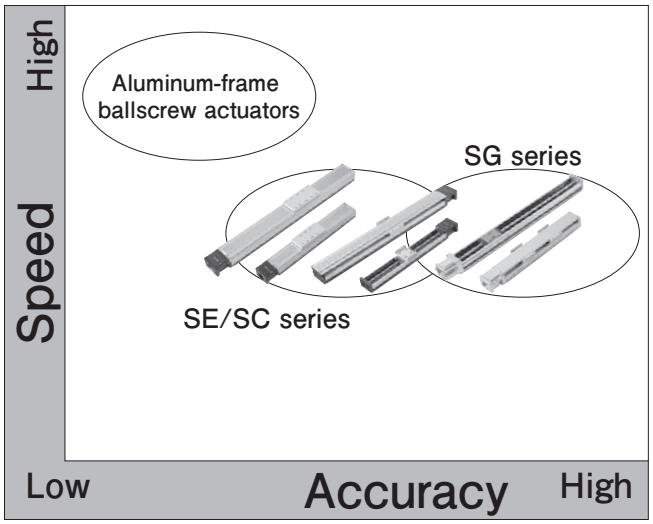
BALLSCREW ACTUATORS

A ballscrew actuator of KURODA is a compact single-axis unit consisting of a ball screw and a slide guide. With its slide block set in U-guide rail, the actuator has achieved low-profile design and compact shape, making it possible to considerably reduce necessary space as compared with the usual table type structure. Despite of its compact structure, the actuator with U-guide rail shows high rigidity against bending moment and deflection, and it can be applied to a structure supported by one end. The linear motion unit, which is gothic arched and in 4 points-contact structure, makes it possible to deliver high precision and high rigidity.

POSITIONS OF BALLSCREW ACTUATORS





WIDE VARIATIONS

Model No.		SG series						SE series				SC series (Note 2)		
		SG20	SG26	SG33	SG3320	SG46	SG55	SE15	SE23	SE30	SE45	SC23	SC30	SC45
Performance grade (Note 1)		P: Repeated positioning accuracy ±1μm H: Repeated positioning accuracy ±3μm						H: Repeated positioning accuracy ±3μm (Note 3) U: Repeated positioning accuracy ±5μm W: Repeated positioning accuracy ±10μm						
Screw shaft dia. (mm)		6	8	10	12	15	20	6	8	10	15	8	10	15
Lead (mm)	1	◎						◎						
	2		◎	●				◎	◎	●		◎	●	
	4								●	◎		●	◎	
	5	◎	◎	◎		●	●		◎	◎	◎	◎	◎	◎
	6									◎			◎	
	8								●			●		
	10			◎		◎	●			◎	◎		◎	◎
	20				◎	◎	◎			◎	◎		◎	◎

◎:In-stock items ●:Manufactured by order

(Note 1) The above table shows precision information on repeated positioning accuracy in particular, as an example. Performance of actuators may be different from the values shown above, depending on applied options and usage. For other precision information, refer to description pages for each series.

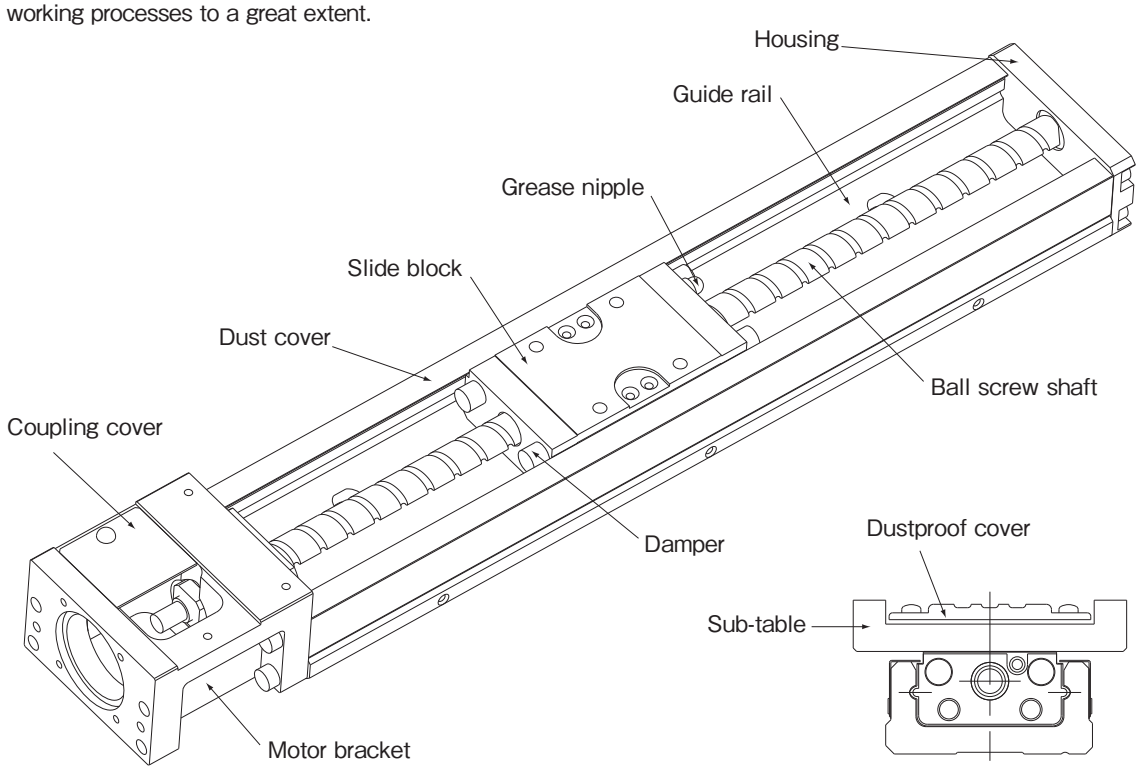
(Note 2) SC series is a full-cover version of SE series ballscrew actuators. For more information, refer to Front matters 5 to 6, and pages 99 to 121.

(Note 3) There is no Performance Grade H in SE30 and SC30 leads 6mm and 20mm.

FEATURES OF SG/SE SERIES

■ No necessity for adjustment

Ball screw and slide guide are integrated in ballscrew actuator, eliminating the need for complicated fine adjustment and reducing the number of working processes to a great extent.

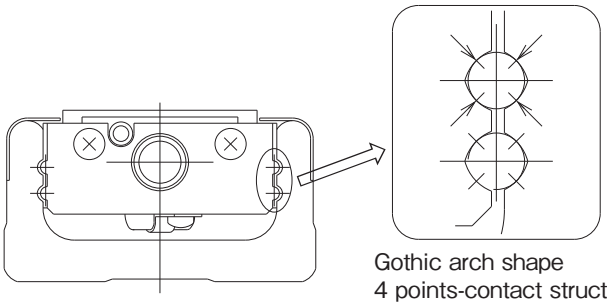


■ High rigidity

With U-guide rail, rigidity of ballscrew actuator has remarkably improved despite of its compact structure, making it possible to be applied even to a structure supported at only one end.

■ High accuracy

Linear motion unit uses "4 or 2 Ballway of 4 points-contact" structure to assure high rigidity. Guide rail, slide block and ball screw shaft are precisely worked, making accurate positioning possible.

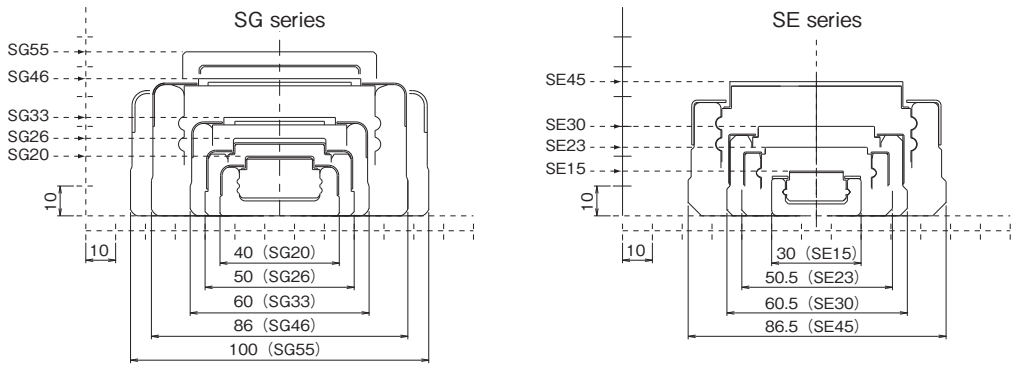


Gothic arch shape
4 points-contact structure

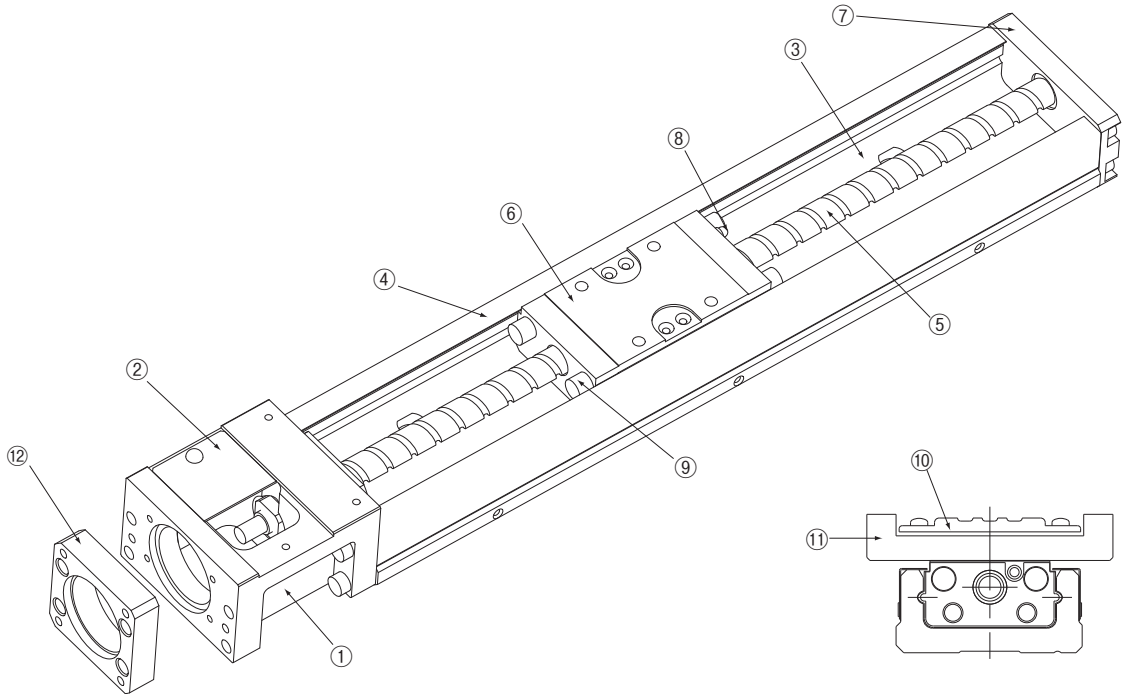
■ Space-saving

With its slide block set in U-guide rail, the actuator has achieved low-profile design and compact shape, making it possible to considerably reduce necessary space as compared with usual table type structure.

(Unit: mm)

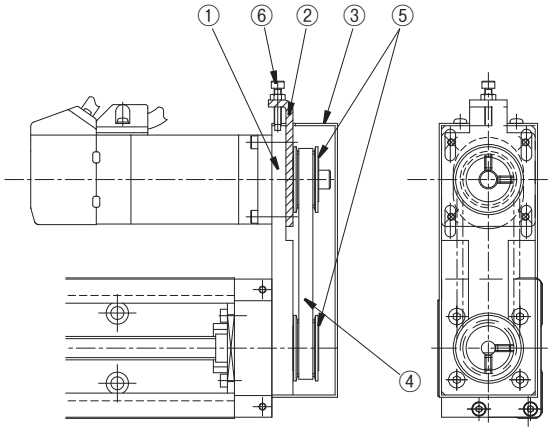


KEY COMPONENTS AND MATERIALS OF SG AND SE SERIES



No.	Part name	Material	Remarks
①	Motor bracket	Aluminum alloy	Anodized treatment or baking finish
②	Coupling cover	Aluminum alloy	Anodized treatment
③	Guide rail	Stainless steel (SG20, SG26) Carbon steel (SG33, SG46, SG55, SE15, SE23, SE30, SE45)	Black coating (Note 1)
④	Dust cover	Aluminum alloy	Anodized treatment
⑤	Ball screw shaft	Chromium-molybdenum steel (SG series) Carbon steel (SE series)	
⑥	Slide block	Chromium-molybdenum steel	
⑦	Housing	Aluminum alloy	Anodized treatment or baking finish
⑧	Grease nipple	Stainless steel	
⑨	Damper (Note 2)	Synthetic rubber	
⑩	Dustproof cover	Aluminum alloy	Anodized treatment
⑪	Sub-table	Aluminum alloy	Anodized treatment
⑫	Intermediate flange	Aluminum alloy (SG20, SG26, SE15, SE23, SE30, SE45) Carbon steel (SG33, SG46, SG55)	Anodized treatment Black coating

(Note 1) Guide rails made from stainless steel are not surface-treated.
(Note 2) Damper position of SG series is different from SE series. For more information, refer to dimensions of each series.
(Note 3) Stainless steel is used for bolts and machine screws to joint components of actuator.



No.	Part name	Material	Remarks
①	Motor mounting plate	Rolled steel	Black coating
②	Tension plate	Stainless steel	
③	Pulley cover	Stainless steel (SG series) Cold-rolled steel plate (SE/SC series)	Anti corrosive black coating (Note 4)
④	Timing belt	Resin	
⑤	Timing pulley	Aluminum alloy	
⑥	Tension bolt	Stainless steel	

(Note 4) Anti corrosive black coating of pulley cover applies to SE and SC series.

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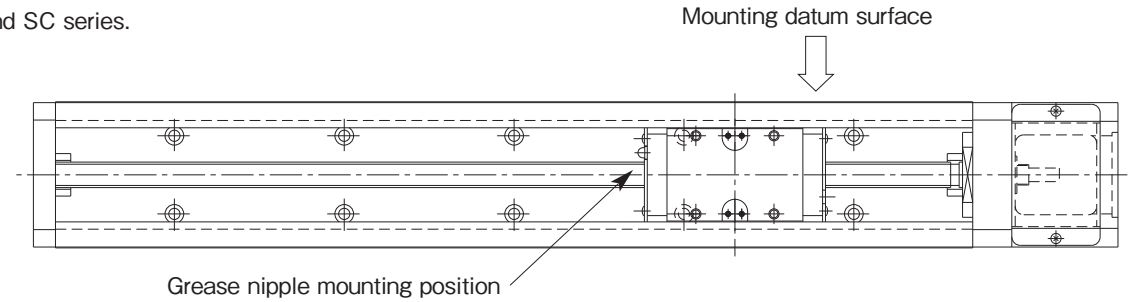
VARIATIONS OF SLIDE BLOCK

Two types of actuator with long block and short block are available. Additional types with either 2 long blocks or 2 short blocks are also available. Appropriate type can be selected from the variations according to your purpose of use.

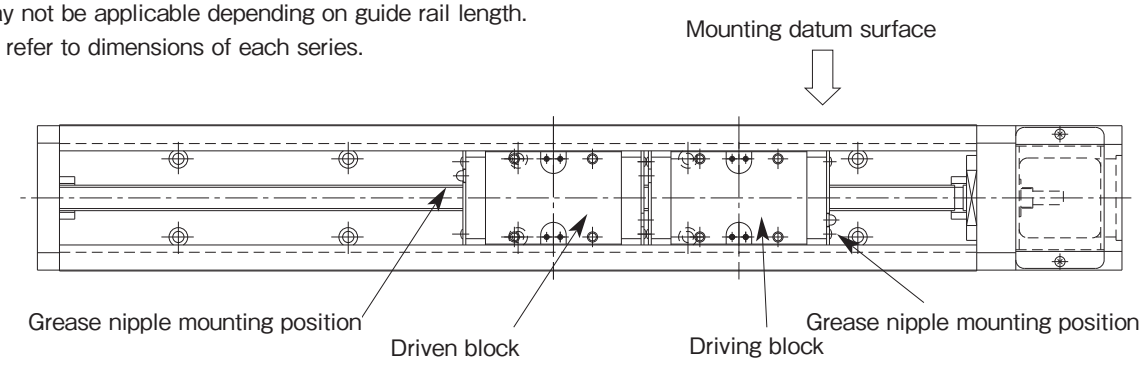
● With 1 long block: A

Applied to SG, SE, and SC series.



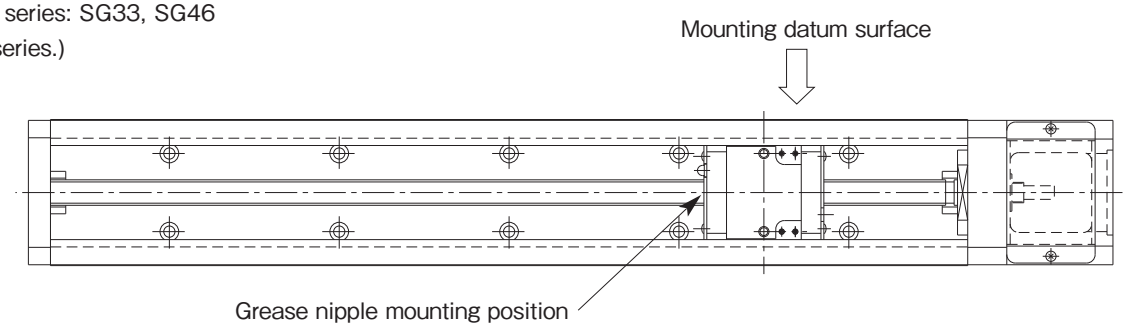
● With 2 long blocks: B

Applied to SG and SE series. (Not available for SC series.)
This configuration may not be applicable depending on guide rail length.
For more information, refer to dimensions of each series.



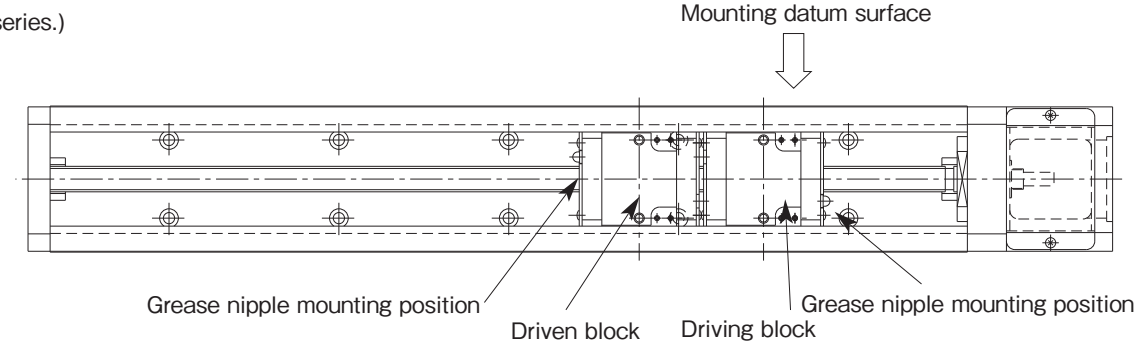
● With 1 short block: C

Applicable size in SE series: SE45
Applicable size in SG series: SG33, SG46
(Not available in SC series.)



● With 2 short blocks: D

Applicable size in SE series: SE45
Applicable size in SG series: SG33, SG46
(Not available in SC series.)



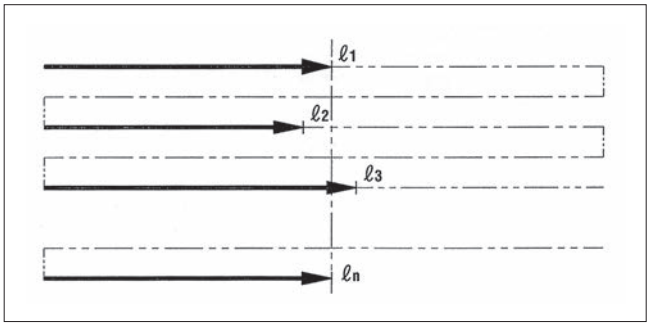
SUMMARY OF ACCURACY INDICATORS

Performance of ballscrew actuators are shown using various accuracy indicators described below.
For details in tolerance of the accuracy indicators, refer to table of performance (accuracy) information for each series.

● Repeated positioning accuracy

Repeat positioning of slide block in the same direction 7 times, measure stop position of slide block and halve maximum difference between obtained readings. Perform this measurement at the center and both ends of travel distance. Maximum value among obtained value is used as measured value.

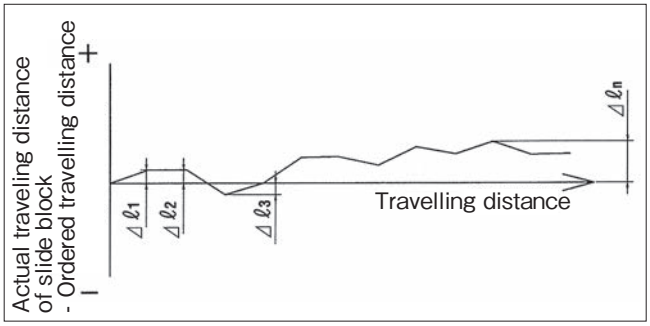
Repeated positioning accuracy
＝±1/2 ((maximum value of ℓn) - (minimum value of ℓn))



● Positioning accuracy

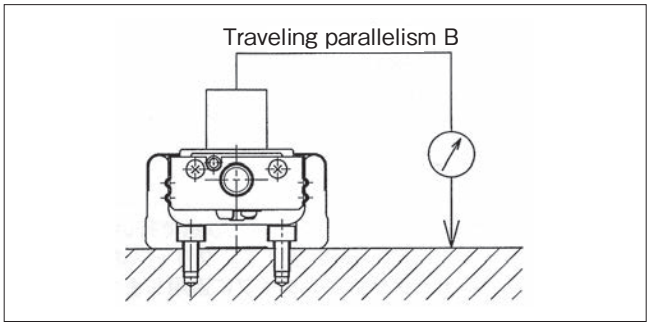
Position slide block properly in a fixed direction and use the obtained position as datum point. Perform positioning of slide block in the same direction and measure difference between actual traveling distance of slide block from datum point and distance ordered to be traveled from datum point. Perform this measurement throughout stroke range and use maximum value.

Positioning accuracy＝(Δ ℓn) max



● Traveling parallelism B

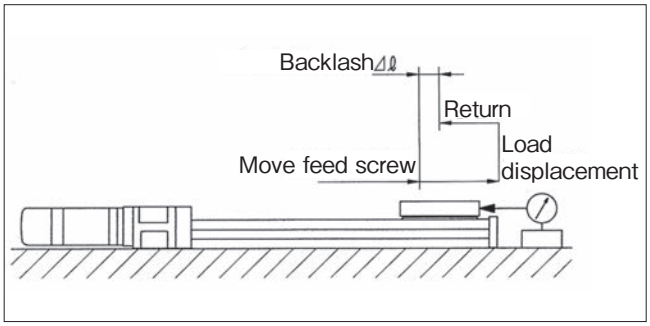
Fix indicator at the center of slide block and apply it to surface plate equipped with guide rail. Move slide block throughout traveling distance and use maximum distance among readings of test indicator as measured value.



● Backlash

Move slide block by rotating ball screw shaft and read test indicator when slide block is slightly moved and use its reading as reference value. Move slide block from this state in the same direction by pressuring prescribed load and measure difference between reading of test indicator with load removed and reference value. Perform this measurement at the center and both ends of traveling distance and use maximum value as a measured value.

Backlash＝Δ ℓ



⚠

・Firmly tighten the fixed part and connection of the ballscrew actuator.
Improper mounting of the body may adversely affect safety and accuracy depends on the circumstances.

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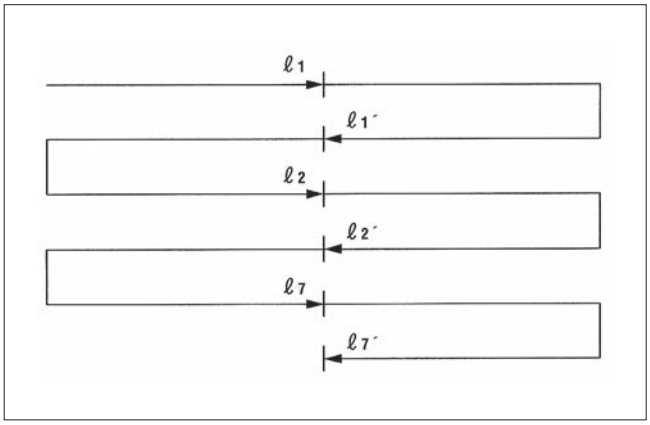
REFERENCE DATA ON ACCURACY

ACCURACY OF UNIT PRODUCT

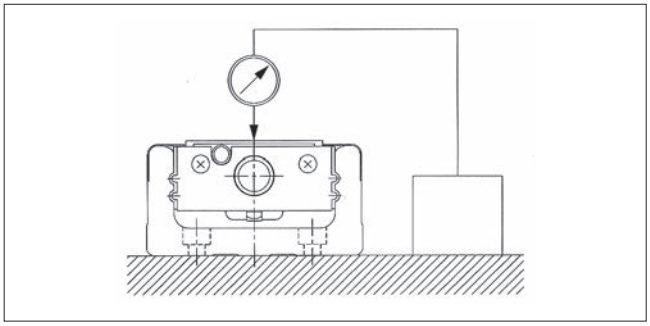
● Lost Motion

Perform positioning in a positive (or negative) direction and measure the position (ℓ_1). Move the slide block in the same direction and perform positioning in a negative (or positive) direction and measure the position (ℓ_1'). Move it further in the same direction and thereafter repeat the procedure in the positive and negative directions seven times each. Obtain the differences of the average values of the stop positions. Conduct this measurement for the entire moving range and use the obtained maximum value as a measured value.

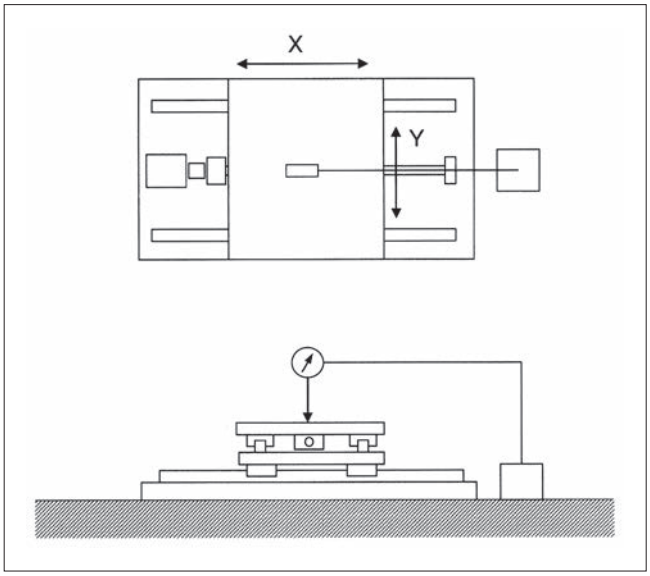


● Traveling Parallelism A

In the case of ballscrew actuators:
Set dial gauge on surface plate, fix indicator on top of slide block, obtain the maximum difference of dial gauge readings in measurable moving range in longitudinal direction of slide block. And use it as a measured value. Since the measurable range is small for ballscrew actuators, Traveling Parallelism B is used as the measurement method for all of the cases except for a few exceptions.



In the case of X-Y stages:
Set dial gauge on surface plate, fix indicator at the center of table, obtain the maximum difference of dial gauge readings in entire moving range in X-Y direction. The maximum difference is used as a measured value.

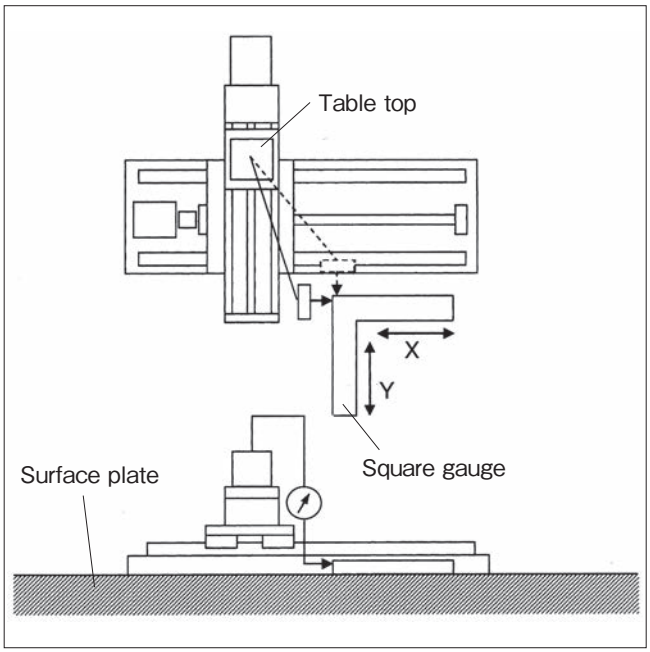


REFERENCE DATA ON ACCURACY

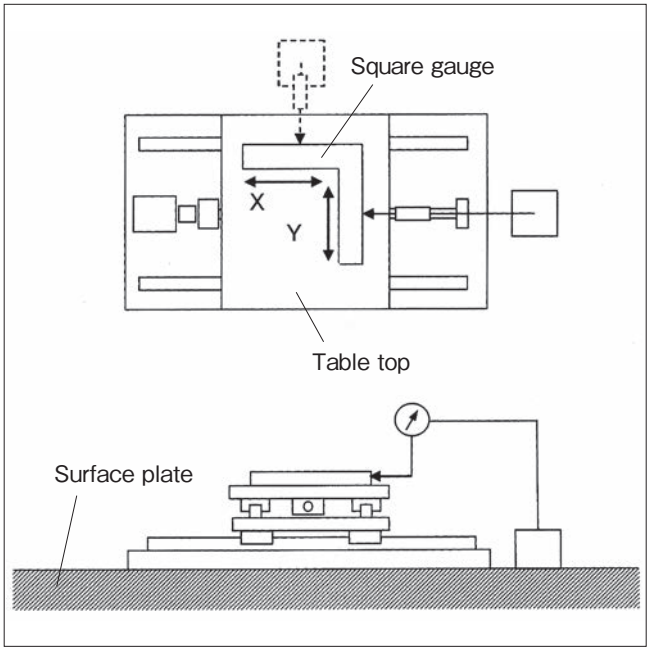
ACCURACY OF UNIT PRODUCT

● Squareness

In case squareness cannot be measured on the table top:
Set a dial gauge on the table top. On surface plate close to the table travel range, fix a square gauge in parallel to X (or Y) travel direction.
Place a fix indicator against the side of square gauge parallel to Y (or X) travel direction. The maximum reading value of the dial gauge in the entire travel range is a measured value of squareness.



In case squareness can be measured on the table top:
Set a dial gauge on surface plate. On the table top, fix a square gauge in parallel to X (or Y) travel direction.
Place a fix indicator against the side of square gauge parallel to Y (or X) travel direction. The maximum reading value of the dial gauge in the entire travel range is a measured value of squareness.



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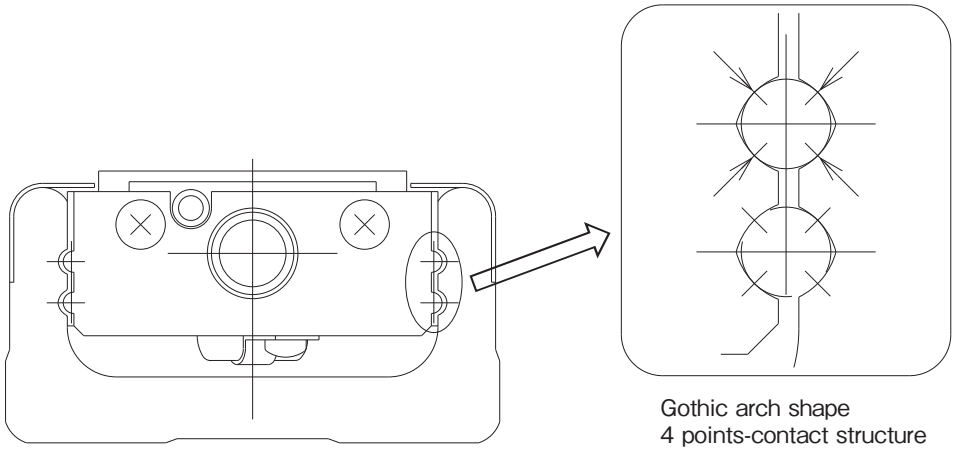
RIGIDITY

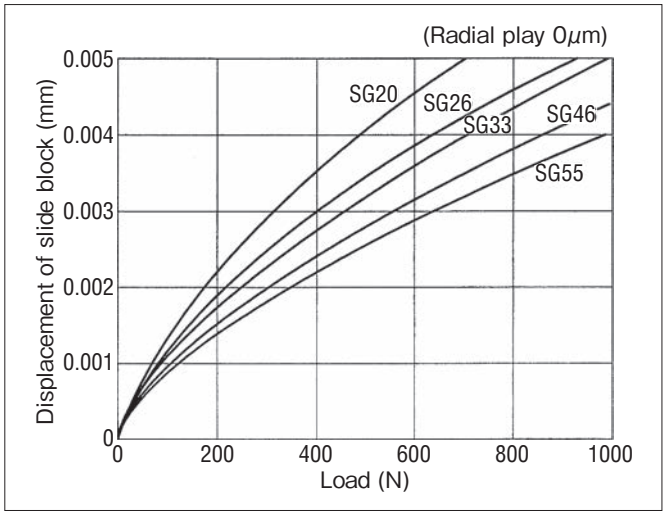
Linear motion units of SG, SE, and SC series, having gothic-arched grooves and 4 points-contact structure on guide rails and slide blocks, have attained high rigidity. Displacement by each radial load in each size with long block configuration is shown below as a reference.



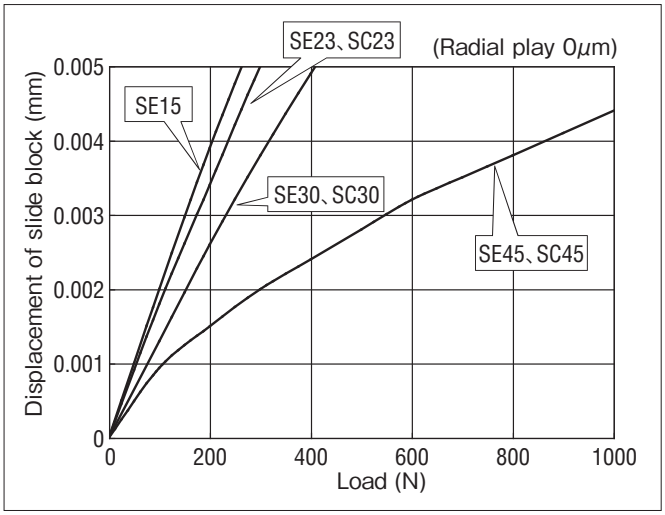
Gothic arch shape
4 points-contact structure

● Displacement of Slide block by Radial Load

SG series



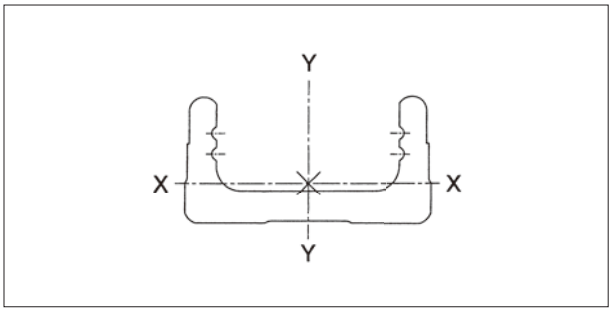
SE/SC series



● Sectional Secondary Moment of Guide Rail

The following table shows sectional secondary moments of guide rails in each size.

Model No.	Sectional secondary moments (mm^4)		Mass (kg/100mm)
	I_X (X axis)	I_Y (Y axis)	
SG20	6.50×10^3	6.00×10^4	0.250
SG26	1.69×10^4	1.47×10^5	0.380
SG33	5.11×10^4	3.42×10^5	0.600
SG46	2.42×10^5	1.49×10^6	1.240
SG55	2.29×10^5	2.28×10^6	1.500
SE15	2.71×10^3	2.36×10^4	0.147
SE23, SC23	1.44×10^4	1.37×10^5	0.410
SE30, SC30	3.88×10^4	3.14×10^5	0.560
SE45, SC45	1.45×10^5	1.26×10^6	1.110



OPTION AND MANUFACTURING BY ORDER

Category	Item		SG series					SE series				SC series		
			SG20	SG26	SG33	SG46	SG55	SE15	SE23	SE30	SE45	SC23	SC30	SC45
Option	Motor bracket configu-ration	Intermediate flange	○	○	○	○	○	○	○	○	○	○	○	○
		R0/RN type bracket (Note 1)	○	○	○	○	○	—	—	○	○	—	○	○
		Parallel motor mounting unit	—	—	○	○	—	—	—	○	○	—	○	○
	Type of cover	Dustproof cover	○	○	○	○	○	○	○	○	○	—	—	—
		Standard full-cover (Note 2)	—	—	—	—	—	—	—	—	—	○	○	○
		Full-cover with grease nipple (Note 2)	—	—	—	—	—	—	—	—	—	○	○	○
		Full-cover with wiper (Note 2)	—	—	—	—	—	—	—	—	—	○	○	○
		Full-cover with grease nipple and wiper (Note 2)	—	—	—	—	—	—	—	—	—	○	○	○
	Sensor	Photo-microsensor Ass'y	○	○	○	○	○	—	○	○	○	○	○	○
		Proximity sensor Ass'y	○	○	○	○	○	○	○	○	○	○	○	○
	Sensor rail Ass'y		○	○	○	○	○	○	○	○	○	○	○	○
	Surface treatment (Note 3)		○	○	○	○	○	○	○	○	○	○	○	○
	Dust preventive grease		○	○	○	○	○	○	○	○	○	○	○	○
	Dowel pin hole (slide block)		○	○	○	○	○	—	○	○	○	—	—	—
	Dowel pin hole (guide rail)		○	○	○	○	○	—	○	○	○	○	○	○
	Lubrication unit LUBSEAL™		—	—	—	—	—	—	○	○	○	○	○	○
	Reversed guide rail reference surface		—	—	—	—	—	○	○	○	○	○	○	○
	Sub guide rail		—	—	—	—	—	○	○	○	○	○	○	○
Manufactured by order (Note 8)	Intermediate stroke		●	●	●	●	●	●	●	●	●	●	●	●
	Oil hole (Note 4)		●	●	●	●	●	—	●	●	●	—	—	—
	XY bracket		●	●	●	●	●	●	●	●	●	●	●	●
	Motor assembling		●	●	●	●	●	●	●	●	●	●	●	●
	Long rail configuration		●	●	●	●	—	●	●	●	●	●	●	●
	Grease options (Note 5)		●	●	●	●	●	●	●	●	●	●	●	●
	Motor bracket configuration (Note 6)		●	●	●	●	●	●	●	●	●	●	●	●
	Sensor options (Note 7)		●	●	●	●	●	●	●	●	●	●	●	●

○: Option —: Not available ●: Manufactured by order

(Note 1) R0 type bracket is applied to SG series and RN type is applied to SE and SC series.

(Note 2) Full-cover type with wiper and with grease nipple is applied only to SC series.

(Note 3) Anti corrosive black coating (film thickness 1-2μm) is provided as surface treatment.

(Note 4) Oil hole for SG and SE series is applied to the configuration with sub-table.

(Note 5) Any grease application other than standard or option grease applications will be provided on a manufactured by order basis.

(Note 6) Ballscrew actuator with motor bracket or intermediate flange configuration other than standard or option configuration will be provided on a manufactured by order basis.

(Note 7) Ballscrew actuator requiring a sensor other than option configuration or two sensors attached on both ends will be provided on a manufactured by order basis.

(Note 8) For ballscrew actuators to be provided on a manufactured by order basis, specifications will be determined after consultation with customers. Please consult KURODA after completing the Specification Data Sheet attached at the end of this catalog.

HOW TO INTERPRET MODEL NO.

Model No.	Lead	Slide block		Guide rail length	Performance grade		Motor bracket configuration	Type of cover	Sensor		Surface treatment	Grease		Dowel pin hole
SG33	10	A	–	500	P	–	A1	C	C	–	N	N	–	PS
①	②	③		④	⑤		⑥	⑦	⑧		⑨	⑩		⑪

Model No. of Main Body

Model No. of Option

① Model of ballscrew actuator

The 2-digits number represents height of mounting surface, from the bottom face of guide rail to top face of slide block. (For SG/SE series with dustproof cover and SC series, Model No. of the unit used as base of the body is shown.)

SG series	SG20	SG26	SG33	SG46	SG55
SE series	SE15	SE23	SE30	SE45	
SC series	SC23	SC30	SC45		

② Lead of ball screw

Permissible speed varies depending on the lead. For more information, refer to dimensions of each series.

Lead	SG series					SE series				SC series		
	SG20	SG26	SG33	SG46	SG55	SE15	SE23	SE30	SE45	SC23	SC30	SC45
1mm	○					○						
2mm		○				○	○			○		
4mm								○			○	
5mm	○	○	○				○	○	○	○	○	○
6mm								○			○	
10mm			○	○				○	○		○	○
20mm			○	○	○			○	○		○	○

③ Variation of slide blocks and number of blocks to be mounted

For configuration with 2 slide blocks, a driving block and driven block in combination is mounted. For more information, refer to dimensions of each series.

④ Guide rail length

For more information, refer to dimensions of each series. Please note that the guide rail length is different from overall length or maximum stroke length of actuator.

Model No.	Standard guide rail length										
SE15	100	150	200								
SE23	150	200	250	300							
SE30	150	200	300	400	500	600	700	750(Note2)			
SE45	340	440	540	640	740	840	940				
SC23	150	200	250	300							
SC30	150	200	300	400	500	600	700	750(Note2)			
SC45	540	640	740	840	940						
SG20	100	150	200								
SG26	150	200	250	300							
SG33	150	200	300	400	500	600(Note1)					
SG46	340	440	540	640	740	840(Note1)	940(Note1)	1040(Note1)	1140(Note1)	1240(Note1)	
SG55	980	1080	1180	1280(Note1)	1380(Note1)						

(Note 1) Only available in Performance Grade H.
(Note 2) Guide rail length 750mm for SE30 and SC30 is only available in lead 10mm.

⑤ Performance of ballscrew actuators, including various positioning accuracy indicators and traveling parallelism

For more information on accuracy, refer to a table of accuracy information for each series.

⑥ Motor bracket configuration

Intermediate flange may be used in combination with basic configuration. For more information, refer to a table of motor bracket configurations and motor option for each series.

⑦ Type of cover

For more information, refer to dimensions of each series.

⑧ With or without sensor / type of sensor

For more information, refer to dimensions of each series.

⑨ With or without surface treatment applied on guide rails and ball screws

With standard specifications (Symbol N), only guide rails are treated with black coating (except for guide rails made from stainless steel).

⑩ Type of grease applied on slide blocks and ball screws of ballscrew actuators

With standard specifications, Multemp PS No.2 Grease (KYODO YUSHI CO., LTD.) is contained.

⑪ Additional options such as reversed reference surface and dowel pin holes

Left blank when additional options are not included.

FOR SAFETY USE

Be sure to read the following instructions before use.
For common instructions, refer to the text of this catalog.

The following safety precautions recommend the correct usage of our products to prevent an injury and a damage.
These precautions are classified into 3 categories : "DANGER","WARNING" and "CAUTION" according to the degree of possible injury or damage and the degree of impendence of such injury or damage.
Be sure to follow all these precautions, as they include important contents regarding safety.

DANGER	WARNING	CAUTION
Indicates an impending hazardous situation that may arise due to improper handling or operation and could result in a serious injury or death.	Indicates a potentially hazardous situation that may arise due to improper handling or operation and could result in a serious injury or death.	Indicates a potentially hazardous situation that may arise due to improper handling or operation and could result in an injury or property damage only.

Be sure to obey "Labor Safety and Sanitation Law" and other safety rules and regulations in addition to these precautions.
There is some situation that may lead to a serious result according to circumstances, even if it is mentioned in the category of "CAUTION". Be sure to follow these precautions, as they contain important matters.

WARNING

- **Select a ballscrew actuator properly.**
  As operating conditions for products mentioned in this catalog are diversified, the applicability of ballscrew actuator to the intended system should be determined by the total system designer or the person who determined specifications for such system after conducting an analysis and testing as necessary.
  The person who determined the applicability of the system shall be responsible for assuring the intended system performance and safety. When configuring a system, the system designer should thoroughly examine all specifications for such a system by referring to the latest product catalog and data, and also take into consideration the possibility of equipment troubles.

- **The ballscrew actuator should be handled by persons who have sufficient knowledge and rich experience.**
  Thoroughly read this catalog and operation manual before use.
  · Never disassemble the ballscrew actuator. Dust can enter the inside, degrading the accuracy of the module and causing an accident. When the ballscrew actuator has been disassembled from necessity, return it to our company for repair and reassembling. (In this case, repairing charges are required.)
  · When mounting a ballscrew actuator to a machine and dismounting it from machine, check that a fall prevention means has been taken and the moving part of the machine has been fixed beforehand.

- **When using the ballscrew actuator in the following conditions or environments, take the proper safety measures and consult KURODA beforehand.**
  · Conditions and environments other than specified and outdoor use.
  · Applications to nuclear power equipment, railroads aircraft, vehicles, medical equipment, equipment connected with food and drink, and the likes.
  · Applications which require extreme safety and will also greatly affect men and property.

- **During operation, make sure to keep your hands away from either of stroke ends, where slide block moves, to prevent your finger from being caught.**

- **During operation, make sure to keep your hands away from screws and axis terminals of ball screw shaft, which are rotating parts, to prevent your hands from being caught.**

- **Pay adequate attention not to allow the actuators to be used for military purpose including for arms and weapons.**

BALLSCREW ACTUATOR/COMMON INSTRUCTIONS

Be sure to read the following instructions before use.
Also refer to "FOR SAFETY USE".

DESIGN

⚠ WARNING

- **Especially when there is the possibility that the ballscrew actuator is dangerous to the human body, provide it with a protective cover.**

  When there is the possibility that the load and the moving part of the ballscrew actuator are dangerous to the human body, design the structure to prevent the human body from touching such load and moving part directly.

- **Firmly tighten the fixed part and connection of the ballscrew actuator.Improper mounting of the body may adversely affect safety and accuracy according to circumstances.**

- **Take into consideration the behavior of the ballscrew actuator in an emergency.**

  When the machine is immediately stopped in an emergency by a person or by a safety device in case of power failure or system trouble, the motion of the module can injure the human body and can damage the machine. So design the machine to prevent an injury to the human body and a damage to the machine.

SELECTION

⚠ WARNING

- **Check specifications.**

  Be sure to use the ballscrew actuator within the given specifications.

- **When selecting a rigid type as coupling for connecting a motor, consult KURODA.**

MOUNTING

⚠ CAUTION

- **Be careful not to dent and flow the body and the mounting surface of the table, side cover, and center sheet.**

  Such dent or flaw will degrade parallelism of mounting surface, resulting in rattling of the guide and increased slide resistance. Note that, since the center sheet of SC series are very thin, such dent or flaw may ruin its dust preventive capability or lead to damage of the sheet function.

- **When connecting the ballscrew actuator to a load with an external support or guide, do so in accordance with a proper connecting method and perform centering satisfactorily.**

- **When mounting a load, do not apply an excessive shock or moment.**

  If the ballscrew actuator receives external force exceeding the permissible moment, the guide will loosen and sliding resistance will increase.

- **Do not start the system until it is confirmed that the ballscrew actuator works properly.**

  After mounting the ballscrew actuator, perform an appropriate functional test and make sure that it is correctly mounted and works safely without fail before starting the system.

- **Although corners of components, such as motor bracket, housing, side cover, and center sheet, are beveled, pay enough attention not to hurt yourself when handling them.**

OPERATING ENVIRONMENT

⚠ DANGER

- **Do not use the ballscrew actuator in a place where an explosive atmosphere exists.**

⚠ WARNING

- **Do not use the ballscrew actuator in an atmosphere containing corrosive gases, chemicals, seawater, water and vapor and in a place where it can be stained with such matters.**

- **When using the ballscrew actuator in a place where it is exposed to dust, cuttings, spatters, etc., fit a protective cover or other protector.**

- **Do not use the ballscrew actuator in a vibratory or shockable place ; otherwise causing a bad condition or breakdown.**

  When using the ballscrew actuator in such an environment, consult KURODA.

⚠ CAUTION

- **Since the SC series is equipped with sheet magnet on side covers for attracting center sheet to keep its position, be careful not to have the magnet contaminated with iron power or metallic fragments.**

LUBRICANTS

⚠ CAUTION

- **Unless otherwise specified, the nut contains Multemp PS No.2 Grease (KYODO YUSHI CO., LTD.) as a lubricant.**

- **Checking and supplying lubricant**

  Check the lubricant 2 to 3 months after the ball screw is used for the first time. If it is extremely dirty, wipe off old grease and apply new grease. Then, check and supply the lubricant once every year as a general rule. However, as the service life of lubricants varies according to operating conditions and environment, adjust the intervals properly.

  When feeding additional grease (lubricant), use the same brand of grease as initially contained.

  With SC series, a central grease filler hole (M3) is provided on side surface of table, making it possible for the grease to be supplied to ball screw and guide through the filler hole.

  Supply additional grease as necessary, preferably with the interval indicated above. When adding grease, 2 dispenses by grease gun (approx. 1 to 2 cc) should be supplied.

  After supplying additional grease, operate the table to the extent of full stroke to apply the grease over the component. Wipe off excess grease attached around the central grease filler hole.

- **Do not use at high temperature over 60 celsius degree.**

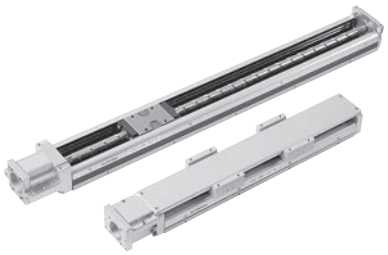
  As resin is used in ballscrew actuator, use at lower temperature than 60 celsius degree. For ballscrew actuator with sensor, use at lower temperature than 55 celsius degree.

CONTENTS

HIGH ACCURACY BALLSCREW ACTUATORS/SG SERIES

VARIATIONS

Model No.		SG20	SG26	SG33	SG3320	SG46	SG55
Performance grade		P: Repeated positioning accuracy ±1μm* H: Repeated positioning accuracy ±3μm*					
Screw shaft dia. (mm)		6	8	10	12	15	20
Lead (mm)	1	◎					
	2		◎	●			
	5	◎	◎	◎		●	●
	10			◎		◎	●
	20				◎	◎	◎



◎: In-stock items ●: Manufactured by order

(Note 1) Asterisked (*) items may be different from the values shown above, depending on applied options and usage.

HOW TO INTERPRET MODEL NO.

SG33	05	A	-	150	P	-	A1	N	N	-	N	N	-	PS
①	②	③		④	⑤		⑥	⑦	⑧		⑨	⑩		⑪

① Model ② Lead

① Model	② Lead
SG20	1, 5
SG26	2, 5
SG33	5, 10, 20
SG46	10, 20
SG55	20

③ Slide block

Model	Slide block
SG20	A: With 1 long block B: With 2 long blocks
SG26	A: With 1 long block B: With 2 long blocks
SG33 (NOTE 1)	A: With 1 long block B: With 2 long blocks C: With 1 short block D: With 2 short blocks
SG46	
SG55	A: With 1 long block B: With 2 long blocks

④ Guide rail length (NOTE 2) (NOTE 3)

Model	Guide rail length (mm)
SG20	100, 150, 200
SG26	150, 200, 250, 300
SG33	150, 200, 300, 400, 500, 600*
SG46	340, 440, 540, 640, 740, 840*, 940*, 1040*, 1140*, 1240*
SG55	980, 1080, 1180, 1280*, 1380*

⑤ Performance grade

P	Repeated positioning accuracy±1μm
H	Repeated positioning accuracy±3μm

⑥ Motor bracket configuration

Model	Motor bracket configuration
SG20	A0, A1, A3, A5, A6, A8, A9, AA, R0
SG26	A0, A1, A3, A5, A6, A8, A9, AA, R0
SG33	A0, A1, A2, A3, A4, A5, A6, A7, B1, B2, R0, E□, F□
SG46	A0, A1, A2, A3, A4, B0, C0, D0, R0, E□, F□, G□
SG55	A0, A1, A2, A3, A4, R0

⑦ Type of cover

N	Without cover
C	With cover
L	Low housing

⑧ Sensor

Model	Sensor
SG20	N: Without sensor S: Photo-microsensor K, E: Proximity sensor 1: For sensor rails only
SG26	
SG33	Without sensor M, Y, C, P, H, J: Photo-microsensor K, E: Proximity sensor 1, 2, 3: For sensor rails only
SG46	
SG55	

⑨ Surface treatment (Note 4)

N	Standard treatment
L	Anti corrosive black coating

⑩ Grease (Note 5)

Model	Grease
SG20	N: Standard grease S: Dust preventive KURODA S grease
SG26	
SG33	
SG46	
SG55	

⑪ Additional options

Blank	No dowel pin hole
PS	For slide block only
PR	For guide rail only
PSR	For both slide block and guide rail

(Note 1) Short slide block type (Symbol: C, D) is not available in lead 20mm.

(Note 2) For specifications of guide rail with long rails or intermediate stroke with non-standard length, consult KURODA.

(Note 3) Asterisked (*) items in the table apply only to performance grade H.

(Note 4) With standard surface treatment (Symbol: N), guide rails of SG20 and SG26 are not treated with anti corrosive coating. For SG33, SG46 and SG55, only guide rails are treated with black coating as the standard surface treatment.

(Note 5) With standard grease (Symbol: N), Multemp PS No.2 Grease (KYODO YUSHI CO., LTD.) is contained in slide block and ball screw components.

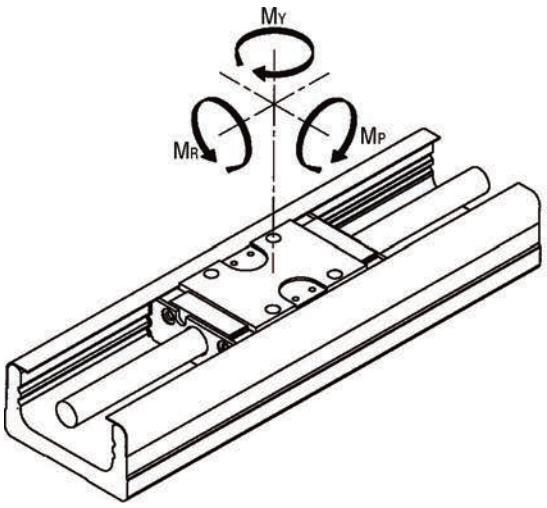
SPECIFICATIONS

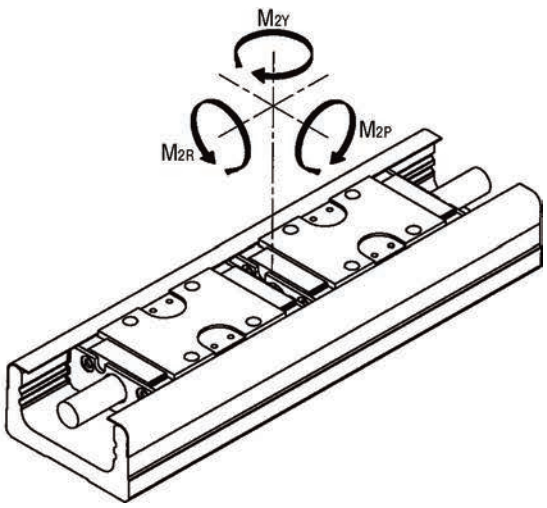
Model No.					SG2001		SG2005		SG2602		SG2605		SG3305		SG3310		SG3320		SG4610		SG4620		SG5520	
Performance grade					H	P	H	P	H	P	H	P	H	P	H	P	H	P	H	P	H	P	H	P
Guide	Radial clearance			μm	-3~0	-6~-3	-3~0	-6~-3	-4~0	-8~-4	-4~0	-8~-4	-3~0	-7~-3	-3~0	-7~-3	-3~0	-7~-3	-5~0	-11~-5	-5~0	-11~-5	-6~0	-18~-6
	Long block	Basic dynamic load rating	C	kN	4.27				7.78				12.6						29.8				43.2	
		Basic static load rating	Co	kN	7.89				14.98				22.7						51.2				74.0	
		Static permissible moment	M_P	N·m	35				99				181						610				1,088	
			M_{2P}		199				550				1,035						3,285				5,465	
			M_Y		42				118				215						727				1,297	
			M_{2Y}		237				656				1,233						3,914				6,513	
			M_R		101				255				500						1,612				2,701	
			M_{2R}		201				509				1,000						3,224				5,402	
	Short block	Basic dynamic load rating	C	kN	Not available				Not available				7.8				Not available		19.9				Not available	
		Basic static load rating	Co	kN									11.4						28.8					
		Static permissible moment	M_P	N·m									49						207					
			M_{2P}										368						1,336					
			M_Y										59						246					
			M_{2Y}										439						1,593					
			M_R										250						907					
			M_{2R}										500						1,814					
Ball screw	Shaft diameter			mm	6				8				10				12		15				20	
	Lead			mm	1		5		2		5		5		10		20		10		20		20	
	Spacer to ball ratio				—				—				—	1:1	—	1:1	—	1:1	—	1:1	—	2:1	—	2:1
	Basic dynamic load rating		Ca	kN	0.63		0.65		2.60		2.35		3.35	2.11	2.20	1.39	2.32	1.46	4.40	2.77	4.40	3.36	5.40	4.12
	Basic static load rating		Coa	kN	1.34		0.92		3.64		3.30		5.90	2.95	3.50	1.75	4.05	2.03	7.90	3.95	7.90	5.27	10.50	7.00
Fixed side bearing	Model No. of bearing				AC5-14DF or equivalent				AC6-16DF or equivalent				708ADFP5 or equivalent						7001ADFP5 or equivalent				7002ADFP5 or equivalent	
	Basic dynamic load rating		Cb	kN	1.31				1.79				4.40						6.77				7.74	
	Basic static load rating		Cob	kN	1.25				1.76				4.36						7.45				9.50	

(Note 1) Static permissible moment, M_{2P} and M_{2Y}, means the values for when 2 slide blocks are used in close contact with each other.

(Note 2) For your use of P grade model of SG20 and SG26 at small stroke (SG2001: 7mm or less, SG2005: 25mm or less, SG2602: 14mm or less, SG2605: 25mm or less) and at high-frequency reciprocation, consult KURODA.

DIRECTION OF MOMENT





ACCURACY

Model No.	Guide rail length (mm)	Repeated positioning accuracy (μm)		Positioning accuracy (μm)		Travelling parallelism B (μm)		Backlash (μm)		Starting torque(Note 2) (N·m)	
		H	P	H	P	H	P	H	P	H	P
SG20	100	±3	±1	50	20	25	10	5	2	0.01	0.012
	150										
	200										
SG26	150	±3	±1	50	20	25	10	5	2	0.015	0.04
	200										
	250										
	300										
SG33	150	±3 (±5)	±1 (±3)	30	15	25	10	5	2	0.07	0.15
	200										
	300			35	20						
	400										
	500			40	25	35	15				
	600		—	70	—		—		—		—
SG46	340	±3 (±5)	±1 (±3)	35	20	35	15	5	2	0.10	0.15
	440										
	540			40	25						
	640										0.17
	740			50	30	40	20				
	840		—	80	—	50	—		—		—
	940										
	1040										
	1140			100							
	1240										
SG55	980	±3	±1	80	35	50	25	5	2	0.12	0.17
	1080										
	1180			100	40		30				0.20
	1280		—		—		—		—		—
	1380										

(Note 1) Measurement is to be performed with KURODA's specified motor mounted.

(Note 2) Above starting torque value is applied when the standard grease is used. The value may change depending on the properties of the grease.

(Note 3) For repeated positioning accuracy, the value in parentheses is for parallel motor mounted configurations.

INERTIA

Inertia for slide block and ball screw of ballscrew actuator is shown in the following table.

(Unit : $\times 10^{-5}$kg·m^2)

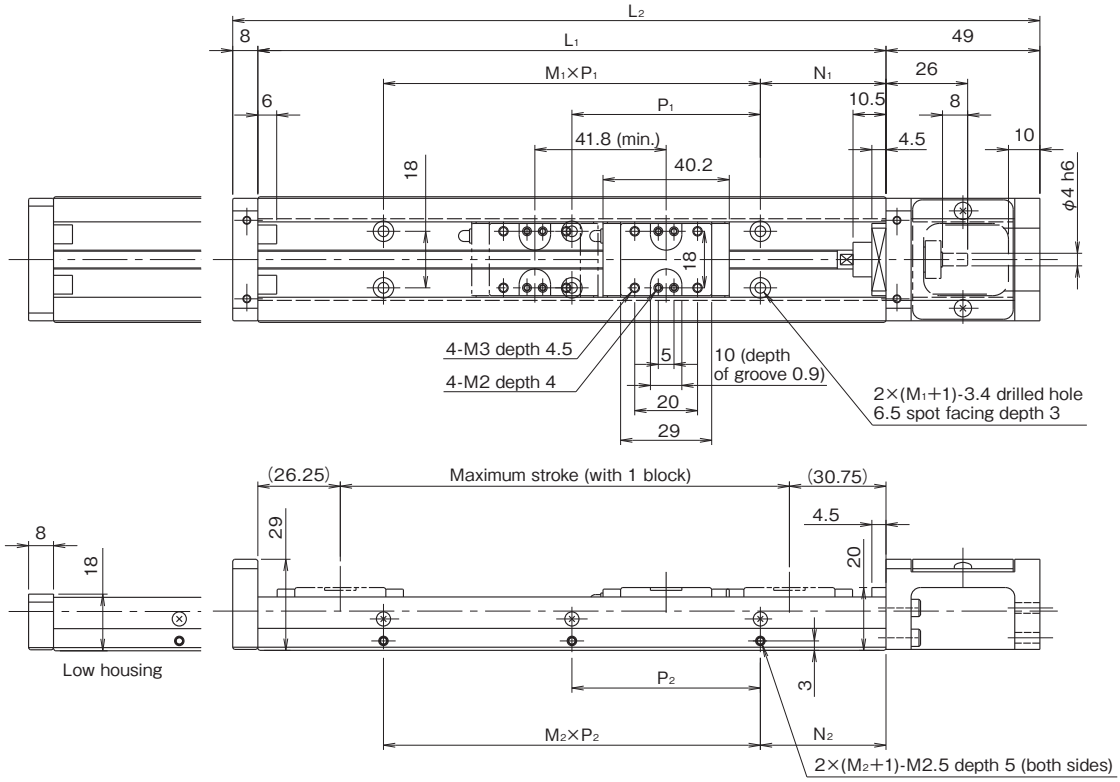
Model No.	Guide rail length (mm)	Without dustproof cover				With dustproof cover			
		Long block		Short block		Long block		Short block	
		1 block	2 blocks	1 block	2 blocks	1 block	2 blocks	1 block	2 blocks
		A	B	C	D	A	B	C	D
SG2001	100	0.0134	—	—		0.0135	—	—	
	150	0.0183	0.0185			0.0184	0.0187		
	200	0.0233	0.0235			0.0234	0.0237		
SG2005	100	0.0176	—	—		0.0200	—	—	
	150	0.0226	0.0270			0.0250	0.0318		
	200	0.0276	0.0320			0.0300	0.0368		
SG2602	150	0.0608	—	—		0.0616	—	—	
	200	0.0765	0.0783			0.0773	0.0797		
	250	0.0922	0.0939			0.0929	0.0954		
	300	0.1080	0.1100			0.1090	0.1110		
SG2605	150	0.0699	—	—		0.0744	—	—	
	200	0.0856	0.0963			0.0901	0.1050		
	250	0.1010	0.1120			0.1060	0.1210		
	300	0.1170	0.1280			0.1210	0.1370		
SG3305	150	0.164	—	0.156	0.164	0.171	—	0.160	0.171
	200	0.202	—	0.194	0.203	0.209	—	0.198	0.210
	300	0.279	0.299	0.271	0.279	0.286	0.313	0.275	0.286
	400	0.355	0.375	0.348	0.356	0.362	0.389	0.351	0.363
	500	0.432	0.452	0.424	0.432	0.439	0.466	0.428	0.439
	600	0.508	0.528	0.501	0.509	0.515	0.542	0.504	0.516
SG3310	150	0.219	—	0.188	0.221	0.247	—	0.202	0.249
	200	0.257	—	0.227	0.259	0.285	—	0.240	0.287
	300	0.334	0.414	0.303	0.336	0.361	0.469	0.317	0.364
	400	0.410	0.490	0.380	0.412	0.438	0.546	0.394	0.440
	500	0.487	0.567	0.456	0.489	0.515	0.622	0.470	0.517
	600	0.563	0.643	0.533	0.565	0.591	0.699	0.547	0.593
SG3320	150	0.594	—	—	—	0.706	—	—	—
	200	0.674	—	—	—	0.785	—	—	—
	300	0.833	1.150	—	—	0.944	1.380	—	—
	400	0.991	1.310	—	—	1.100	1.530	—	—
	500	1.150	1.470	—	—	1.260	1.690	—	—
	600	1.310	1.630	—	—	1.420	1.850	—	—
SG4610	340	1.79	2.02	1.69	1.82	1.87	2.17	1.74	1.92
	440	2.18	2.41	2.08	2.20	2.25	2.56	2.13	2.31
	540	2.57	2.79	2.46	2.59	2.64	2.95	2.52	2.69
	640	2.95	3.18	2.85	2.98	3.03	3.33	2.90	3.08
	740	3.34	3.57	3.24	3.37	3.42	3.72	3.29	3.47
	840	3.73	3.96	3.63	3.75	3.80	4.11	3.67	3.83
	940	4.12	4.35	4.02	4.14	4.19	4.50	4.06	4.22
	1040	4.50	4.74	4.41	4.53	4.58	4.88	4.44	4.61
	1140	4.89	5.12	4.79	4.92	4.97	5.27	4.83	4.99
	1240	5.28	5.51	5.18	5.30	5.35	5.66	5.22	5.38
SG4620	340	2.47	3.39	2.07	2.58	2.78	3.99	2.27	2.98
	440	2.86	3.77	2.46	2.96	3.17	4.38	2.66	3.37
	540	3.25	4.16	2.84	3.35	3.55	4.77	3.05	3.76
	640	3.64	4.55	3.23	3.74	3.94	5.16	3.44	4.14
	740	4.03	4.94	3.62	4.13	4.33	5.55	3.82	4.53
	840	4.41	5.34	4.02	4.51	4.71	5.93	4.17	4.82
	940	4.80	5.72	4.41	4.90	5.09	6.32	4.56	5.21
	1040	5.19	6.11	4.80	5.29	5.48	6.71	4.95	5.59
	1140	5.57	6.50	5.18	5.68	5.87	7.09	5.34	5.98
	1240	5.96	6.89	5.57	6.06	6.26	7.48	5.72	6.37
SG5520	980	14.6	16.4	—		15.2	17.6	—	
	1080	15.9	17.6			16.5	18.8		
	1180	17.1	18.8			17.7	20.0		
	1280	18.3	20.0			18.9	21.2		
	1380	19.5	21.3			20.1	22.5		

(Note 1) Dash (-) in the above table means the configuration is not available.

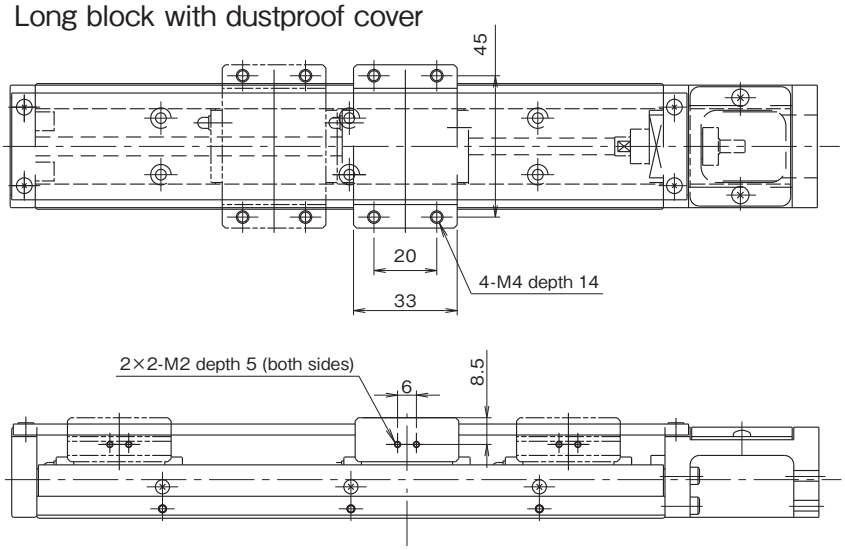
SG20

● LONG BLOCK CONFIGURATIONS

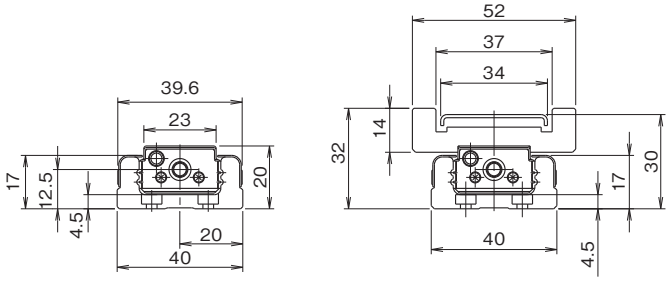
With 1 long block: A (With 2 long blocks: B)



Long block with dustproof cover



Without dustproof cover With dustproof cover



SG20

● LONG BLOCK DIMENSIONS

(Unit: mm)

Guide rail length L_1	Overall length L_2	N_1	$M_1 \times P_1$	N_2	$M_2 \times P_2$	Maximum stroke	
						Long block	
						A: 1 block	B: 2 blocks
100	157	20	1×60	20	1×60	43	—
150	207	15	2×60	15	2×60	93	51
200	257	40		40		143	101

● PERMISSIBLE SPEED / MASS

Guide rail length L_1 (mm)	Permissible speed (mm/s)		Mass (kg)					
	Lead		Without cover		With cover		Slide block	
	1mm	5mm	A	B	A	B	Without cover	With cover
100	187	925	0.45	—	0.5	—	0.07	0.11
150			0.58	0.65	0.63	0.74		
200			0.71	0.78	0.77	0.88		

(Note 1) The mass indicated in the columns "Without cover" and "With cover" in the above table includes the mass of slide block.
(Note 2) For long rail configurations, please consult KURODA.

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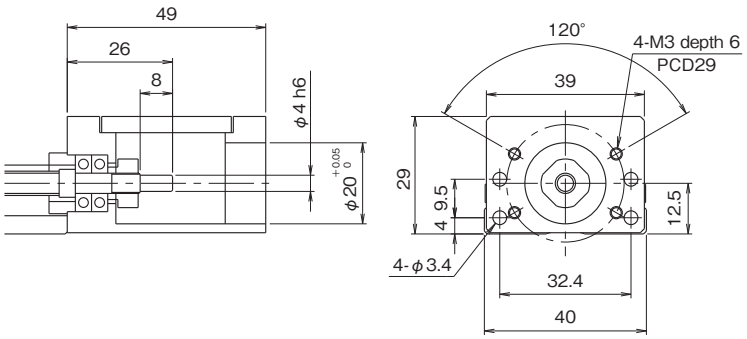
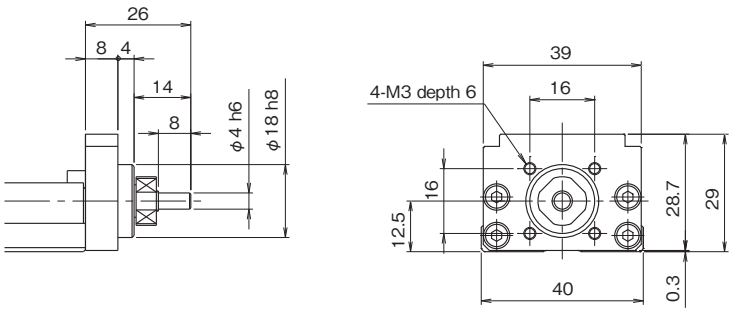
● MOTOR BRACKET CONFIGURATIONS

Motor bracket configuration: A0



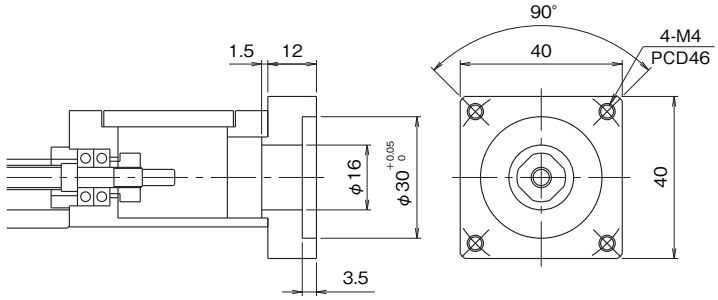
Motor bracket configuration: R0



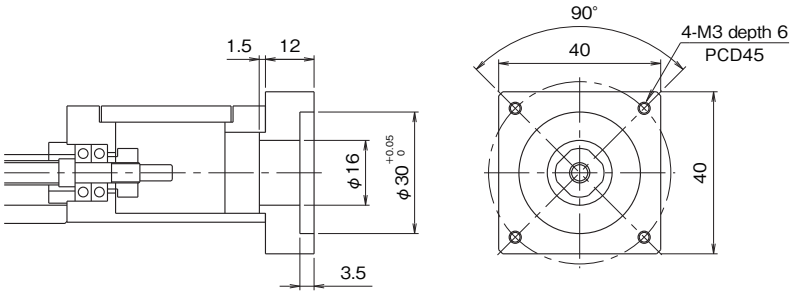
Mass of the R0 configuration is 0.04 kg less than the value shown in the table on page 7.

● MOTOR BRACKET CONFIGURATIONS (INTERMEDIATE FLANGE)

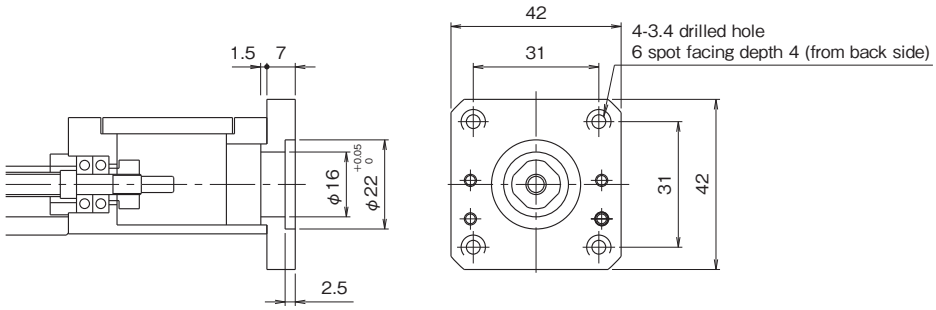
Motor bracket configuration: A1 (mass: 38g)



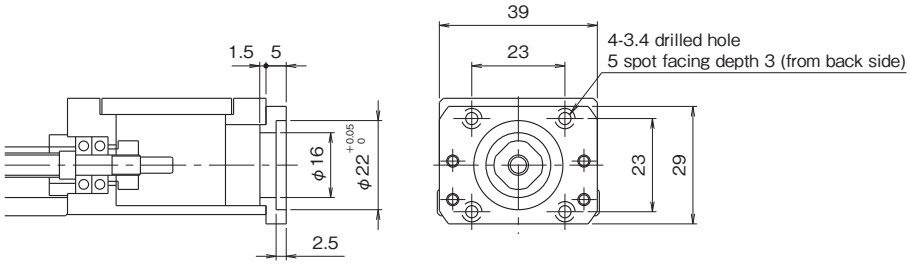
Motor bracket configuration: A3 (mass: 39g)



Motor bracket configuration: A5 (mass: 26g)



Motor bracket configuration: A6 (mass: 10g)



(Note) For A5 and A6 configurations, install the intermediate flange to motor before mounting it to actuator.

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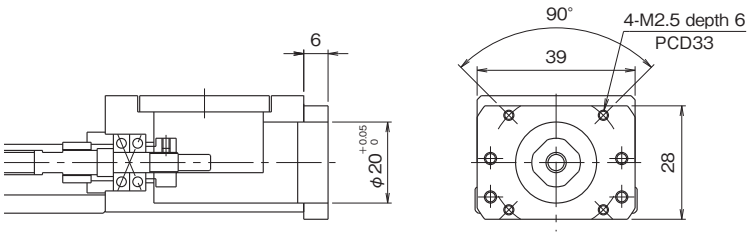
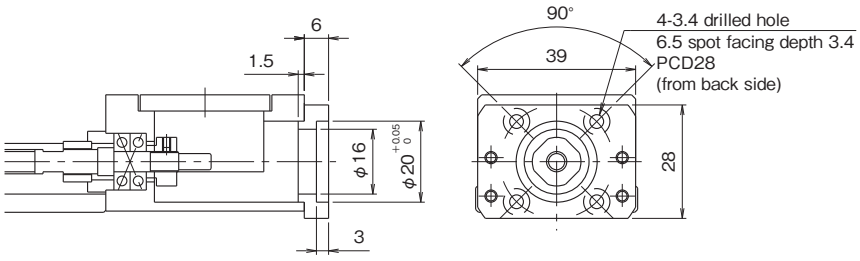
● MOTOR BRACKET CONFIGURATIONS (INTERMEDIATE FLANGE)

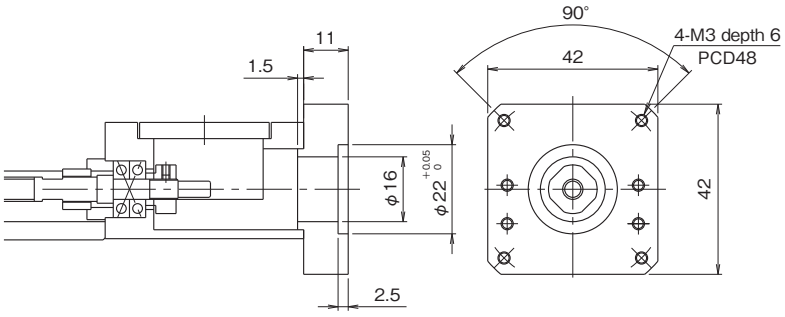
Motor bracket configuration: A8 (mass: 12g)



Motor bracket configuration: A9 (mass: 14g)



Motor bracket configuration: AA (mass: 46g)



(Note) For A9 and AA configurations, install the intermediate flange to motor before mounting it to actuator.

● MOTOR BRACKET CONFIGURATIONS AND MOTOR OPTION

Motor option					Motor bracket configuration	Recommended coupling
Motor type	Maker	Series	Model No.	Output		
AC SERVO motor	PANASONIC	MINAS E	MUMA5A	50W	AA	SFC-010DA2(MIKI PULLEY) ACD-19A(ISEL)
			MUMA01	100W		
		MINAS A5	MSME5A	50W	A3	
			MSME01	100W		
		MINAS A6	MSMF5A	50W		
			MSMF01	100W		
	MITSUBISHI ELECTRIC	MELSERVO J3	HF-KP(MP)053	50W	A1	
			HF-KP(MP)13	100W		
		MELSERVO J4	HG-AK0136	10W	A9	
			HG-AK0236	20W		
			HG-AK0336	30W		
			HG-KR(MR)053	50W	A1	
			HG-KR(MR)13	100W		
	YASKAWA ELECTRIC	Σ-V	SGMMV-A1	10W	A9	
			SGMMV-A2	20W		
			SGMMV-A3	30W		
			SGMJV, SGMAV-A5	50W	A1	
			SGMJV, SGMAV-01	100W		
			SGMJV, SGMAV-C2	150W		
		Σ-7	SGM7M-A1	10W	A9	
			SGM7M-A2	20W		
			SGM7M-A3	30W		
			SGM7J, SGM7A-A5	50W	A1	
			SGM7J, SGM7A-01	100W		
			SGM7J, SGM7A-C2	150W		
	SANYO ELECTRIC	SANMOTION R	R2AA04005	50W	A1	
			R2AA04010	100W		
Stepping motor	ORIENTAL MOTOR	α step	ARM2	□28mm	A6	
			ARM4	□42mm	A5	
		5-Phase	CRK52	□28mm	A6	
			CRK54	□42mm	A5	
			RKS54	□42mm		
		2-Phase	PKP22	□28mm	A6	
			PKP24	□42mm	A5	
	SANYO ELECTRIC	5-Phase	F series□42mm	□42mm	A5	

・For motors other than above-mentioned, consult KURODA.
・When selecting a rigid type of coupling for connecting a motor, consult KURODA.
・For detailed specifications of above-mentioned motors and couplings, refer to catalogs or websites provided by the makers.

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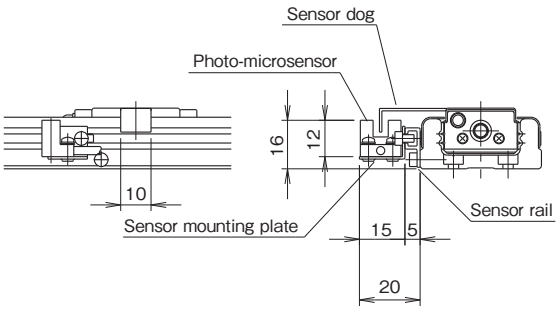
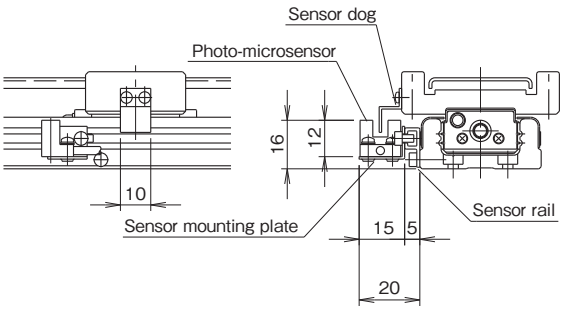
● SENSOR

Symbol S (NPN): Photo-microsensor (Panasonic Industrial Devices SUNX)

Without dustproof cover

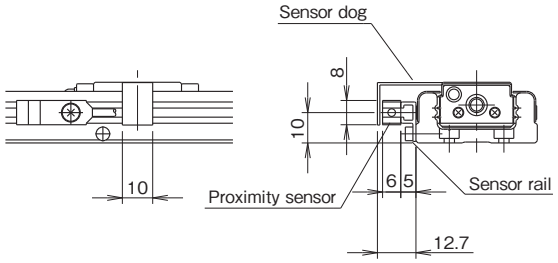


With dustproof cover

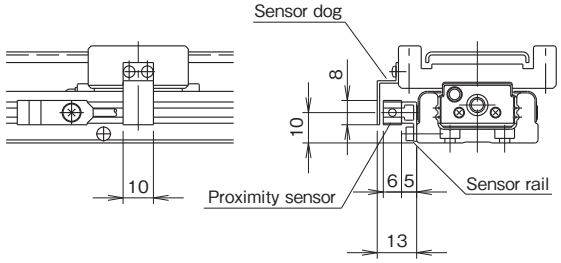


Symbol K (NPN)/E (PNP): Proximity sensor (Azbil)

Without dustproof cover



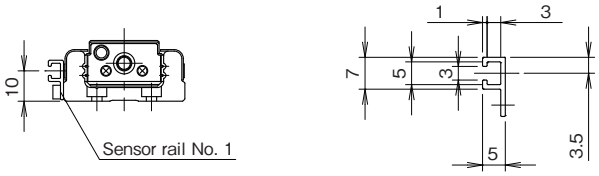
With dustproof cover



● SENSOR RAIL

Sensor rails only available with no sensors.

Sensor rail No. 1



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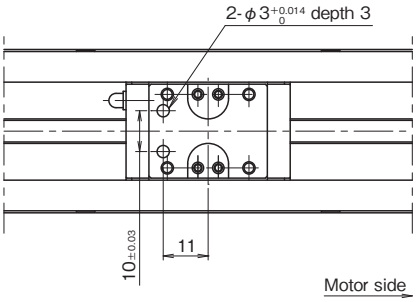
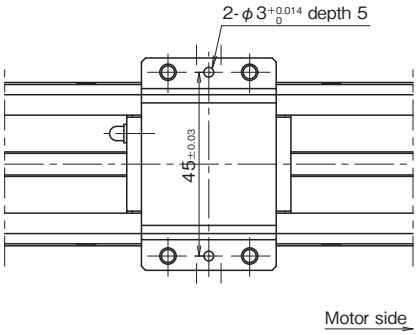
● DOWEL PIN HOLE

Dowel pin holes are applicable on the slide blocks with part number "PS", sub-tables "PR"or slide blocks and sub-tables "PSR". For actuators with 2 blocks, they are on both driving-side block and driven-side block. Please note that dowel pins are not equipped.

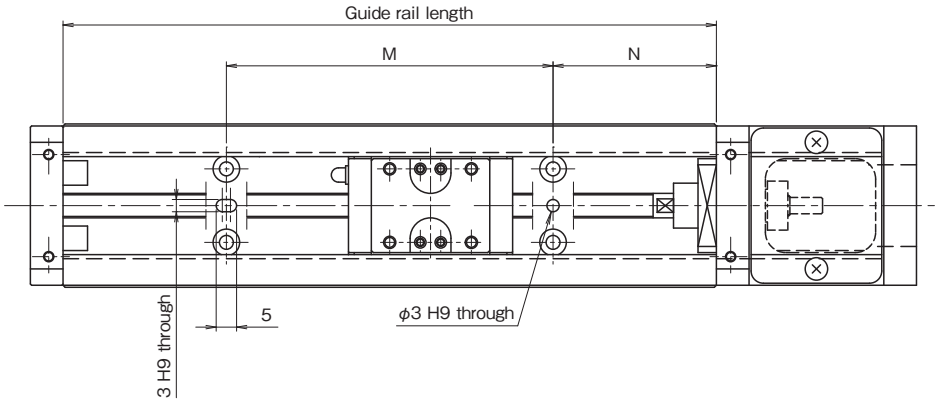
Long block without dustproof cover with "PS"



Long block with dustproof cover with "PS"



Guide rail with "PR"



(Unit: mm)

Guide rail length	N	M	Dowel pin height
100	20	60	Less than 4.5
150	15	120	
200	40		

Notice: In case dowel pin is stuck out from the U-guide rail, it may interfere with and break the slide block.

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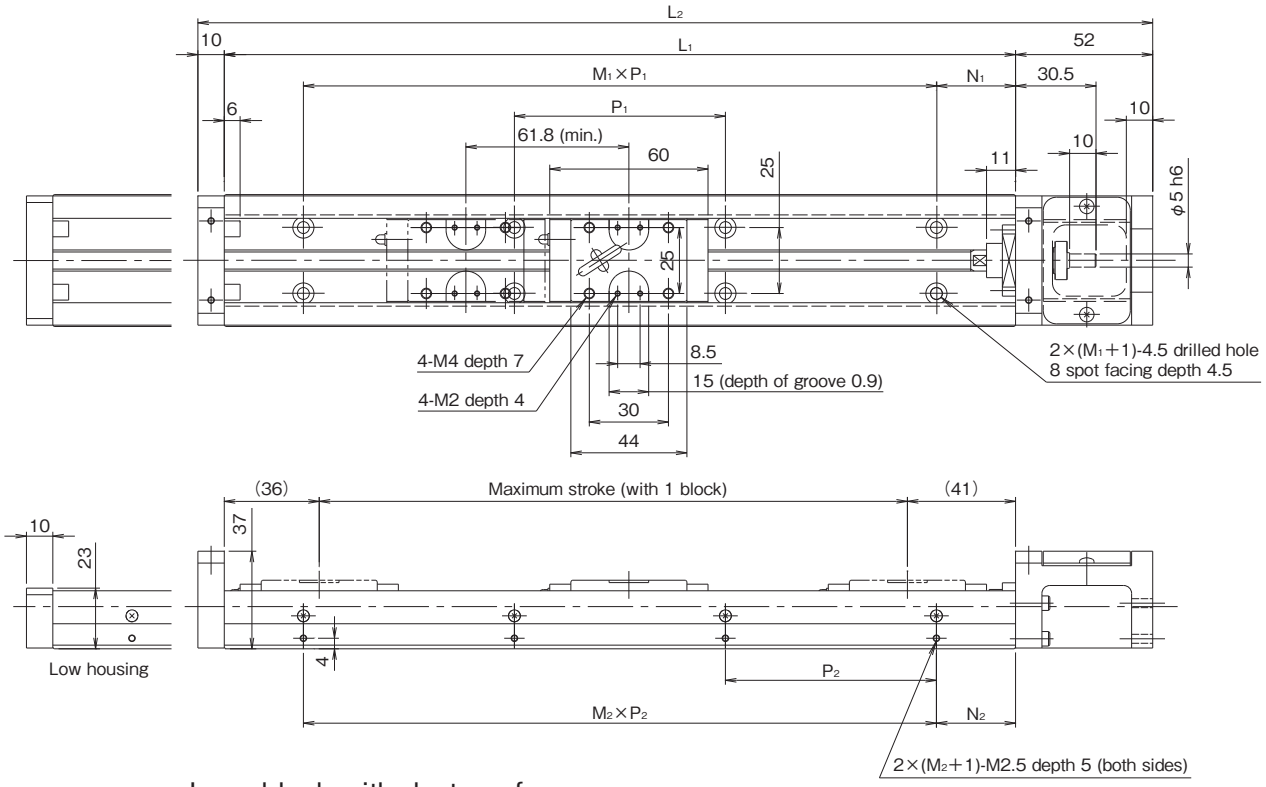
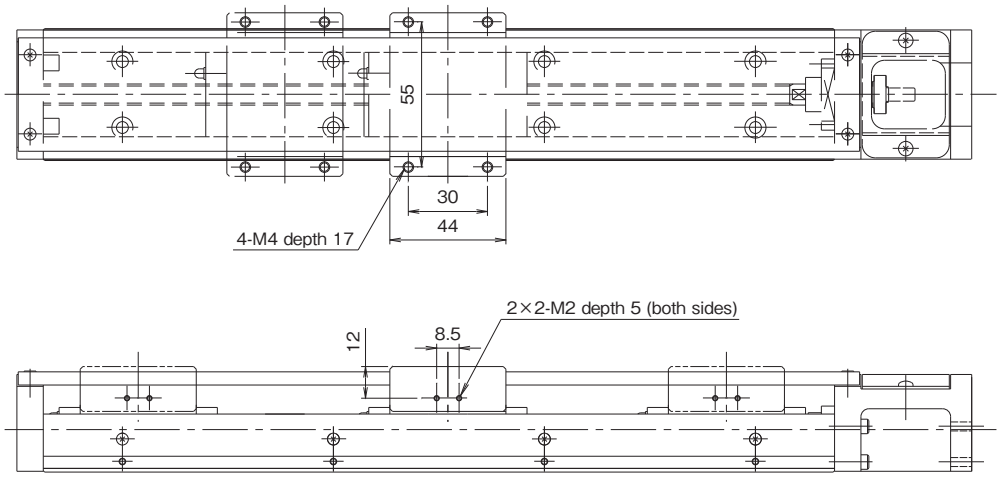
● LONG BLOCK CONFIGURATIONS

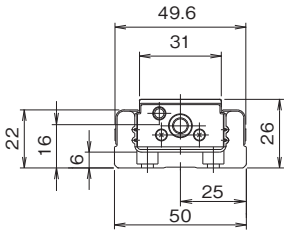
With 1 long block: A (With 2 long blocks: B)



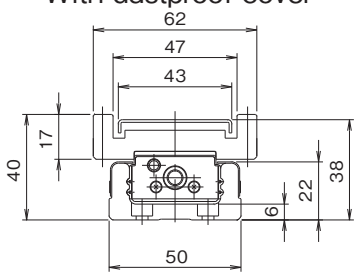
Long block with dustproof cover



Without dustproof cover



With dustproof cover



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● LONG BLOCK DIMENSIONS

(Unit: mm)

Guide rail length L_1	Overall length L_2	N_1	$M_1 \times P_1$	N_2	$M_2 \times P_2$	Maximum stroke	
						Long block	
						A: 1 block	B: 2 blocks
150	212	35	1×80	35	1×80	73	—
200	262	20	2×80	20	2×80	123	61
250	312	45		45		173	111
300	362	30	3×80	30	3×80	223	161

● PERMISSIBLE SPEED / MASS

Guide rail length L_1 (mm)	Permissible speed (mm/s)		Mass (kg)					
	Lead		Without cover		With cover		Slide block	
	2mm	5mm	A	B	A	B	Without cover	With cover
150	281	694	0.93	—	1.07	—	0.17	0.24
200			1.14	1.31	1.3	1.54		
250			1.36	1.53	1.53	1.78		
300			1.57	1.74	1.76	2.01		

(Note 1) The mass indicated in the columns "Without cover" and "With cover" in the above table includes the mass of slide block.
(Note 2) For long rail configurations, please consult KURODA.

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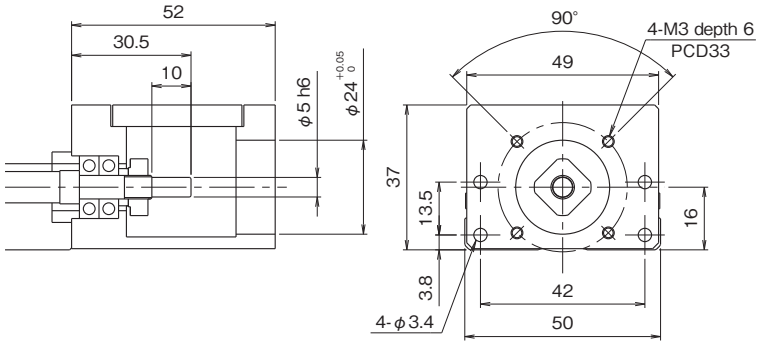
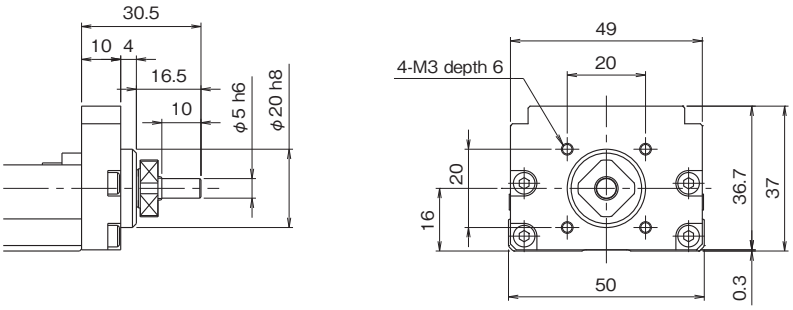
● MOTOR BRACKET CONFIGURATIONS

Motor bracket configuration: A0



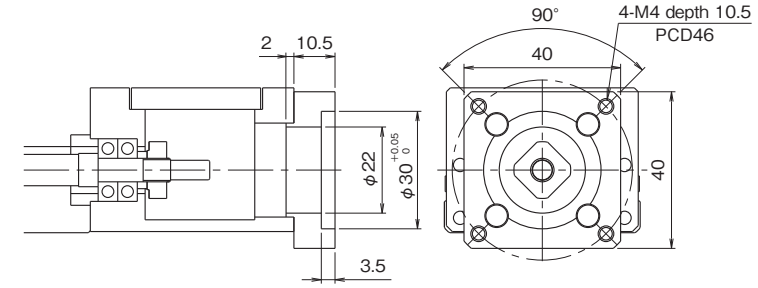
Motor bracket configuration: R0



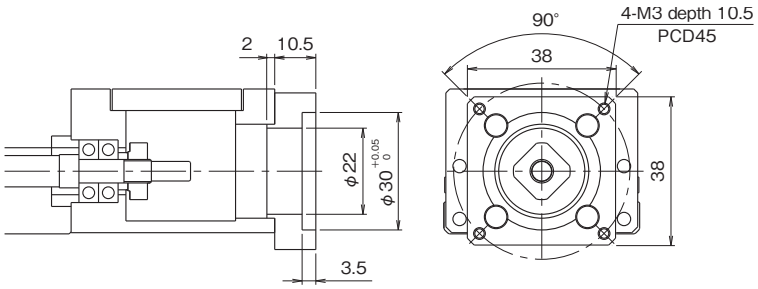
Mass of the R0 configuration is 0.08 kg less than the value shown in the table on page 15.

● MOTOR BRACKET CONFIGURATIONS (INTERMEDIATE FLANGE)

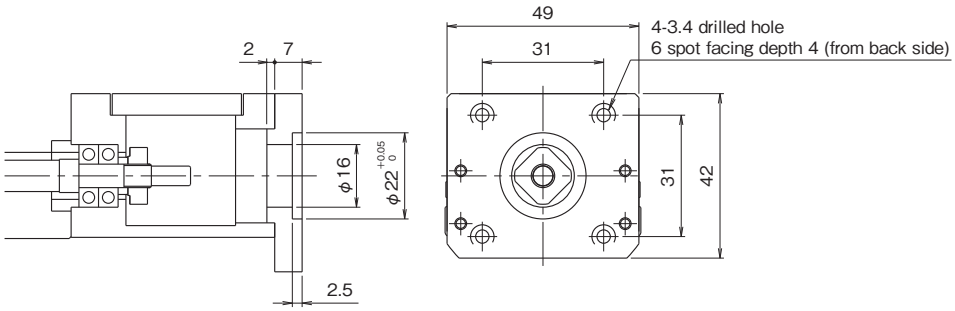
Motor bracket configuration: A1 (mass: 28g)



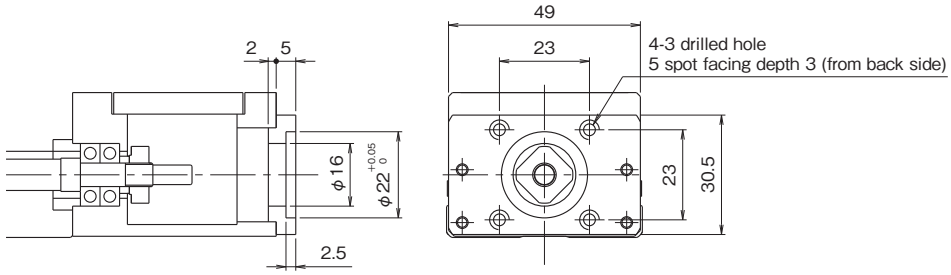
Motor bracket configuration: A3 (mass: 24g)



Motor bracket configuration: A5 (mass: 32g)



Motor bracket configuration: A6 (mass: 16g)



(Note) For A5 and A6 configurations, install the intermediate flange to motor before mounting it to actuator.

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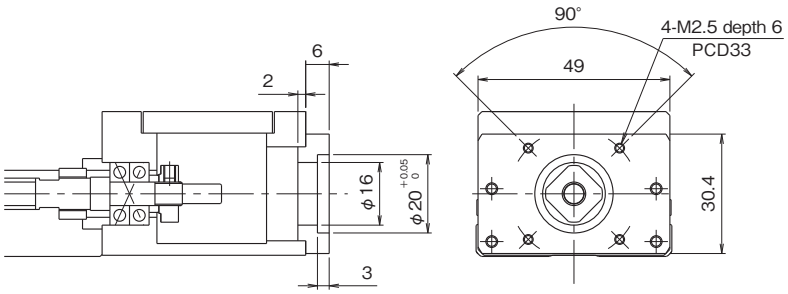
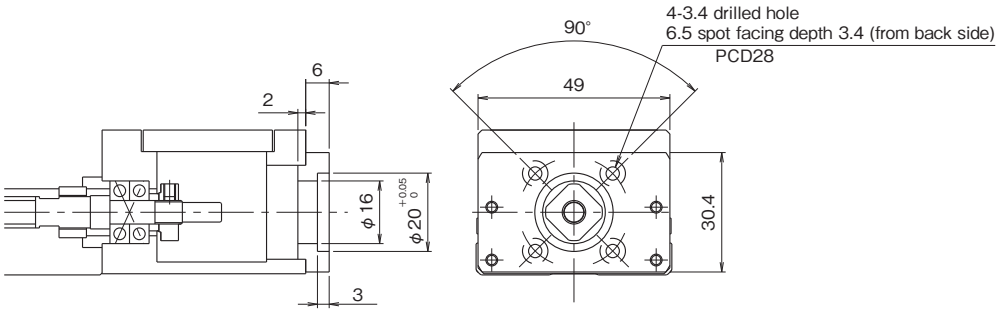
● MOTOR BRACKET CONFIGURATIONS (INTERMEDIATE FLANGE)

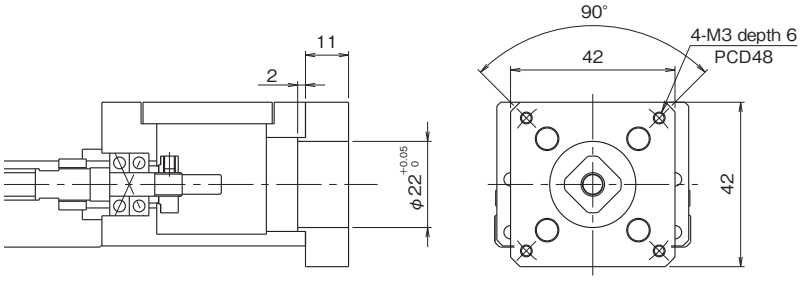
Motor bracket configuration: A8 (mass: 21g)



Motor bracket configuration: A9 (mass: 21g)



Motor bracket configuration: AA (mass: 41g)



(Note) For A9 configuration, install the intermediate flange to motor before mounting it to actuator.

● MOTOR BRACKET CONFIGURATIONS AND MOTOR OPTION

Motor option					Motor bracket configuration	Recommended coupling
Motor type	Maker	Series	Model No.	Output		
AC SERVO motor	PANASONIC	MINAS E	MUMA5A	50W	AA	SFC-010DA2(MIKI PULLEY) ACD-19A(ISEL)
			MUMA01	100W		
		MINAS A5	MSME5A	50W	A3	
			MSME01	100W		
		MINAS A6	MSMF5A	50W		
			MSMF01	100W		
	MITSUBISHI ELECTRIC	MELSERVO J3	HF-KP(MP)053	50W	A1	
			HF-KP(MP)13	100W		
		MELSERVO J4	HG-AK0136	10W	A9	
			HG-AK0236	20W		
			HG-AK0336	30W		
			HG-KR(MR)053	50W	A1	
			HG-KR(MR)13	100W		
	YASKAWA ELECTRIC	Σ-V	SGMMV-A1	10W	A9	
			SGMMV-A2	20W		
			SGMMV-A3	30W		
			SGMJV, SGMAV-A5	50W	A1	
			SGMJV, SGMAV-01	100W		
			SGMJV, SGMAV-C2	150W		
		Σ-7	SGM7M-A1	10W	A9	
			SGM7M-A2	20W		
			SGM7M-A3	30W		
			SGM7J, SGM7A-A5	50W	A1	
			SGM7J, SGM7A-01	100W		
			SGM7J, SGM7A-C2	150W		
	SANYO ELECTRIC	SANMOTION R	R2AA04005	50W	A1	
			R2AA04010	100W		
Stepping motor	ORIENTAL MOTOR	α step	ARM2	□28mm	A6	
			ARM4	□42mm	A5	
		5-Phase	CRK52	□28mm	A6	
			CRK54	□42mm	A5	
			RKS54	□42mm		
		2-Phase	PKP22	□28mm	A6	
			PKP24	□42mm	A5	
	SANYO ELECTRIC	5-Phase	F series□42mm	□42mm	A5	

・For motors other than above-mentioned, consult KURODA.
・When selecting a rigid type of coupling for connecting a motor, consult KURODA.
・For detailed specifications of above-mentioned motors and couplings, refer to catalogs or websites provided by the makers.

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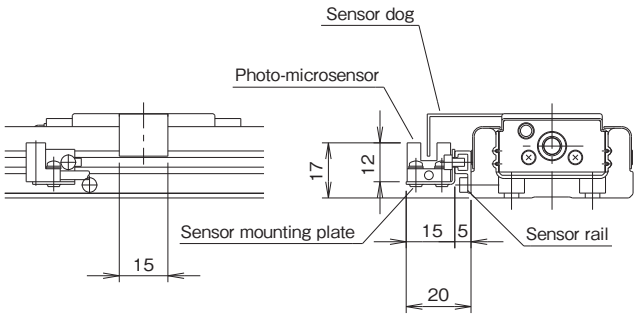
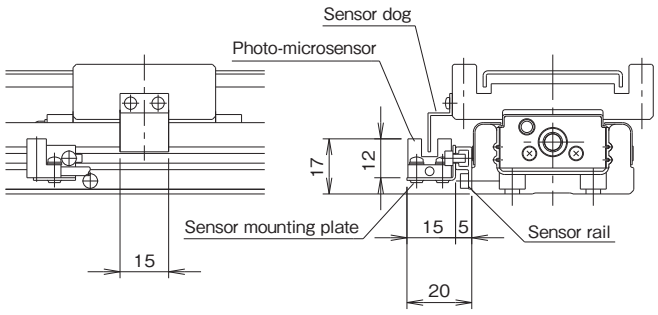
● SENSOR

Symbol S (NPN): Photo-microsensor (Panasonic Industrial Devices SUNX)

Without dustproof cover

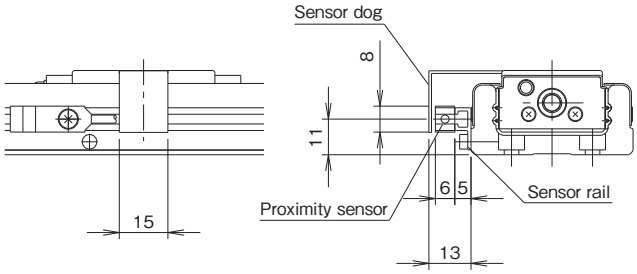


With dustproof cover

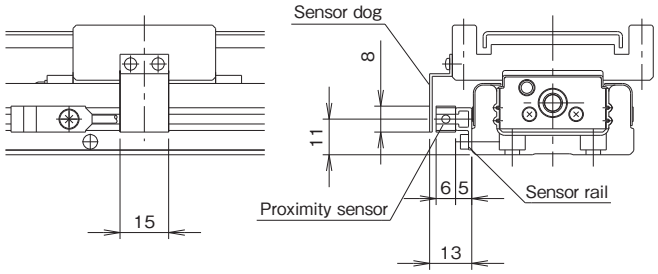


Symbol K (NPN)/E (PNP): Proximity sensor (Azbil)

Without dustproof cover



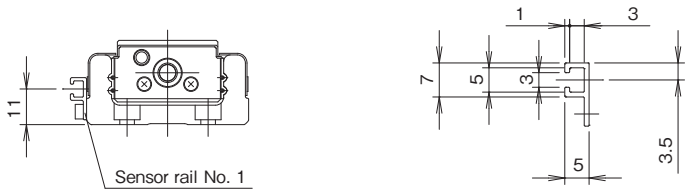
With dustproof cover



● SENSOR RAIL

Sensor rails only available with no sensors.

Sensor rail No. 1



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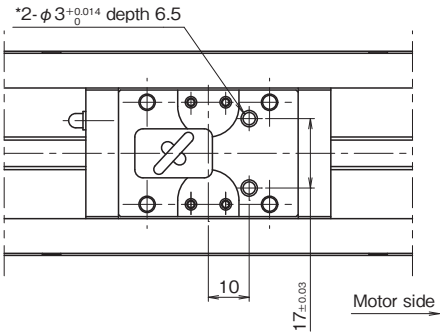
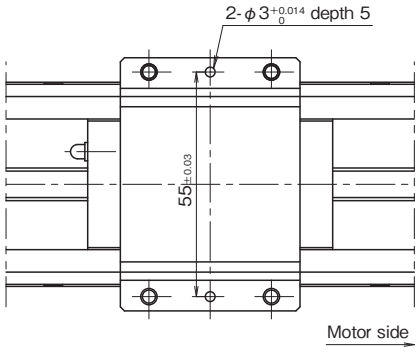
● DOWEL PIN HOLE

Dowel pin holes are applicable on the slide blocks with part number "PS", sub-tables "PR"or slide blocks and sub-tables "PSR". For actuators with 2 blocks, they are on both driving-side block and driven-side block. Please note that dowel pins are not equipped.

Long block without dustproof cover with "PS"

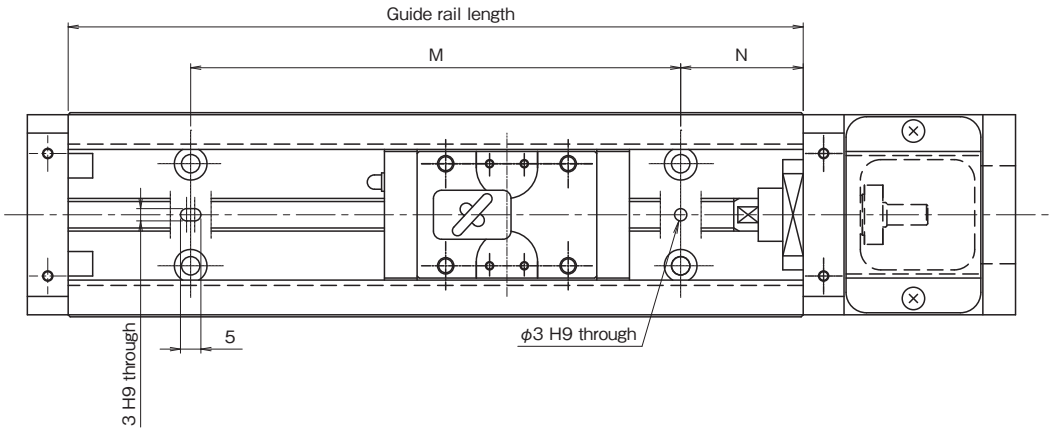


Long block with dustproof cover with "PS"



The hole with asterisk (*) may have diameter 4 counterbores depth 2 for erasing the quenching layer when needed.

Guide rail with "PR"



(Unit: mm)

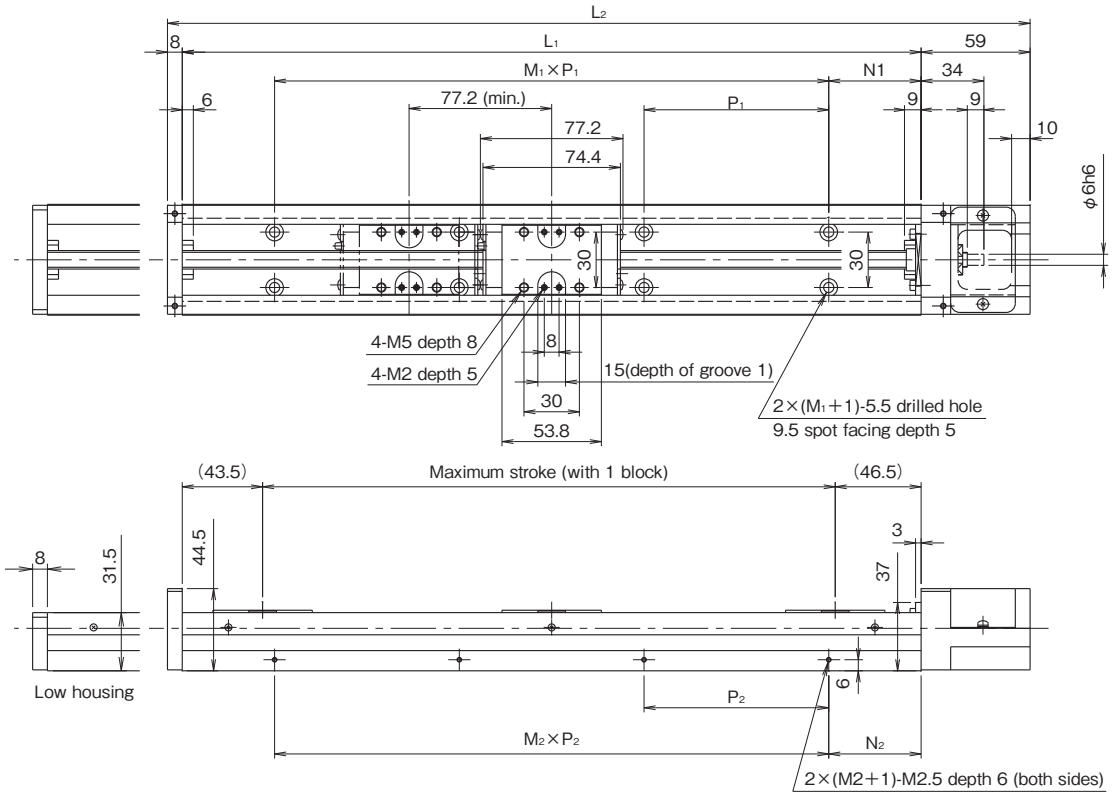
Guide rail length	N	M	Dowel pin height
150	35	80	Less than 6
200	20	160	
250	45		
300	30	240	

Notice: In case dowel pin is stuck out from the U-guide rail, it may interfere with and break the slide block.

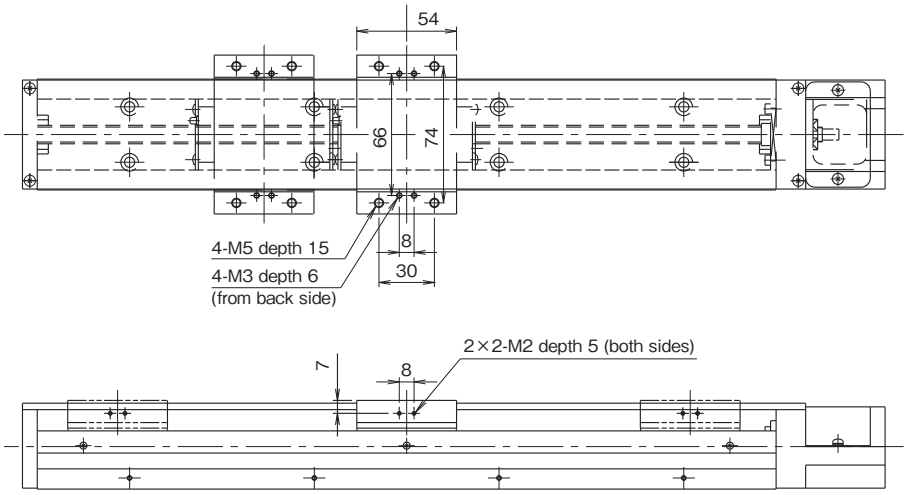
SG33

● LONG BLOCK CONFIGURATIONS

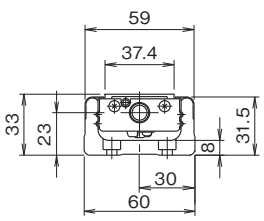
With 1 long block: A (With 2 long blocks: B)



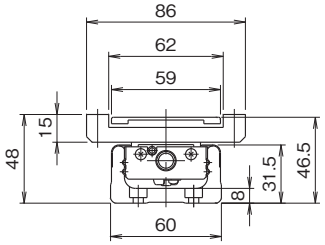
With dustproof cover



Without dustproof cover



With dustproof cover



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● LONG BLOCK DIMENSIONS

(Unit: mm)

Guide rail length L_1	Overall length L_2	N_1	$M_1 \times P_1$	N_2	$M_2 \times P_2$	Maximum stroke	
						Long block	
						A: 1 block	B: 2 blocks
150	217	25	1×100	25	1×100	60	—
200	267	50	1×100	50	1×100	110	—
300	367		2×100		2×100	210	133
400	467		3×100		3×100	310	233
500	567		4×100		4×100	410	333
600	667		5×100		5×100	510	433

● PERMISSIBLE SPEED / MASS

Guide rail length L_1 (mm)	Permissible speed (mm/s)			Mass (kg)					
	Lead			Without cover		With cover		Slide block	
	5mm	10mm	20mm	A	B	A	B	Without cover	With cover
150	550	1100	1500	1.6 (1.7)	—	1.8 (1.9)	—	0.30	0.40
200				2.0 (2.1)	—	2.1 (2.2)	—		
300				2.6 (2.7)	2.9 (3.0)	2.8 (2.9)	3.2 (3.3)		
400				3.2 (3.4)	3.6 (3.8)	3.5 (3.7)	3.9 (4.1)		
500	460	930		3.9 (4.1)	4.2 (4.4)	4.2 (4.4)	4.6 (4.8)		
600	310	620		4.6 (4.8)	4.9 (5.1)	4.9 (5.1)	5.3 (5.5)		

(Note 1) The mass indicated in the columns "Without cover" and "With cover" in the above table includes the mass of slide block.
(Note 2) The figures in parentheses in the above table apply to SG3320 configuration.
(Note 3) For long rail configurations, please consult KURODA.

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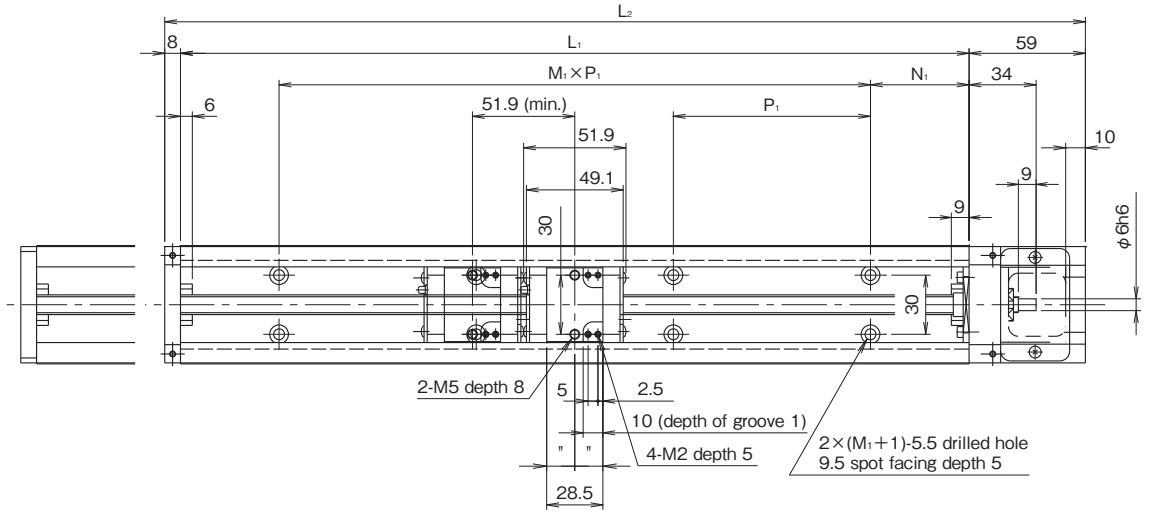
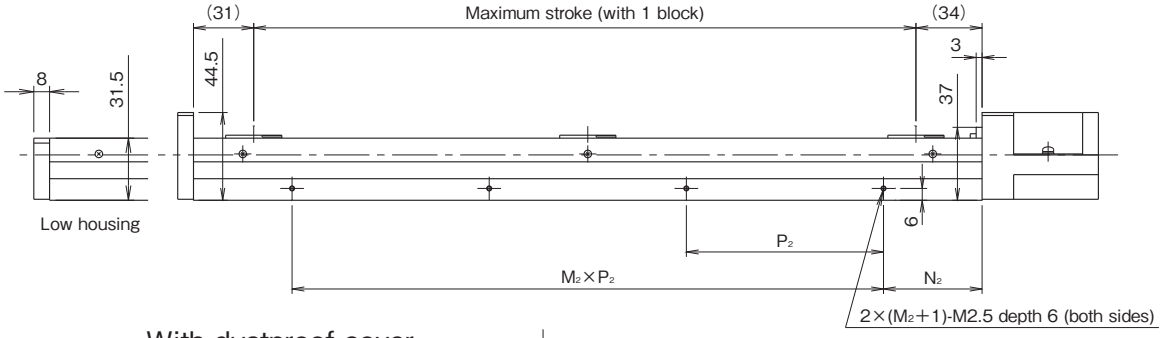
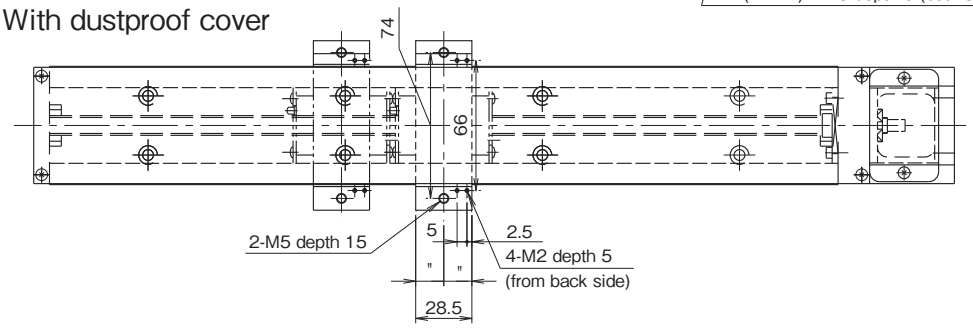
● SHORT BLOCK CONFIGURATIONS

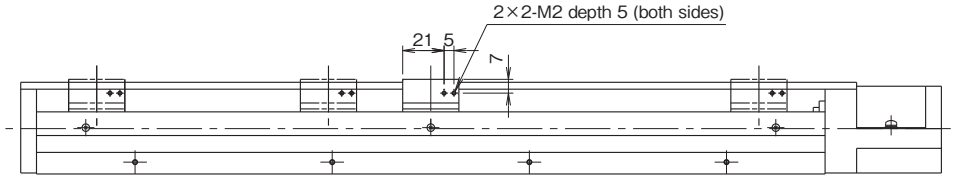
With 1 short block: C (With 2 short blocks: D)



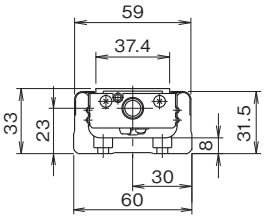


With dustproof cover

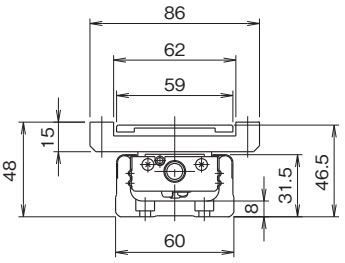




Without dustproof cover



With dustproof cover



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● SHORT BLOCK DIMENSIONS

(Unit: mm)

Guide rail length L_1	Overall length L_2	N_1	$M_1 \times P_1$	N_2	$M_2 \times P_2$	Maximum stroke	
						Short block	
						C: 1 block	D: 2 blocks
150	217	25	1×100	25	1×100	85	34
200	267	50	1×100	50	1×100	135	84
300	367		2×100		2×100	235	184
400	467		3×100		3×100	335	284
500	567		4×100		4×100	435	384
600	667		5×100		5×100	535	484

● PERMISSIBLE SPEED / MASS

Guide rail length L_1 (mm)	Permissible speed (mm/s)		Mass (kg)					
	Lead		Without cover		With cover		Slide block	
	5mm	10mm	C	D	C	D	Without cover	With cover
150	550	1100	1.5	1.7	1.6	1.9	0.15	0.20
200			1.8	2	2	2.2		
300			2.5	2.7	2.6	2.9		
400			3.1	3.3	3.3	3.5		
500	460	930	3.8	3.9	4	4.2		
600	310	620	4.4	4.6	4.7	4.9		

(Note 1) The mass indicated in the columns "Without cover" and "With cover" in the above table includes the mass of slide block.
(Note 2) Short-block configuration is not available for SG3320
(Note 3) For long rail configurations, please consult KURODA.

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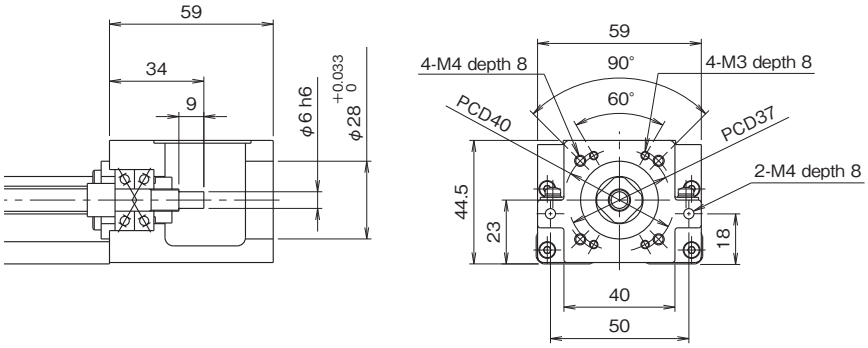
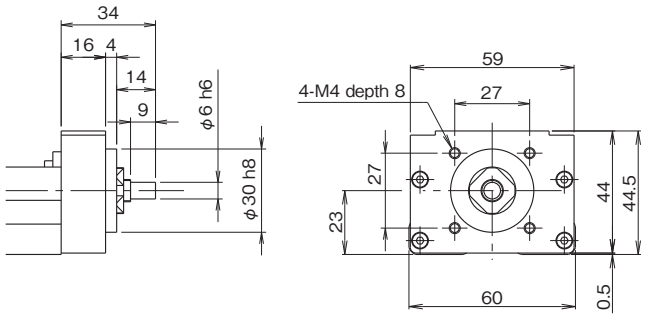
● MOTOR BRACKET CONFIGURATIONS

Motor bracket configuration: A0



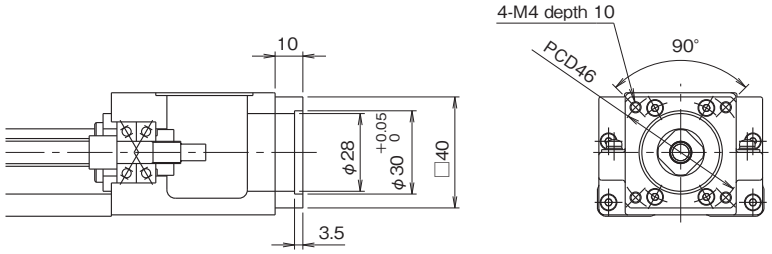
Motor bracket configuration: R0



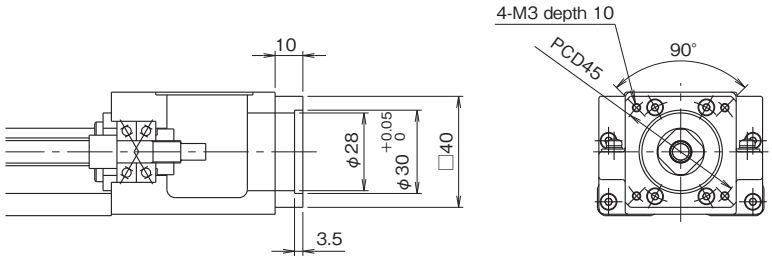
Mass of the R0 configuration is 0.1 kg less than the values shown in the tables on pages 23 and 25.

● MOTOR BRACKET CONFIGURATIONS (INTERMEDIATE FLANGE)

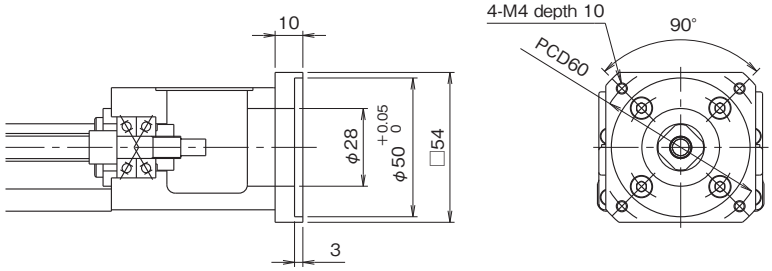
Motor bracket configuration: A1 (mass: 66g)



Motor bracket configuration: A2 (mass: 67g)



Motor bracket configuration: A3 (mass: 133g)



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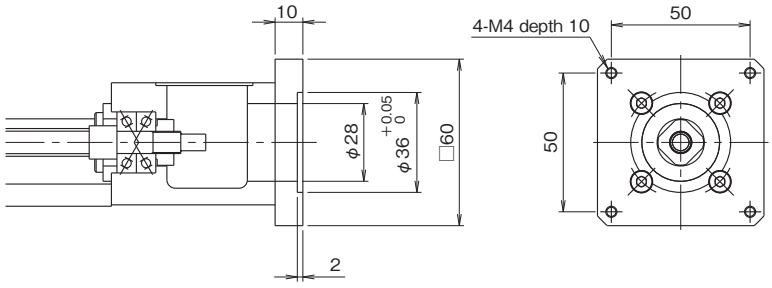
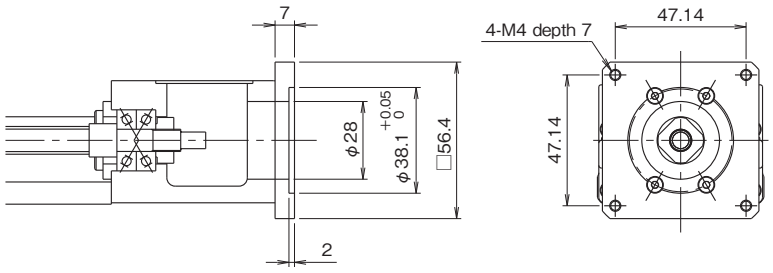
● MOTOR BRACKET CONFIGURATIONS (INTERMEDIATE FLANGE)

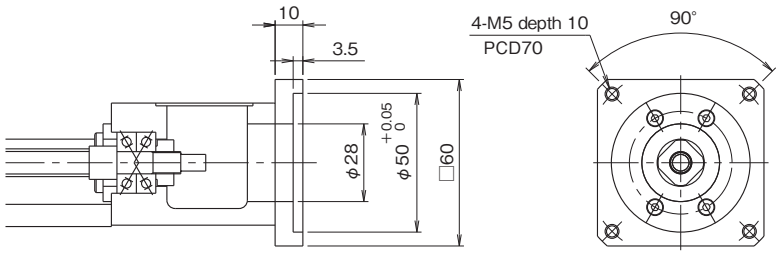
Motor bracket configuration: A4 (mass: 212g)



Motor bracket configuration: A5 (mass: 125g)



Motor bracket configuration: A6 (mass: 215g)



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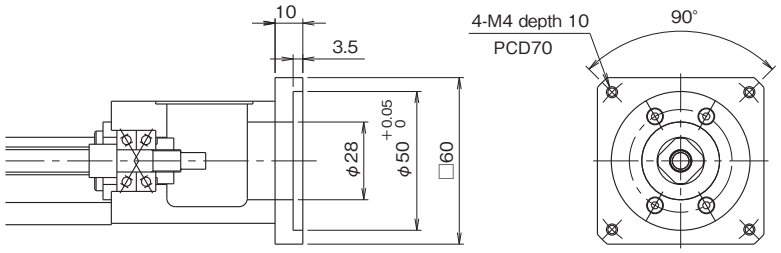
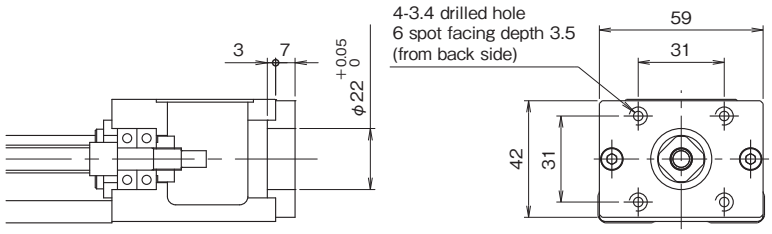
● MOTOR BRACKET CONFIGURATIONS (INTERMEDIATE FLANGE)

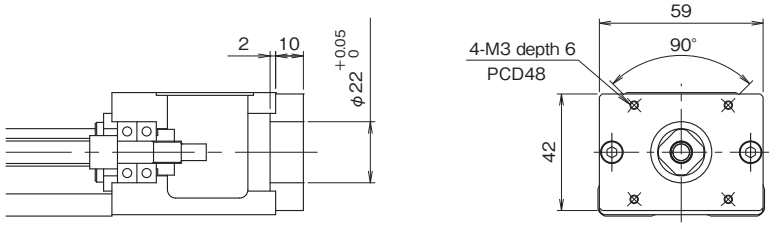
Motor bracket configuration: A7 (mass: 215g)



Motor bracket configuration: B1 (mass: 111g)



Motor bracket configuration: B2 (mass: 167g)



(Note) For B1 and B2 configuration, install the intermediate flange to motor before mounting it to actuator.

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● MOTOR BRACKET CONFIGURATIONS AND MOTOR OPTION

Motor option					Motor bracket configuration	Recommended coupling
Motor type	Maker	Series	Model No.	Output		
AC SERVO motor	PANASONIC	MINAS E	MUMA5A	50W	B2	SFC-020DA2 (MIKI PULLEY) ACD-27A (ISEL)
			MUMA01	100W		
			MUMA02	200W	A7	XBW-27C2 (NABEYA BI-TECH)
		MINAS A5	MSME5A	50W	A2	SFC-020DA2 (MIKI PULLEY) ACD-27A (ISEL)
			MSME01	100W		
			MSME02	200W	A7	XBW-27C2 (NABEYA BI-TECH)
		MINAS A6	MSMF5A	50W	A2	SFC-020DA2 (MIKI PULLEY) ACD-27A (ISEL)
			MSMF01	100W		
			MSMF02	200W	A7	XBW-27C2 (NABEYA BI-TECH)
	MITSUBISHI ELECTRIC	MELSERVO J3	HF-KP (MP) 053	50W	A1	SFC-020DA2 (MIKI PULLEY) ACD-27A (ISEL)
			HF-KP (MP) 13	100W		
			HF-KP (MP) 23	200W	A6	XBW-27C2 (NABEYA BI-TECH)
		MELSERVO J4	HG-KR (MR) 053	50W	A1	SFC-020DA2 (MIKI PULLEY) ACD-27A (ISEL)
			HG-KR (MR) 13	100W		
			HG-KR (MR) 23	200W	A6	XBW-27C2 (NABEYA BI-TECH)
	YASKAWA ELECTRIC	Σ-V	SGMJV, SGMAV-A5	50W	A1	SFC-020DA2 (MIKI PULLEY) ACD-27A (ISEL)
			SGMJV, SGMAV-01	100W		
			SGMJV, SGMAV-C2	150W		
			SGMJV, SGMAV-02	200W	A6	XBW-27C2 (NABEYA BI-TECH)
		Σ-7	SGM7J, SGM7A-A5	50W	A1	SFC-020DA2 (MIKI PULLEY) ACD-27A (ISEL)
			SGM7J, SGM7A-01	100W		
			SGM7J, SGM7A-C2	150W		
			SGM7J, SGM7A-02	200W	A6	XBW-27C2 (NABEYA BI-TECH)
	SANYO ELECTRIC	SANMOTION R	R2AA04005	50W	A3	SFC-020DA2 (MIKI PULLEY) ACD-27A (ISEL)
			R2AA04010	100W		
			R2AA06020	200W	A6	XBW-27C2 (NABEYA BI-TECH)
Stepping motor	ORIENTAL MOTOR	α step	ARM4	□42mm	B1	SFC-010DA2 (MIKI PULLEY) ACD-19A (ISEL)
		5-Phase	CRK54	□42mm		
			RKS54	□42mm		
		2-Phase	PKP24	□42mm		
			PK26	□60mm	A5	SFC-020D2 (MIKI PULLEY) ACD-27A (ISEL)
	SANYO ELECTRIC	5-Phase	F series□42mm	□42mm	B1	SFC-010DA2 (MIKI PULLEY) ACD-19A (ISEL)
			F series□60mm	□42mm	A4	SFC-020DA2 (MIKI PULLEY) ACD-27A (ISEL)

・For motors other than above-mentioned, consult KURODA.
・When selecting a rigid type of coupling for connecting a motor, consult KURODA.
・For detailed specifications of above-mentioned motors and couplings, refer to catalogs or websites provided by the makers.

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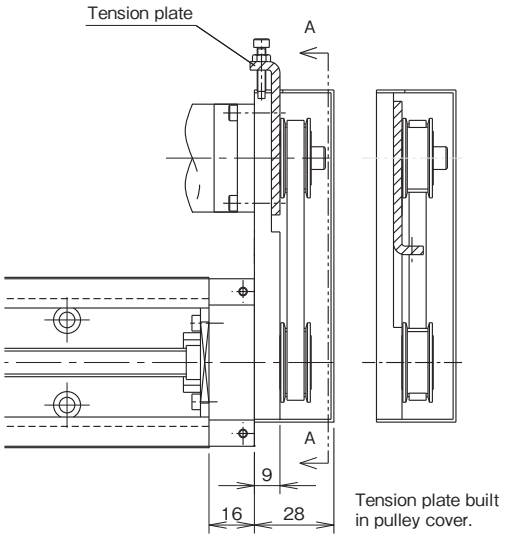
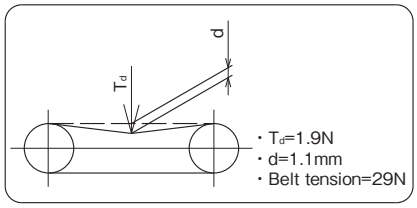
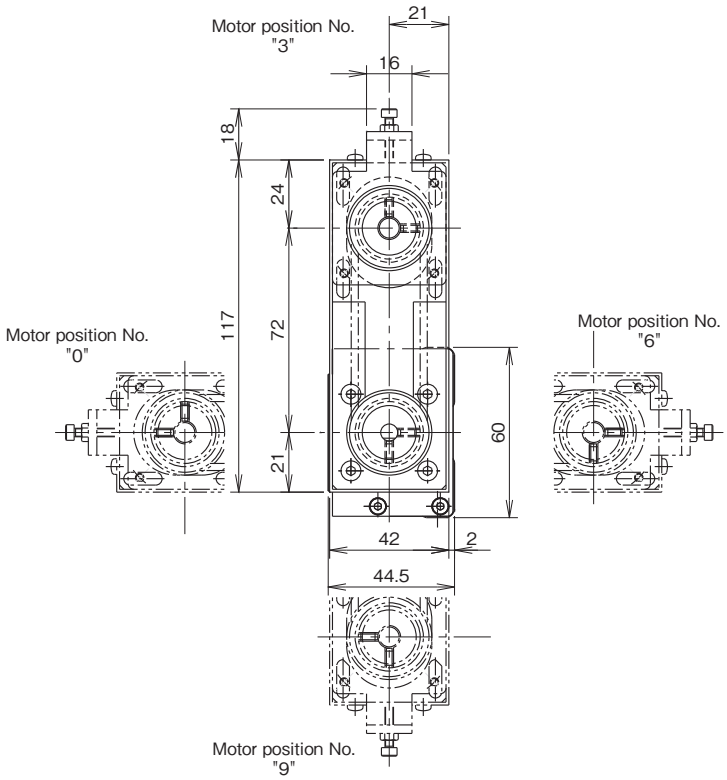
● PARALLEL MOTOR MOUNTING





Tension of belt



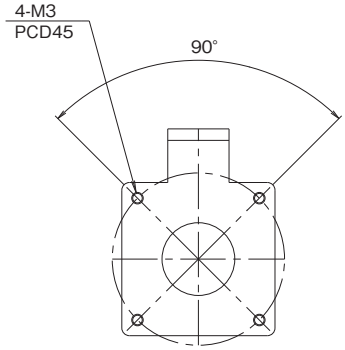
A-A sectional view

・Pulley unit position can be adjusted at every 90 degree.
・Motor parallel mounting can be equipped with dustproof cover and sensor.
・Tension plate position can be built in pulley cover.
・The mass is 0.2kg larger than the values shown in tables on pages 23 and 25.
・Inertia moment is 2.22×10^{-5}kg・m^2 larger than the value shown in table on page 5.

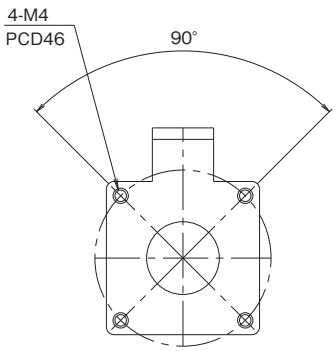
Mark	Pulley Inner dia.	Applicable motor	
E□	Inner dia. ϕ8	Panasonic	50 - 100W motor and so on
F□	Inner dia. ϕ8	Yaskawa	50 - 100W motor and so on
		Mitsubishi Electric	50 - 100W motor and so on
		Sanyo Electric	50 - 100W motor and so on

Fullfill the motor position No. in □.
Check the spec. if the motor can be assembled before using.

Parallel motor mounting type E□
Tension plate dimension



Parallel motor mounting type F□
Tension plate dimension



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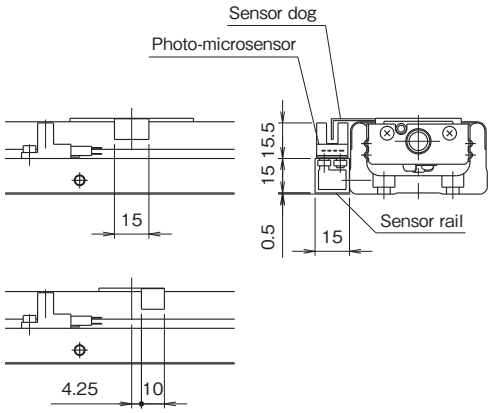
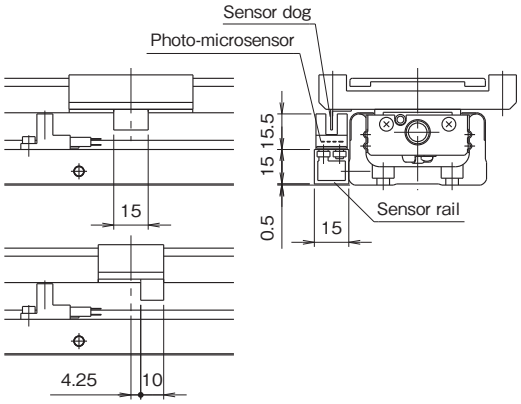
● SENSOR

Symbol C (NPN) / P (PNP), M (NPN) / Y (PNP): Photo-microsensor (OMRON, Panasonic Industrial Devices SUNX)
Note 1) 2 sensor dogs are used for SG33□D-150 sensor with Symbol "C" or "P".

Without dustproof cover

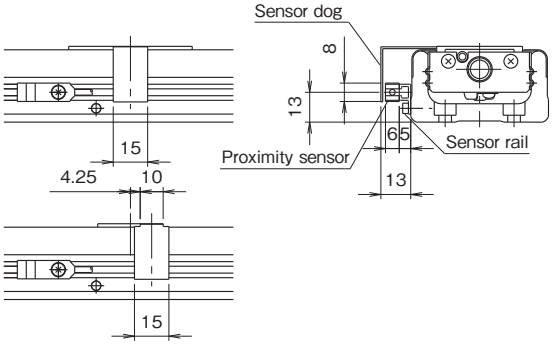


With dustproof cover

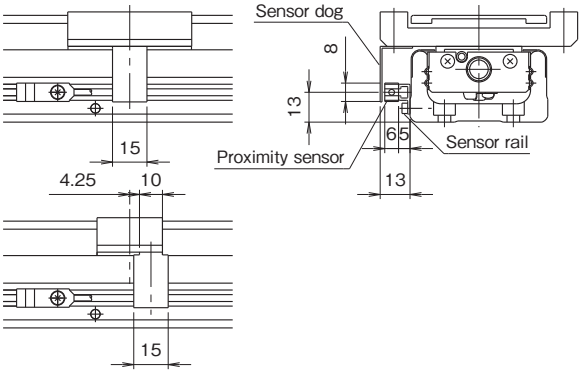


Symbol K (NPN) / E (PNP): Proximity sensor (Azbil)

Without dustproof cover

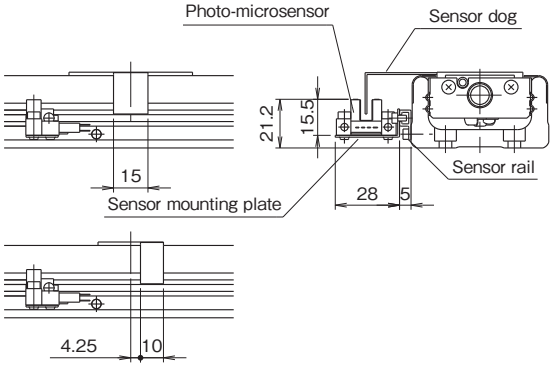


With dustproof cover

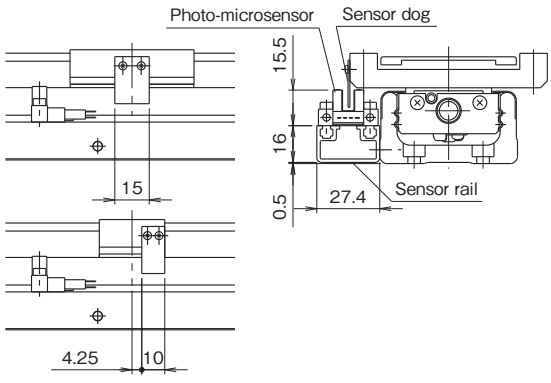


Symbol H (NPN) / J (PNP): Photo-microsensor (OMRON)

Without dustproof cover



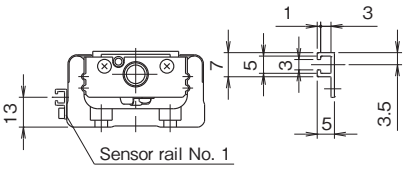
With dustproof cover



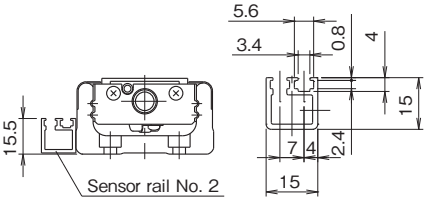
● SENSOR RAIL

Sensor rails only available with no sensors.

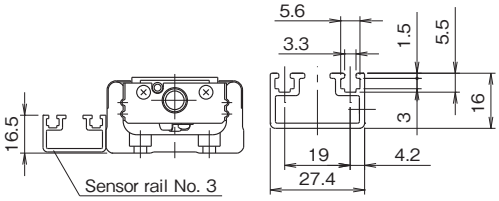
Sensor rail No. 1



Sensor rail No. 2



Sensor rail No. 3



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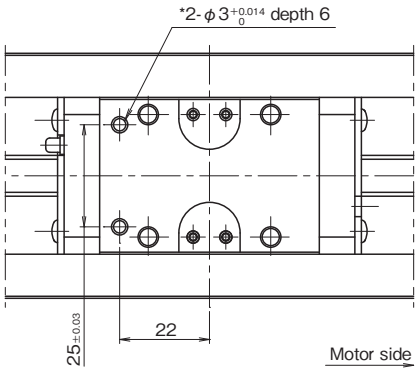
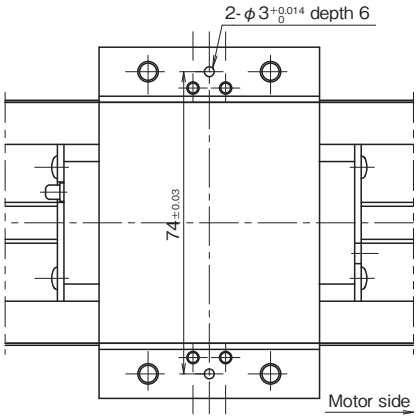
● DOWEL PIN HOLE

Dowel pin holes are applicable on the slide blocks with part number "PS", sub-tables "PR"or slide blocks and sub-tables "PSR". For actuators with 2 blocks, they are on both driving-side block and driven-side block. Please note that dowel pins are not equipped.

Long block without dustproof cover with "PS"

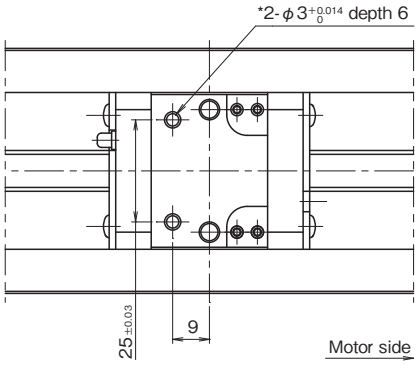


Long block with dustproof cover with "PS"

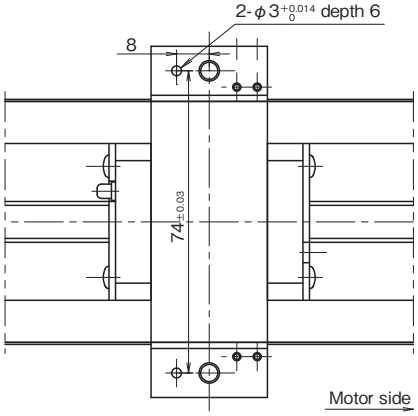


The hole with asterisk (*) may have diameter 4 counterbores depth 2 for erasing the quenching layer when needed.

Short block without dustproof cover with "PS"

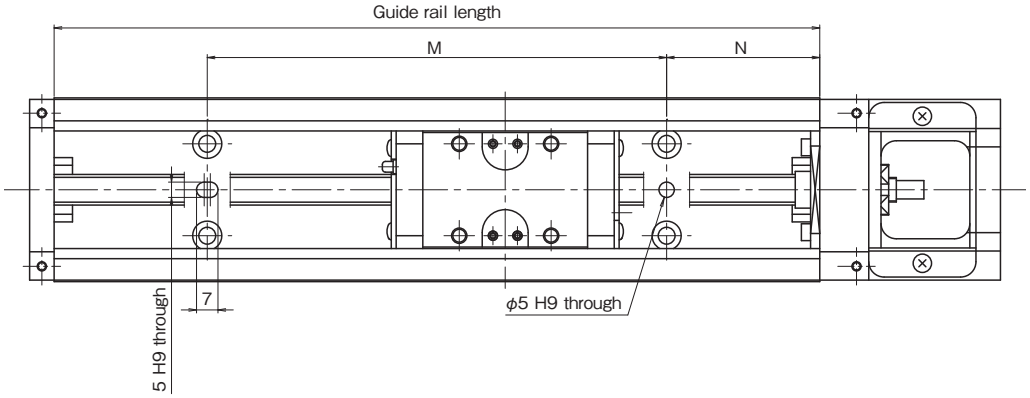


Short block with dustproof cover with "PS"



The hole with asterisk (*) may have diameter 4 counterbores depth 2 for erasing the quenching layer when needed.

Guide rail with "PR"



(Unit: mm)

Guide rail length	N	M	Dowel pin height
150	25	100	Less than 8
200	50	100	
300		200	
400		300	
500		400	
600		500	

Notice: In case dowel pin is stuck out from the U-guide rail, it may interfere with and break the slide block.

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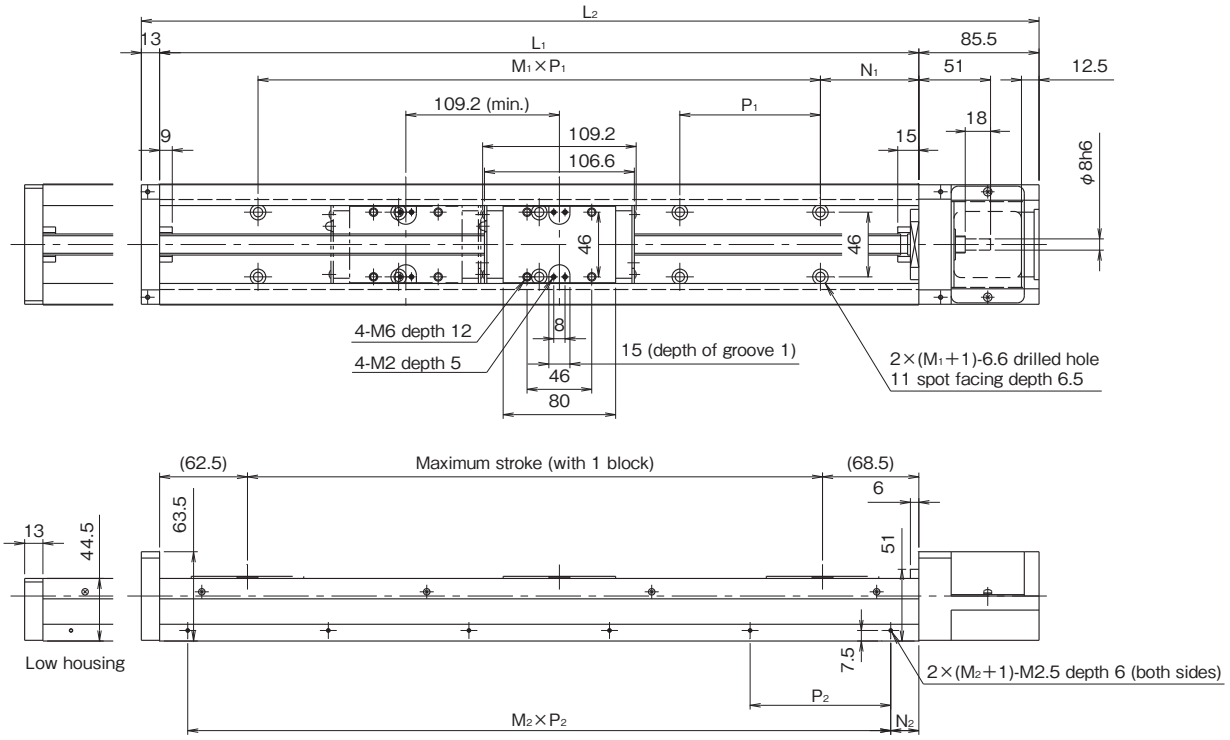
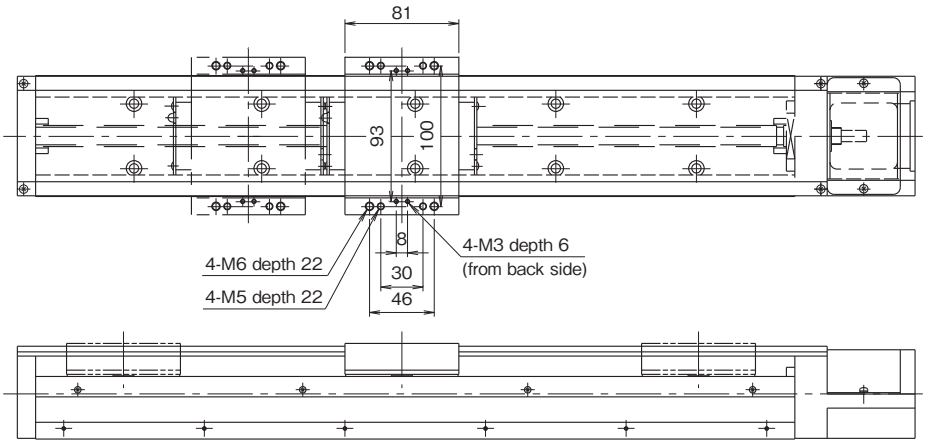
● LONG BLOCK CONFIGURATIONS

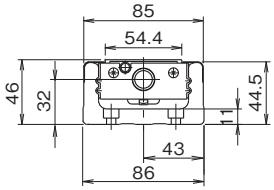
With 1 long block: A (With 2 long blocks: B)



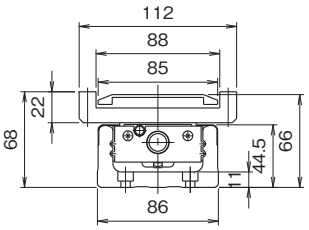
With dustproof cover



Without dustproof cover



With dustproof cover



KURODA JENATEC

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● LONG BLOCK DIMENSIONS

(Unit: mm)

Guide rail length L_1	Overall length L_2	N_1	$M_1 \times P_1$	N_2	$M_2 \times P_2$	Maximum stroke	
						Long block	
						A: 1 block	B: 2 blocks
340	438.5	70	2×100	20	3×100	209	100
440	538.5		3×100		4×100	309	200
540	638.5		4×100		5×100	409	300
640	738.5		5×100		6×100	509	400
740	838.5		6×100		7×100	609	500
840	938.5		7×100		8×100	709	600
940	1038.5		8×100		9×100	809	700
1040	1138.5		9×100		10×100	909	800
1140	1238.5		10×100		11×100	1009	900
1240	1338.5		11×100		12×100	1109	1000

● PERMISSIBLE SPEED / MASS

Guide rail length L_1 (mm)	Permissible speed (mm/s)		Mass (kg)					
	Lead		Without cover		With cover		Slide block	
	10mm	20mm	A	B	A	B	Without cover	With cover
340	740	1480	6.5	7.5	7.0	8.0	0.90	1.20
440			8.0	8.5	8.5	9.5		
540			9.0	10.0	10.0	11.0		
640			10.5	11.5	11.0	12.5		
740	650	1300	12.0	13.0	12.5	14.0		
840	500	1000	13.0	14.0	14.0	15.5		
940	390	780	14.5	15.5	15.5	16.5		
1040	315	630	16.0	17.0	17.0	18.0		
1140	260	520	17.5	18.0	18.5	19.5		
1240	220	440	18.5	19.5	19.5	21.0		

(Note 1) The mass indicated in the columns "Without cover" and "With cover" in the above table includes the mass of slide block.
(Note 2) For long rail configurations, please consult KURODA.

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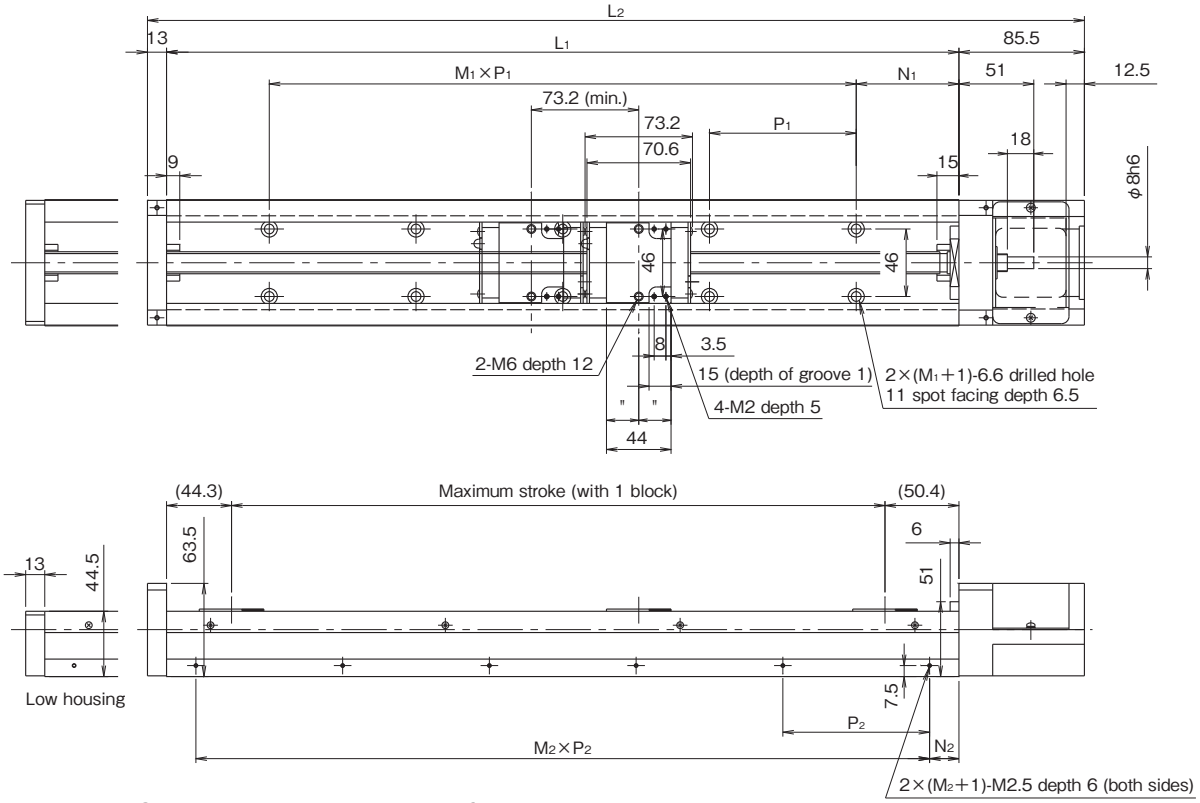
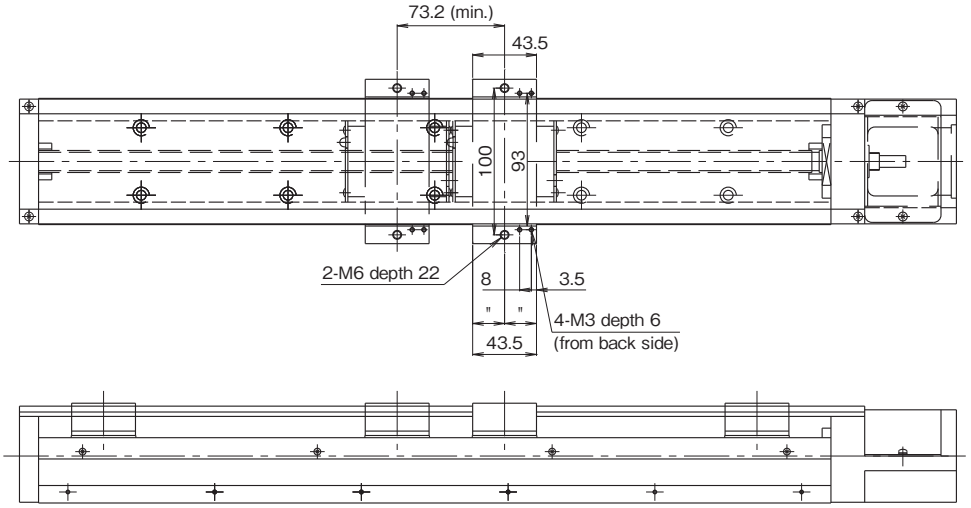
● SHORT BLOCK CONFIGURATIONS

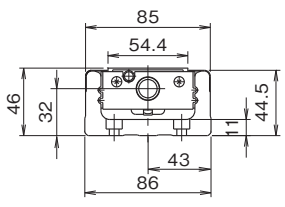
With 1 short block: C (With 2 short blocks: D)



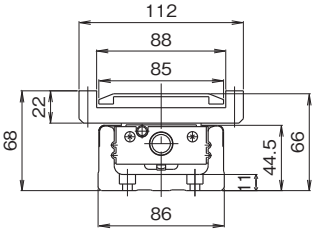
Short block with dustproof cover



Without dustproof cover



With dustproof cover



KURODA JENATEC

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● SHORT BLOCK DIMENSIONS

(Unit: mm)

Guide rail length L_1	Overall length L_2	N_1	$M_1 \times P_1$	N_2	$M_2 \times P_2$	Maximum stroke	
						Short block	
						C: 1 block	D: 2 blocks
340	438.5	70	2×100	20	3×100	245	172
440	538.5		3×100		4×100	345	272
540	638.5		4×100		5×100	445	372
640	738.5		5×100		6×100	545	472
740	838.5		6×100		7×100	645	572
840	938.5		7×100		8×100	745	672
940	1038.5		8×100		9×100	845	772
1040	1138.5		9×100		10×100	945	872
1140	1238.5		10×100		11×100	1045	972
1240	1338.5		11×100		12×100	1145	1072

● PERMISSIBLE SPEED / MASS

Guide rail length L_1 (mm)	Permissible speed (mm/s)		Mass (kg)					
	Lead		Without cover		With cover		Slide block	
	10mm	20mm	C	D	C	D	Without cover	With cover
340	740	1480	6.0	6.5	6.5	7	0.50	0.70
440			7.5	8.0	8	8.5		
540			8.5	9.5	9.5	10		
640			10.0	10.5	10.5	11.5		
740	650	1300	11.5	12.0	12	13		
840	500	1000	13.0	13.5	13.5	14		
940	390	780	14.0	14.5	15	15.5		
1040	315	630	15.5	16.0	16.5	17		
1140	260	520	17.0	17.5	18	18.5		
1240	220	440	18.5	19.0	19	20		

(Note 1) The mass indicated in the columns "Without cover" and "With cover" in the above table includes the mass of slide block.
(Note 2) For long rail configurations, please consult KURODA.

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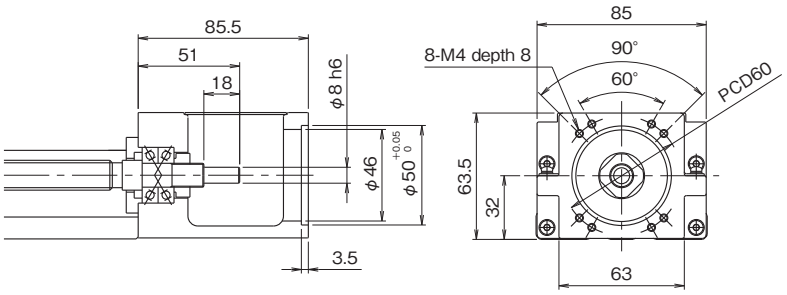
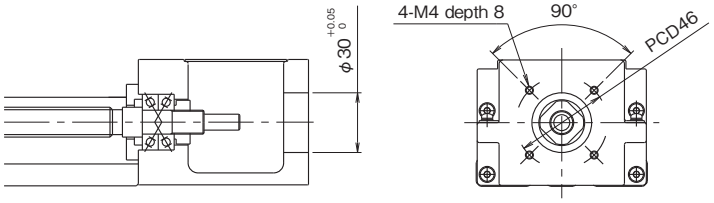
● MOTOR BRACKET CONFIGURATIONS

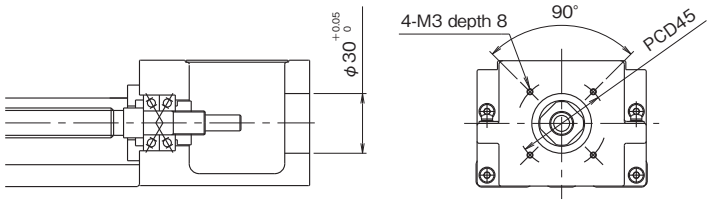
Motor bracket configuration: A0



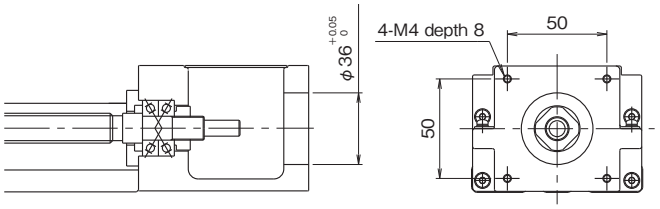
Motor bracket configuration: B0



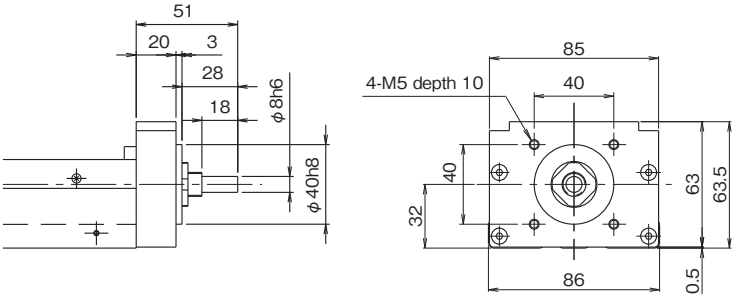
Motor bracket configuration: C0



Motor bracket configuration: D0



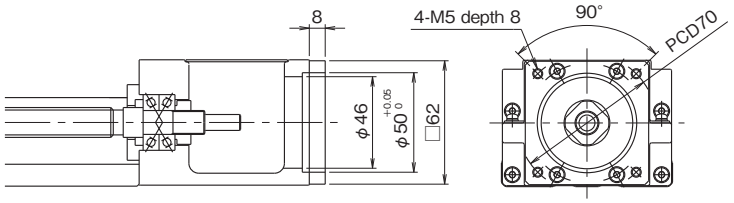
Motor bracket configuration: R0



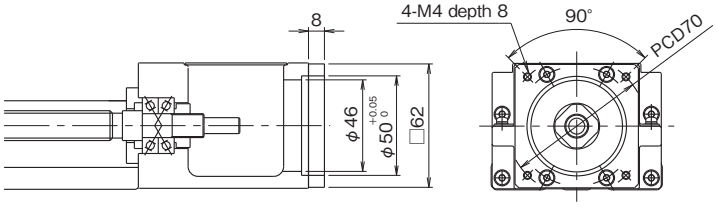
Mass of the R0 configuration is 0.3 kg less than the value shown in the table on page 37.

● MOTOR BRACKET CONFIGURATIONS (INTERMEDIATE FLANGE)

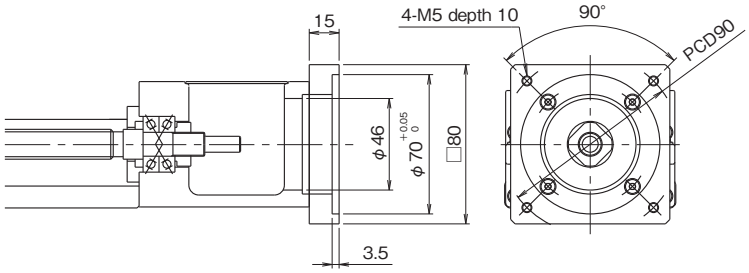
Motor bracket configuration: A1 (mass: 103g)



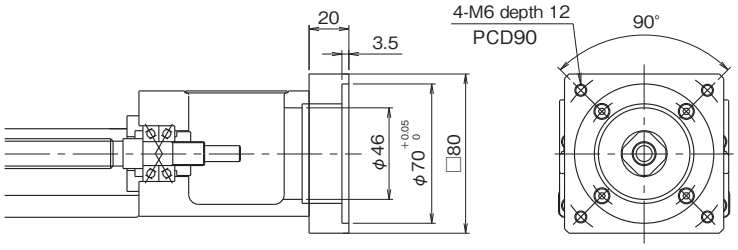
Motor bracket configuration: A2 (mass: 106g)



Motor bracket configuration: A3 (mass: 448g)



Motor bracket configuration: A4 (mass: 628g)



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● MOTOR BRACKET CONFIGURATIONS AND MOTOR OPTION

Motor option					Motor bracket configuration	Recommended coupling
Motor type	Maker	Series	Model No.	Output		
AC SERVO motor	PANASONIC	MINAS E	MUMA02	200W	A2	SFC-030DA2 (MIKI PULLEY) ACD-34A (ISEL)
			MUMA04	400W		
		MINAS A5	MSME5A	50W	C0	SFC-020DA2 (MIKI PULLEY) ACD-27A (ISEL)
			MSME01	100W		
			MSME02	200W	A2	SFC-030DA2 (MIKI PULLEY) ACD-34A (ISEL)
			MSME04	400W		
			MSME08	750W	A3	SFC-040DA2 (MIKI PULLEY) ACD-44A (ISEL)
		MINAS A6	MSMF5A	50W	C0	SFC-020DA2 (MIKI PULLEY) ACD-27A (ISEL)
			MSMF01	100W		
			MSMF02	200W	A2	SFC-030DA2 (MIKI PULLEY) ACD-34A (ISEL)
			MSMF04	400W		
			MSMF08	750W	A3	SFC-040DA2 (MIKI PULLEY) ACD-44A (ISEL)
	MITSUBISHI ELECTRIC	MELSERVO J3	HF-KP (MP) 053	50W	B0	SFC-020DA2 (MIKI PULLEY) ACD-27A (ISEL)
			HF-KP (MP) 13	100W		
			HF-KP (MP) 23	200W	A1	SFC-030DA2 (MIKI PULLEY) ACD-34A (ISEL)
			HF-KP (MP) 43	400W		
			HF-KP (MP) 73	750W	A4	SFC-040DA2 (MIKI PULLEY) ACD-44A (ISEL)
		MELSERVO J4	HG-KR (MR) 053	50W	B0	SFC-020DA2 (MIKI PULLEY) ACD-27A (ISEL)
			HG-KR (MR) 13	100W		
			HG-KR (MR) 23	200W	A1	SFC-030DA2 (MIKI PULLEY) ACD-34A (ISEL)
			HG-KR (MR) 43	400W		
			HG-KR (MR) 73	750W	A4	SFC-040DA2 (MIKI PULLEY) ACD-44A (ISEL)
	YASKAWA ELECTRIC	Σ-V	SGMJV, SGMAV-A5	50W	B0	SFC-020DA2 (MIKI PULLEY) ACD-27A (ISEL)
			SGMJV, SGMAV-01	100W		
			SGMJV, SGMAV-C2	150W		
			SGMJV, SGMAV-02	200W	A1	SFC-030DA2 (MIKI PULLEY) ACD-34A (ISEL)
			SGMJV, SGMAV-04	400W		
			SGMJV, SGMAV-06	600、550W		SFC-035DA2 (MIKI PULLEY) ACD-39A (ISEL)
			SGMJV, SGMAV-08	750W	A4	SFC-040DA2 (MIKI PULLEY) ACD-44A (ISEL)
		Σ-7	SGM7J, SGM7A-A5	50W	B0	SFC-020DA2 (MIKI PULLEY) ACD-27A (ISEL)
			SGM7J, SGM7A-01	100W		
			SGM7J, SGM7A-C2	150W		
			SGM7J, SGM7A-02	200W	A1	SFC-030DA2 (MIKI PULLEY) ACD-34A (ISEL)
			SGM7J, SGM7A-04	400W		
			SGM7J, SGM7A-06	600W		SFC-035DA2 (MIKI PULLEY) ACD-39A (ISEL)
			SGM7J, SGM7A-08	750W	A4	SFC-040DA2 (MIKI PULLEY) ACD-44A (ISEL)
	SANYO ELECTRIC	SANMOTION R	R2AA04005	50W	B0	SFC-020DA2 (MIKI PULLEY) ACD-27A (ISEL)
			R2AA04010	100W		
			R2AA06020	200W	A1	SFC-030DA2 (MIKI PULLEY) ACD-34A (ISEL)
			R2AA06040	400W		
			R2AA08075	750W	A4	SFC-040DA2 (MIKI PULLEY) ACD-44A (ISEL)
Stepping motor	ORIENTAL MOTOR	α step	ARM6	□60mm	D0	SFC-020DA2 (MIKI PULLEY) LACD-27A (ISEL)
	SANYO ELECTRIC	5-Phase	F series□60mm	□60mm	D0	

・For motors other than above-mentioned, consult KURODA.
・When selecting a rigid type of coupling for connecting a motor, consult KURODA.
・For detailed specifications of above-mentioned motors and couplings, refer to catalogs or websites provided by the makers.

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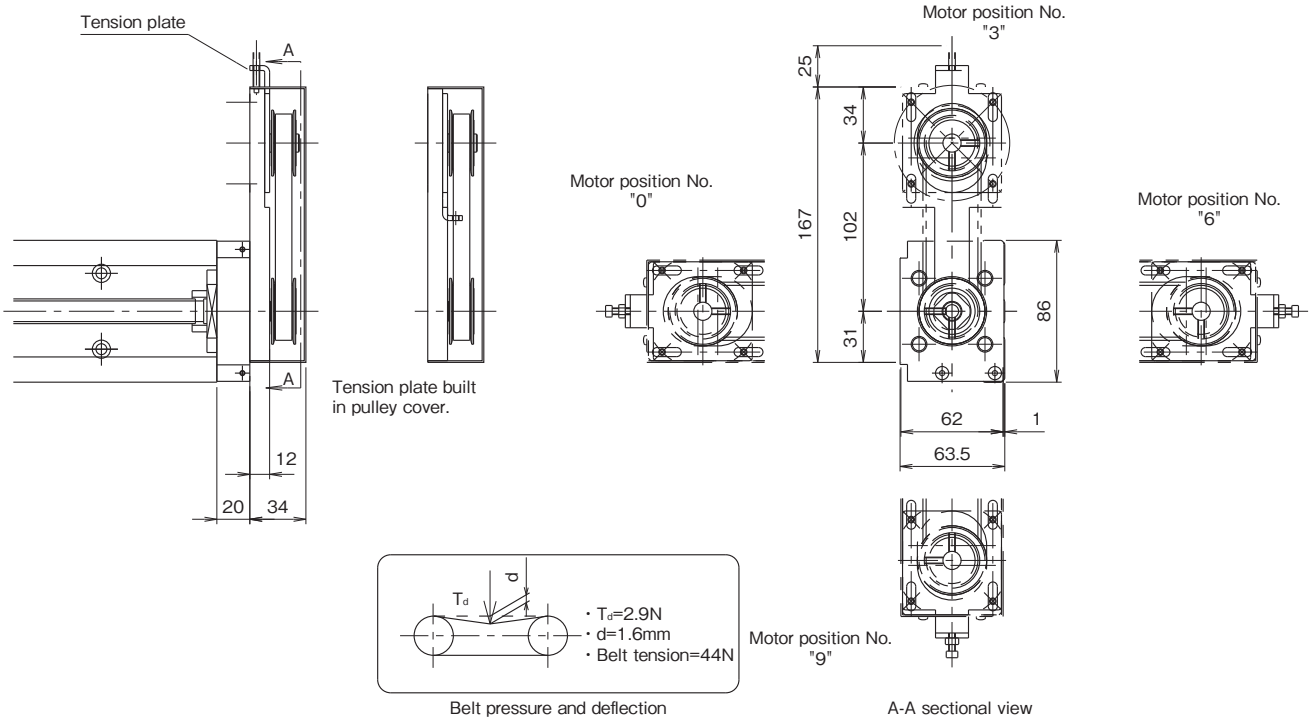
● PARALLEL MOTOR MOUNTING

● SG46

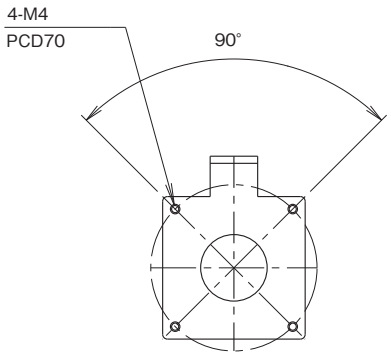


・Pulley unit position can be adjusted at every 90 degree.
・Motor parallel mounting can be equipped with dustproof cover and sensor.
・Tension plate position can be built in pulley cover.
・The mass is 0.7kg larger than the values shown in tables on pages 35 and 37.
・Inertia moment is 1.24×10^{-5}kg・m² larger than the value shown in table on page 5.

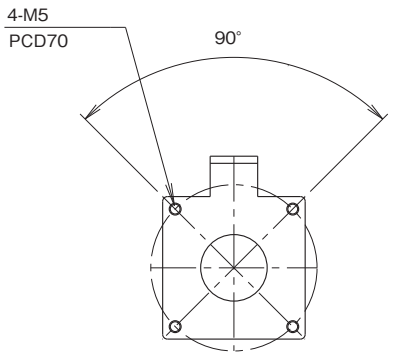
Mark	Pulley Inner dia.	Applicable motor	
E□	Inner dia. ϕ11	Panasonic	200W motor and so on
F□	Inner dia. ϕ14	Yaskawa	200W motor and so on
		Mitsubishi Electric	200W motor and so on
		Sanyo Electric	200W motor and so on
G□	Inner dia. ϕ8	Oriental Motor Stepping Motor □60 series and so on	

Fullfill the motor position No. in □.
Check the spec. if the motor can be assembled before using.

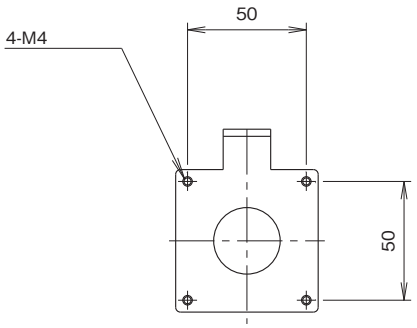
Parallel motor mounting type E□
Tension plate dimension



Parallel motor mounting type F□
Tension plate dimension



Parallel motor mounting type G□
Tension plate dimension



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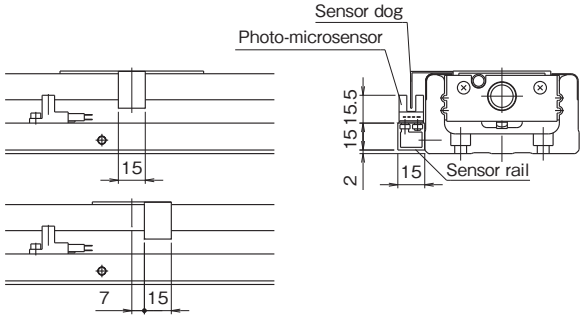
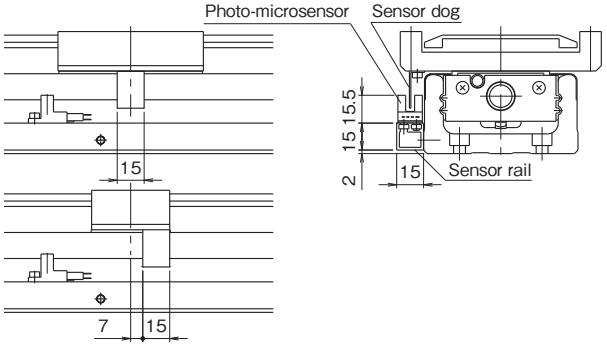
● SENSOR

Symbol C (NPN) / P (PNP), M (NPN) / Y (PNP): Photo-microsensor (OMRON, Panasonic Industrial Devices SUNX)

Without dustproof cover

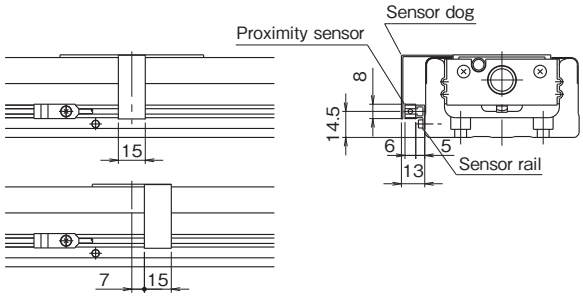


With dustproof cover

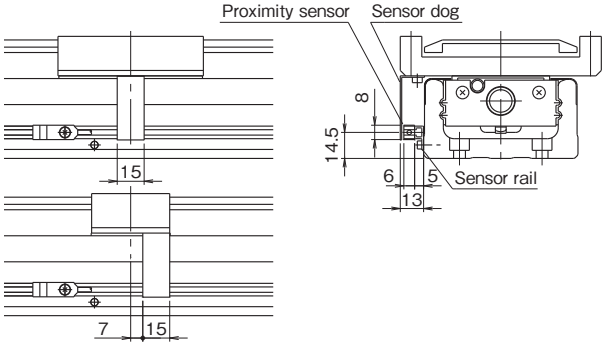


Symbol K (NPN) / E (PNP): Proximity sensor (Azbil)

Without dustproof cover

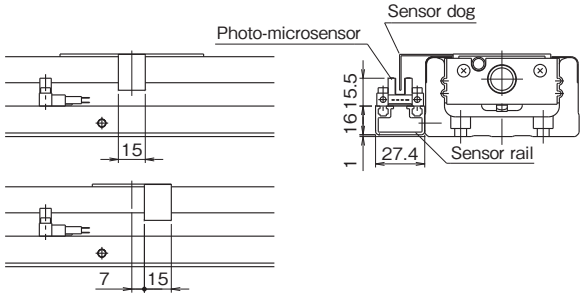


With dustproof cover

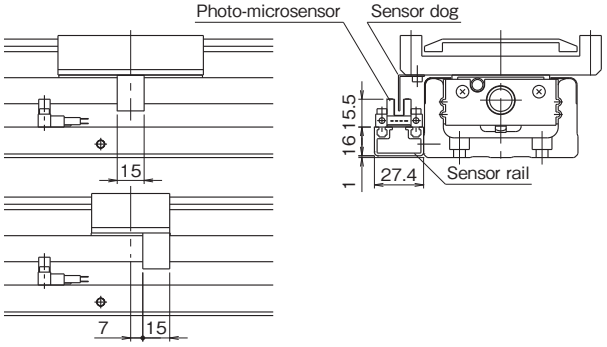


Symbol H (NPN) / J (PNP): Photo-microsensor (OMRON)

Without dustproof cover



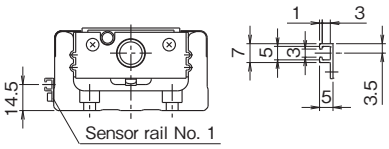
With dustproof cover



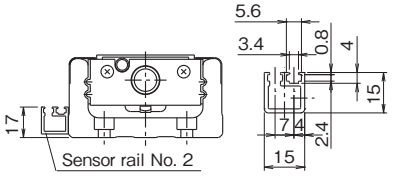
● SENSOR RAIL

Sensor rails only available with no sensors.

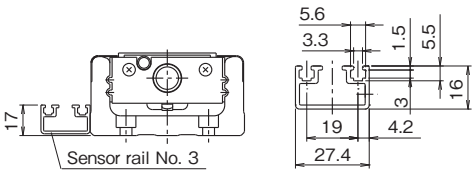
Sensor rail No. 1



Sensor rail No. 2



Sensor rail No. 3



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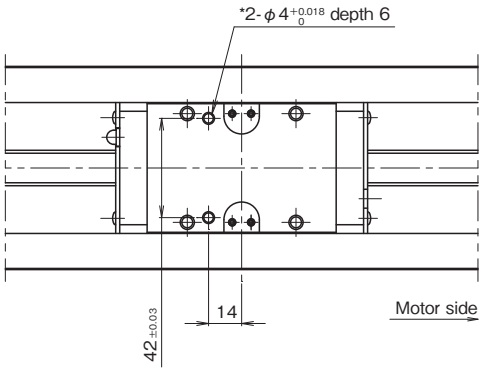
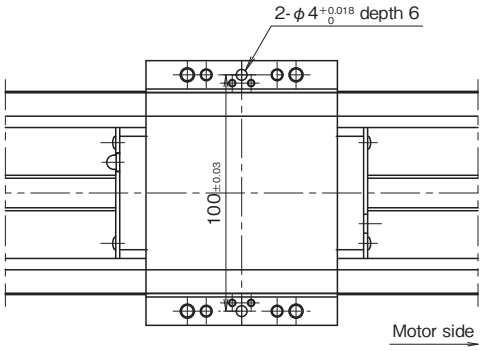
● DOWEL PIN HOLE

Dowel pin holes are applicable on the slide blocks with part number "PS", sub-tables "PR"or slide blocks and sub-tables "PSR". For actuators with 2 blocks, they are on both driving-side block and driven-side block. Please note that dowel pins are not equipped.

Long block without dustproof cover with "PS"

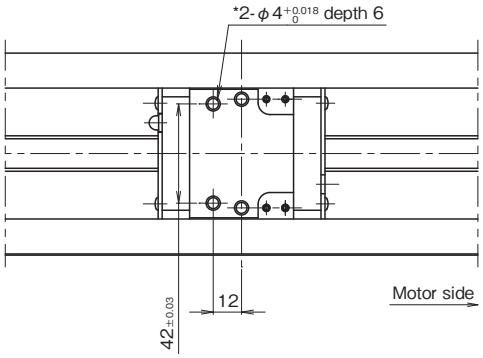


Long block with dustproof cover with "PS"

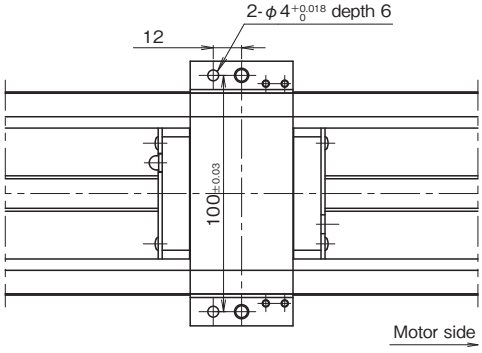


The hole with asterisk (*) may have diameter 5 counterbores depth 2 for erasing the quenching layer when needed.

Short block without dustproof cover with "PS"

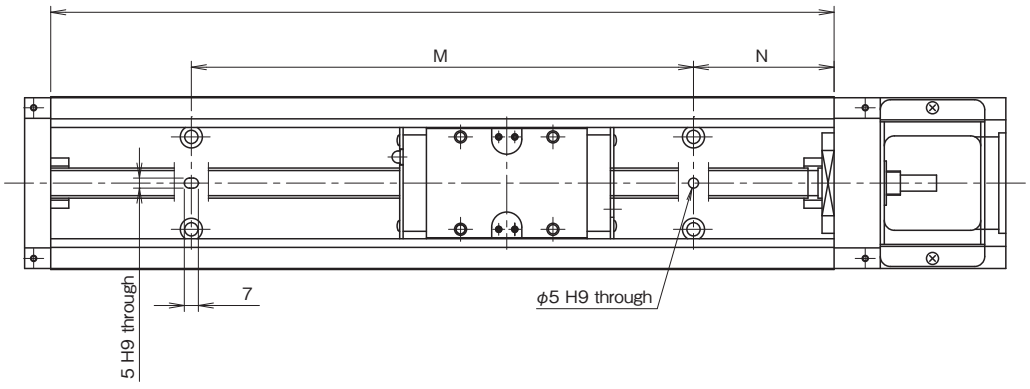


Short block with dustproof cover with "PS"



The hole with asterisk (*) may have diameter 5 counterbores depth 2 for erasing the quenching layer when needed.

Guide rail with "PR"



(Unit: mm)

Guide rail length	N	M	Dowel pin height
340	70	200	Less than 11
440		300	
540		400	
640		500	
740		600	
840		700	
940		800	
1040		900	
1140		1000	
1240		1100	

Notice: In case dowel pin is stuck out from the U-guide rail, it may interfere with and break the slide block.

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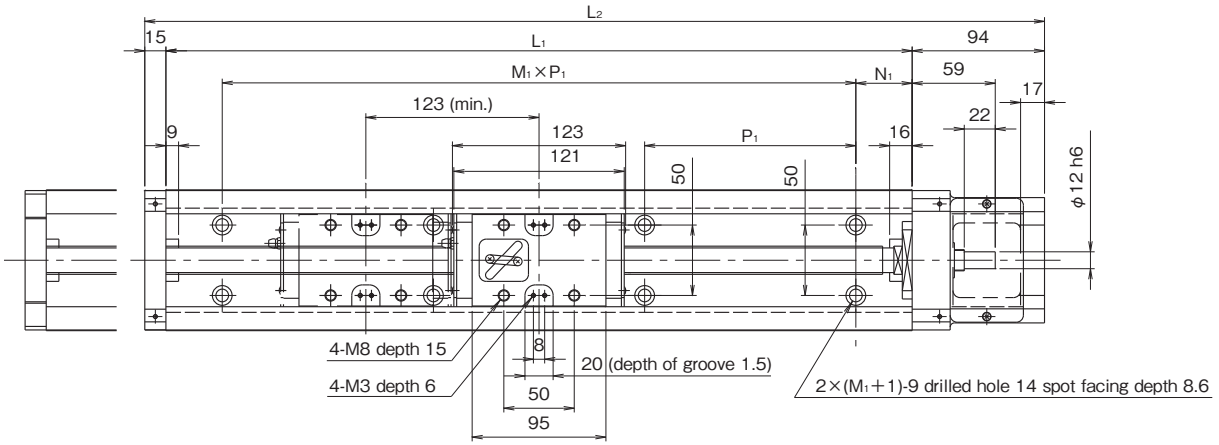
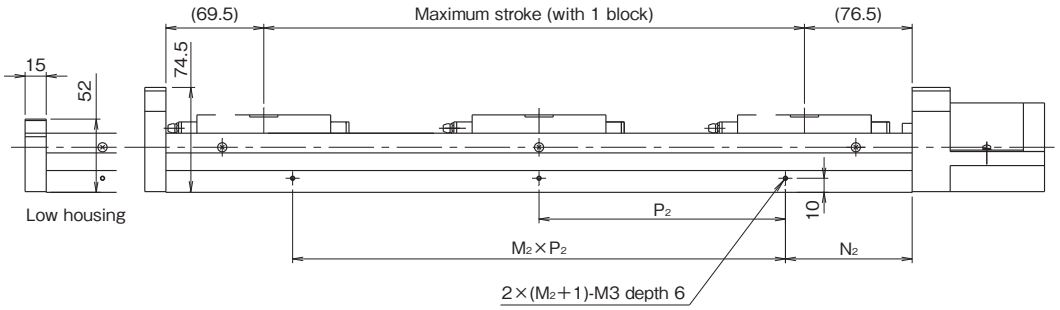
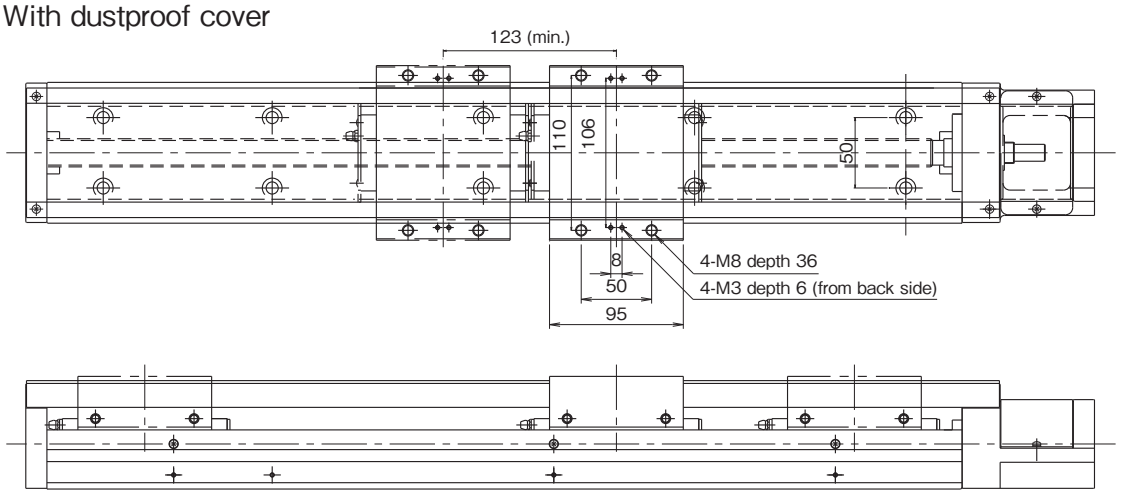
● LONG BLOCK CONFIGURATIONS

With 1 long block: A (With 2 long blocks: B)

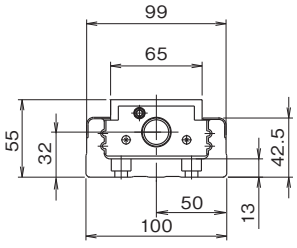




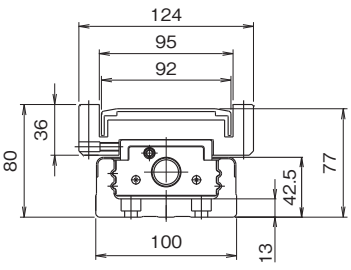
With dustproof cover



Without dustproof cover



With dustproof cover



KURODA JENATEC

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● LONG BLOCK DIMENSIONS

(Unit: mm)

Guide rail length L_1	Overall length L_2	N_1	$M_1 \times P_1$	N_2	$M_2 \times P_2$	Maximum stroke	
						Long block	
						A: 1 block	B: 2 blocks
980	1089	40	6×150	90	4×200	834	711
1080	1189	15	7×150	40	5×200	934	811
1180	1289	65		90		1034	911
1280	1389	40	8×150	40	6×200	1134	1011
1380	1489	15	9×150	90		1234	1111

● PERMISSIBLE SPEED / MASS

Guide rail length L_1 (mm)	Permissible speed (m/s)	Mass (kg)					
	Lead	Without cover		With cover		Slide block	
	20mm	A	B	A	B	Without cover	With cover
980	1120	20	22	21	24	1.70	2.30
1080	910	22	24	23	26		
1180	750	23	25	25	27		
1280	630	25	27	27	29		
1380	530	27	29	29	31		

(Note 1) The mass indicated in the columns "Without cover" and "With cover" in the above table includes the mass of slide block.
(Note 2) For long rail configurations, please consult KURODA.

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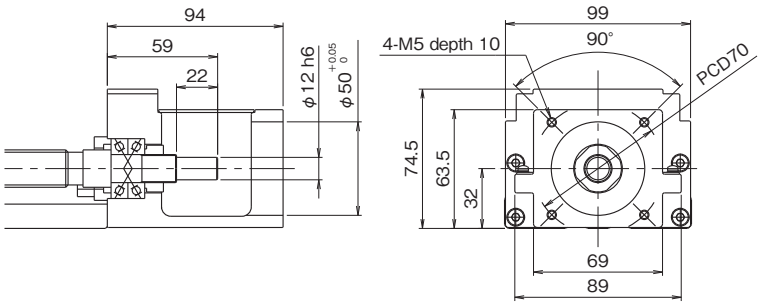
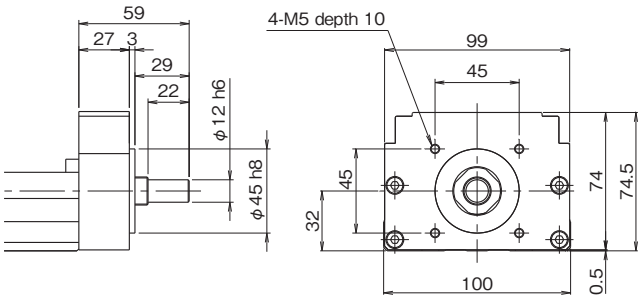
● MOTOR BRACKET CONFIGURATIONS

Motor bracket configuration: A0



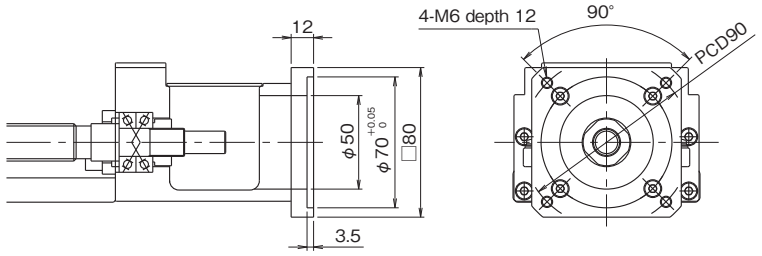
Motor bracket configuration: R0



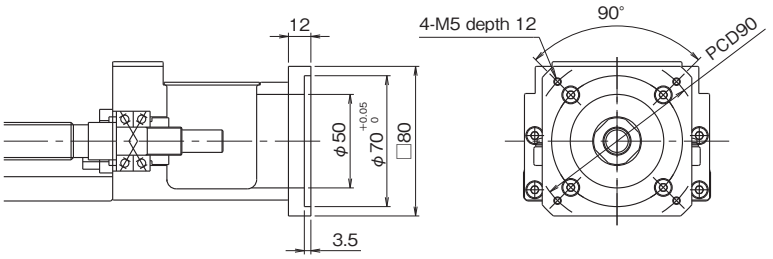
Mass of the R0 configuration is 0.3 kg less than the value shown in the table on page 45.

● MOTOR BRACKET CONFIGURATIONS (INTERMEDIATE FLANGE)

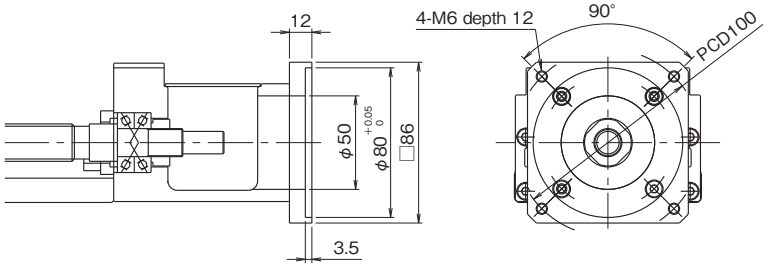
Motor bracket configuration: A1 (mass: 329g)



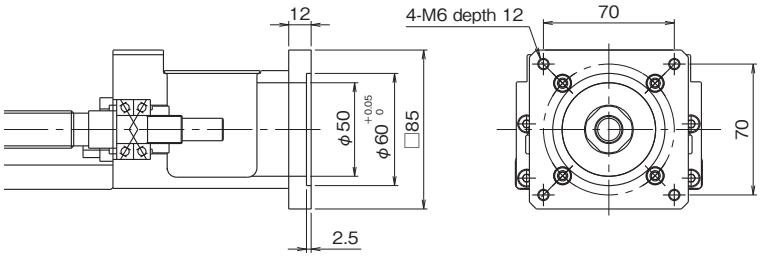
Motor bracket configuration: A2 (mass: 333g)



Motor bracket configuration: A3 (mass: 399g)



Motor bracket configuration: A4 (mass: 449g)



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● MOTOR BRACKET CONFIGURATIONS AND MOTOR OPTION

Motor option					Motor bracket configuration	Recommended coupling
Motor type	Maker	Series	Model No.	Output		
AC SERVO motor	PANASONIC	MINAS A5	MSME08	750W	A2	SFC-040DA2 (MIKI PULLEY) ACD-44A (ISEL)
		MINAS A6	MSMF08			
	MITSUBISHI ELECTRIC	MELSERVO J3	HF-KP (MP) 23	200W	A0	SFC-035DA2 (MIKI PULLEY) ACD-39A (ISEL)
			HF-KP (MP) 43	400W		
			HF-KP (MP) 73	750W	A1	SFC-040DA2 (MIKI PULLEY) ACD-44A (ISEL)
		MELSERVO J4	HG-KR (MR) 23	200W	A0	SFC-035DA2 (MIKI PULLEY) ACD-39A (ISEL)
			HG-KR (MR) 43	400W		
			HG-KR (MR) 73	750W	A1	SFC-040DA2 (MIKI PULLEY) ACD-44A (ISEL)
	YASKAWA ELECTRIC	Σ-V	SGMJV, SGMAV-02	200W	A0	SFC-035DA2 (MIKI PULLEY) ACD-39A (ISEL)
			SGMJV, SGMAV-04	400W		
			SGMJV, SGMAV-06	600、550W		
			SGMJV, SGMAV-08	750W	A1	SFC-040DA2 (MIKI PULLEY) ACD-44A (ISEL)
		Σ-7	SGM7J, SGM7A-02	200W	A0	SFC-035DA2 (MIKI PULLEY) ACD-39A (ISEL)
			SGM7J, SGM7A-04	400W		
			SGM7J, SGM7A-06	600W		
			SGM7J, SGM7A-08	750W	A1	SFC-040DA2 (MIKI PULLEY) ACD-44A (ISEL)
	SANYO ELECTRIC	SANMOTION R	R2AA06020	200W	A0	SFC-035DA2 (MIKI PULLEY) ACD-39A (ISEL)
			R2AA06040	400W		
			R2AA08075	750W	A1	SFC-040DA2 (MIKI PULLEY) ACD-44A (ISEL)
Stepping motor	ORIENTAL MOTOR	α step	ARM9	□85mm	A4	SFC-035DA2 (MIKI PULLEY) ACD-39A (ISEL)
	SANYO ELECTRIC	5-Phase	F series□85mm	□86mm		

・For motors other than above-mentioned, consult KURODA.
・When selecting a rigid type of coupling for connecting a motor, consult KURODA.
・For detailed specifications of above-mentioned motors and couplings, refer to catalogs or websites provided by the makers.

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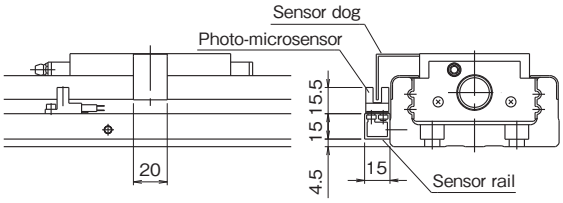
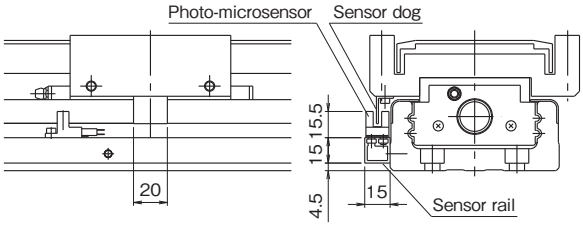
● SENSOR

Symbol C (NPN) / P (PNP), M (NPN) / Y (PNP): Photo-microsensor (OMRON, Panasonic Industrial Devices SUNX)

Without dustproof cover

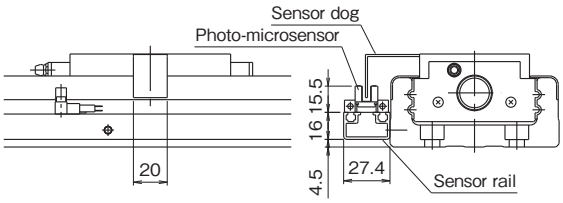


With dustproof cover

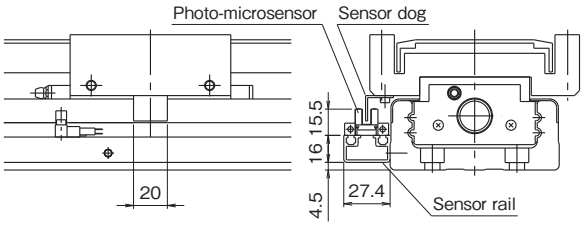


Symbol H (NPN) / J (PNP): Photo-microsensor (OMRON)

Without dustproof cover

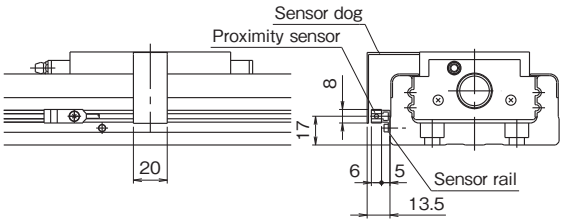


With dustproof cover

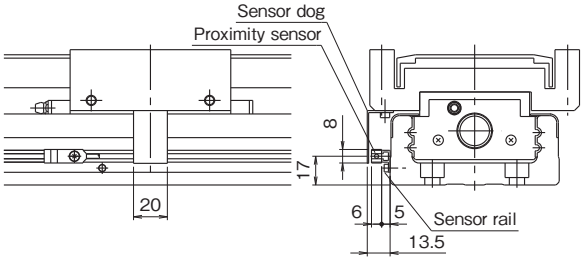


Symbol K (NPN) / E (PNP): Proximity sensor (Azbil)

Without dustproof cover



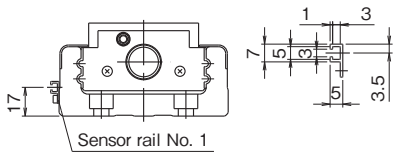
With dustproof cover



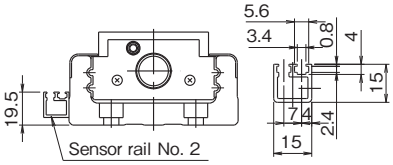
● SENSOR RAIL

Sensor rails only available with no sensors.

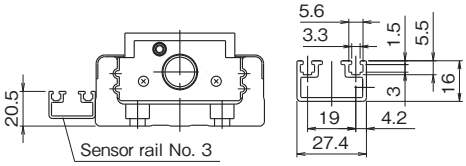
Sensor rail No. 1



Sensor rail No. 2



Sensor rail No. 3



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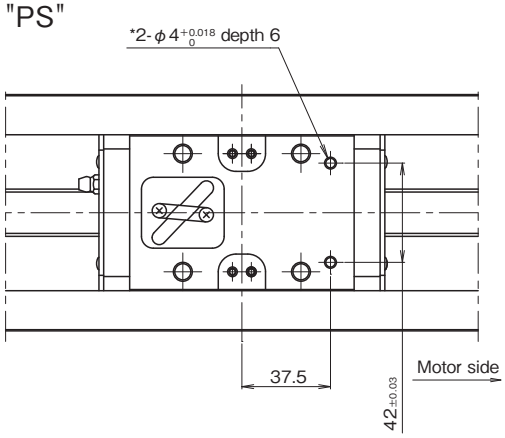
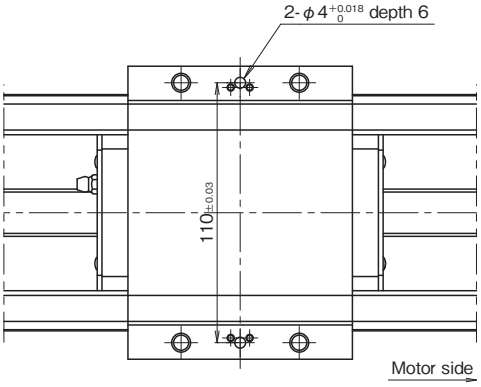
● DOWEL PIN HOLE

Dowel pin holes are applicable on the slide blocks with part number "PS", sub-tables "PR"or slide blocks and sub-tables "PSR". For actuators with 2 blocks, they are on both driving-side block and driven-side block. Please note that dowel pins are not equipped.

Long block without dustproof cover with "PS"

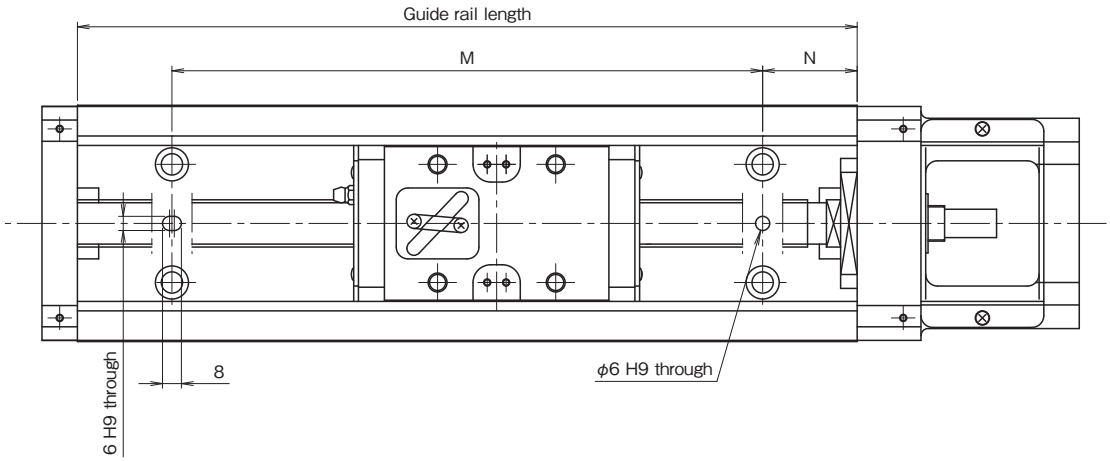


Long block with dustproof cover with "PS"



The hole with asterisk (*) may have diameter 5 counterbores depth 2 for erasing the quenching layer when needed.

Guide rail with "PR"



(Unit: mm)

Guide rail length	N	M	Dowel pin height
980	40	900	Less than 13
1080	15	1050	
1180	65	1050	
1280	40	1200	
1380	15	1350	

Notice: In case dowel pin is stuck out from the U-guide rail, it may interfere with and break the slide block.

● Specifications

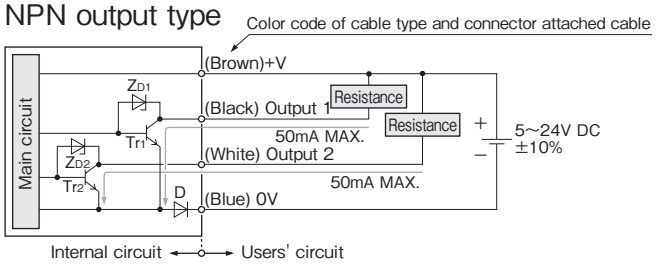
Model No.	NPN output type	PM-L25	PM-Y65
	PNP output type	-	PM-Y65P
Sensing range		6mm (fixed)	
Minimum sensing object		0.8X1.2mm opaque object	
Hysteresis		0.05mm or less	
Repeatability		0.01mm or less	
Supply voltage		5 to 24V DC ±10% Ripple P-P 10% or less	
Current consumption		15mA or less	
Output		NPN output type: NPN transistor open collector Maximum sink current : 50mA Applied voltage : 30V DC or less (between output and 0V) Residual voltage : 2V or less (at 50mA sink current) 1V or less (at 16mA sink current)	NPN output type: NPN transistor open collector Maximum sink current : 50mA Applied voltage : 30V DC or less (between output and 0V) Residual voltage : 2V or less (at 50mA sink current) 1V or less (at 16mA sink current) PNP output type: PNP transistor open collector Maximum sink current : 50mA Applied voltage : 30V DC or less (between output and +V) Residual voltage : 2V or less (at 50mA sink current) 1V or less (at 16mA sink current)
Output operation		Incorporated with 2 outputs : Light-ON/Dark-ON	
Short-circuit protection		Incorporated	
Response time		Under light received condition : 20μs or less Under light shielded condition : 80μs or less (Maximum response frequency 3kHz)	
Operation indicator		Orange LED (lights up under light received condition)	
Pollution degree		3	
Environmental resistance	Protection	IP64 (IEC)	IP40 (IEC)
	Ambient temperature	-25 to +55℃: (No dew condensation or icing allowed), Storage: -30 to +80℃:	
	Ambient humidity	5 to 85% RH, Storage: 5 to 95% RH	
	Ambient illuminance	Fluorescent light : 1000lx or less at the light-receiving face	
	Voltage withstandability	1000V AC for 1 min. between all supply terminals connected together and enclosure	
	Insulation resistance	20MΩ or more with 250V DC megger between all supply terminals connected together and enclosure	
	Vibration resistance	10 to 2000Hz frequency, 1.5mm amplitude (maximum acceleration 196m/s^2) in X, Y and Z directions for 2 hours each	
	Shock resistance	15000m/s^2 acceleration (1500G approx.) in X, Y and Z directions for 3 times each	
Emitting element		Infrared LED (Peak emission wavelength: 855nm (0.034mil), non-modulated)	
Material		Case: PBT Display: Polycarbonate	
Cable		0.09mm^2 4-core cabtyre cable, 1m long	-
Cable extension		Extension up to total 100m (328.084ft) is possible with 0.3mm^2, or more, cable.	Extension up to total 100m (328.084ft) is possible with 0.3mm^2, or more, cable.
Mass		Main body : 10g approx.	Main body : 3g approx.

Accessories	Specifications		
	S	M	Y
Sensor Model No.	PM-L25 (NPN) : 3	PM-Y65 (NPN) : 3	PM-Y65P (PNP) : 3
Sensor mounting plate (Note 1)	: 3	: 3	: 3
Sensor rail	: 1	: 1	: 1
Sensor dog (Note 2)	: 1	: 1	: 1
Connector for sensor	-	CN-14A : 3	CN-14A : 3

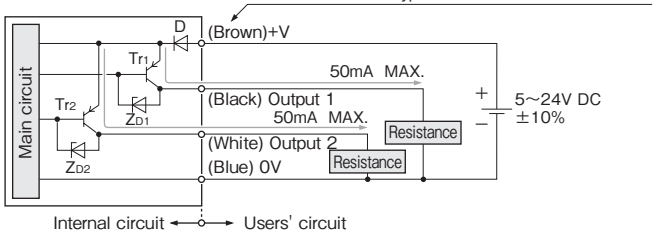
(Note 1) Sensor mounting plate is applied to SE and SC series.
(Note 2) 2 sensor dogs are used for SG33□D-150 sensor with Symbol "M" or "Y".

● I/O circuit diagram

NPN output type

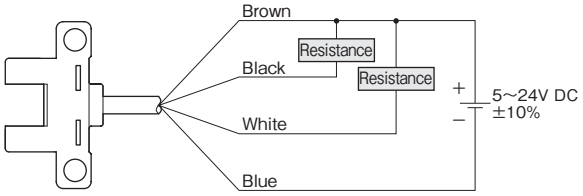


PNP output type

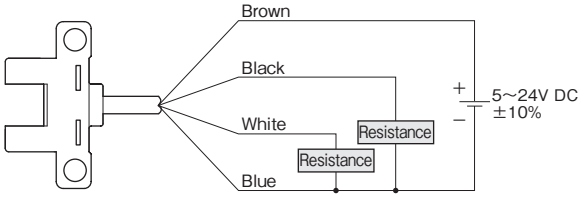


● Wiring diagram

NPN output type



PNP output type



(Note) For detailed information and operating precautions, refer to catalogs and operating instructions supplied by the sensor maker.

PROXIMITY SENSOR/Azbil

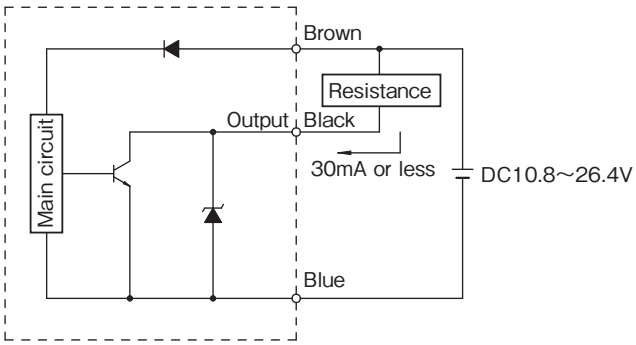
● Specifications

Model No.	NPN output type	APM-D3B1, APM-D3B1F (different-frequency type)
	PNP output type	APM-D3E1, APM-D3E1F (different-frequency type)
Sensing method		High-frequency oscillation type (unshielded type)
Rated supply voltage		DC 12/24V
Rated sensing distance		2.5mm ±15%
Usable sensing distance		0～1.8mm
Sensing object		15×15mm t=1mm Iron
Hysteresis		15% or less in sensing length
Operating voltage range		DC 10.8～26.4V(Ripple 10% or less)
Current consumption		10mA or less
Output type		NPN transistor open collector
		PNP transistor open collector
Operation mode		Normally closed (N.C.)
Control Output	Switching current	30mA or less (resistance load)
	Residual voltage	1V or less (switching current 30mA
	Output dielectric strength	26.4V
Response frequency		120Hz
Repeatability		0.05mm or less
Temperature characteristics		±15% max. for the range of -10 to +55℃ when +25℃ is taken as standard temperature in sensing distance
Supply voltage characteristics		±2% max. with 10% voltage fluctuation with rated supply voltage as standard voltage in sensing distance
Operation indicator		Lights up in orange under light received condition
Ambient temperature		−10～+55℃
Ambient temperature at storage		−25～+70℃
Ambient humidity		35～85%RH
Insulation resistance		50MΩ or more (measured by DC 500V insulation ohmmeter)
Voltage withstandability		1000V AC , 50/60Hz for 1 min. between all supply terminals connected together and enclosure
Vibration resistance		10 to 55Hz, 1.5mm amplitude in X, Y, and Z directions for 2 hours each
Shock resistance		500m/s² in X, Y, and Z directions for 3 times each
Protection		IP67 (IEC529)
Mass		10g approx.
Circuit protection		Surge absorption, reverse connection protection circuit (-S: load short protection)
Connection		Pre-leaded (oil-resistant cord: 2.5 mm O.D., 0.08 mm², 3-core, 1 m)
Case material		Polyarylate resin
Tightening torque		0.5N·m (M2.6 screw)

Accessories	Specifications	
	K	E
Sensor Model No.	APM-D3B1 (NPN) : 2	APM-D3E1 (PNP) : 2
	APM-D3B1F (NPN) : 1	APM-D3E1F (PNP) : 1
Sensor rail	: 1	: 1
Sensor dog	: 1	: 1

● Wiring diagram

NPN output type



PNP output type

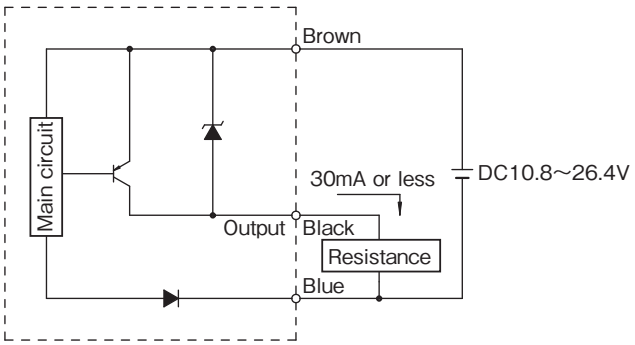


PHOTO-MICROSENSOR/OMRON

● Specifications

Model No.	NPN output type	EE-SX674	EE-SX671
	PNP output type	EE-SX674P	EE-SX671P
Sensing range		5mm (slot width)	
Sensing object		Opaque object 2 x 0.8mm or more	
Hysteresis		0.025mm or less	
Light source (peak emission wavelength)		GaAs IRED (940 nm)	
Operation indicator		Lights up at light-received (Red LED)	
Supply voltage		5 to 24V DC±10% Ripple P-P 10% or less	
Current consumption		12mA and less (connector type, when to open L connector)	
Output		NPN output type: NPN transistor open collector Output : 5 to 24V DC 100mA or less Residual voltage : 0.8V or less (at 100mA load current), 0.4V or less (at 40mA load current) OFF-state current 0.5mA or less	
		PNP output type : PNP transistor open collector Output : 5 to 24V DC 50mA or less Residual voltage : 1.3V or less (at 50mA load current) OFF-state current 0.5mA or less	
Response frequency		1kHz or above (3kHz in average)	
Ambient illuminance		Fluorescent light : 1000 lx at the light-receiving face	
Ambient temperature		Operation: -25 to +55℃, Storage: -30 to +80℃ (no dew condensation or icing allowed)	
Ambient humidity		Operation: 5 to 85% RH, Storage: 5 to 95% RH (no dew condensation or icing allowed)	
Vibration resistance		20 to 2000Hz (100m/s² peaked acceleration), 1.5mm amplitude in X, Y and Z directions for 2 hours each (4min. cycle)	
Shock resistance		500m/s² in X, Y and Z directions for 3 times each	
Protection		IP50 IEC60529	
Connection		Connector (available for direct soldering)	
Mass		3g approx.	
Material	Case	Poly Butylene Terephtalate (PBT)	
	Cover	Polycarbonate	
	Terminal		

Accessories	Specifications			
	C	P	H (Note 2)	J (Note 2)
Sensor Model No.	EE-SX674 (NPN) : 3	EE-SX674P (PNP) : 3	EE-SX671 (NPN) : 3	EE-SX671P (PNP) : 3
Connector for sensor	EE-1001: 3	EE-1001: 3	EE-1001: 3	EE-1001: 3
Sensor rail	: 1	: 1	: 1	: 1
Sensor dog (Note 3)	: 1	: 1	: 1	: 1
Sensor mounting plate (Note 1)	: 3	: 3		

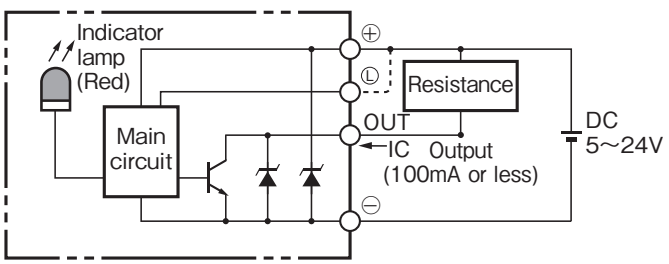
(Note 1) Sensor mounting plate is applied to SE and SC series.

(Note 2) If H or J configuration is used for the model without cover in SG33 series, a sensor mounting plate is attached in addition to the above-mentioned accessories.

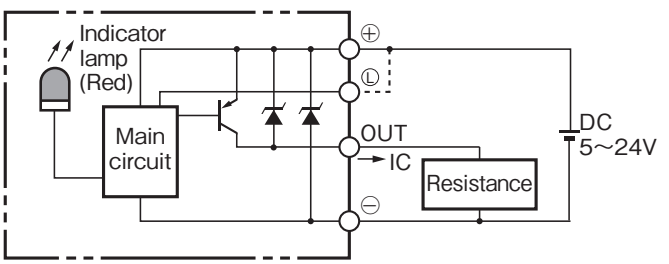
(Note 3) 2 sensor dogs are used for SG33□D-150 sensor with Symbol "M" or "Y".

● I/O circuit diagram

NPN output type



PNP output type



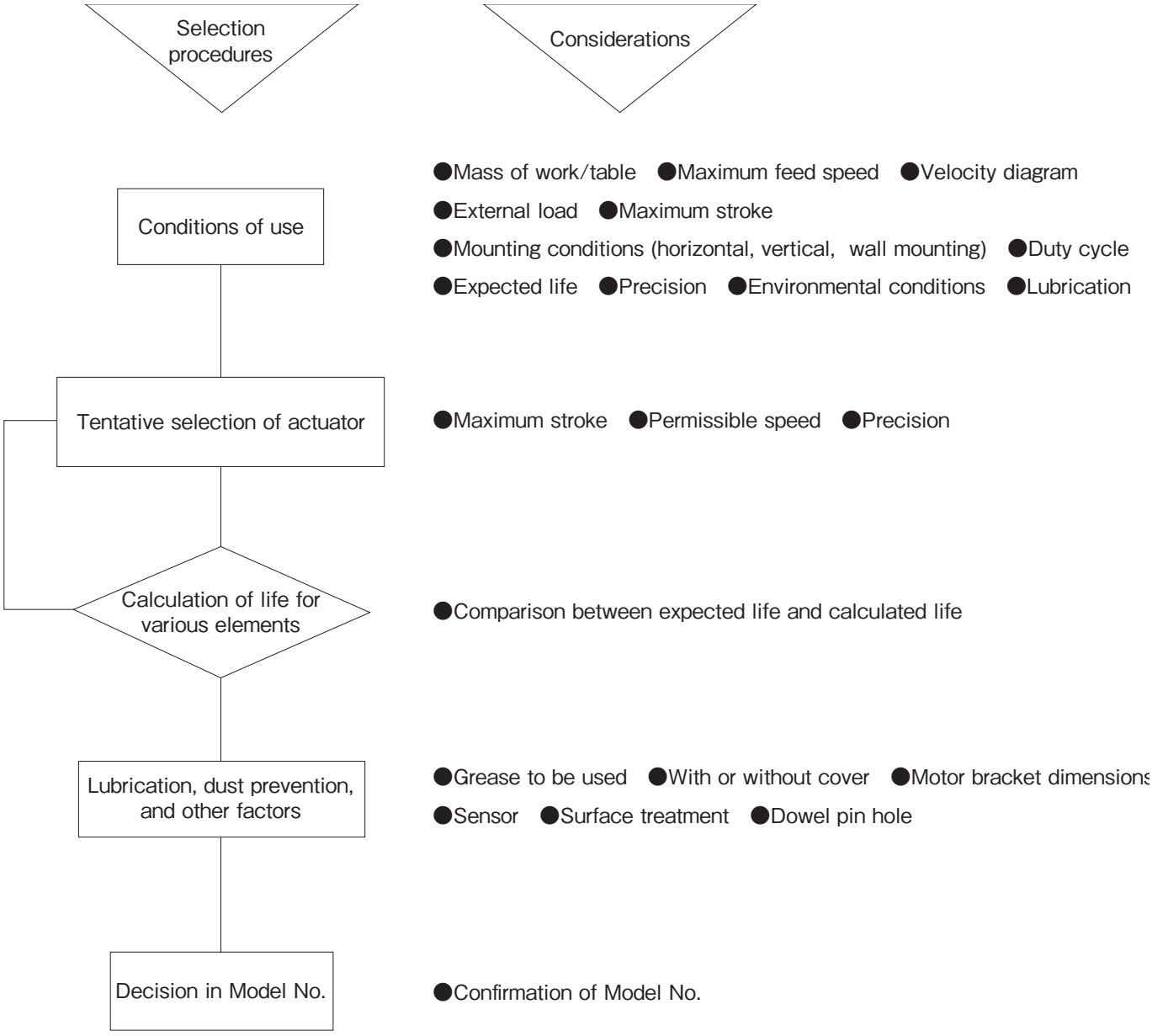
(Note) For detailed information and operating precautions, refer to catalogs and operating instructions supplied by the sensor maker.

CONTENTS

TECHNICAL DATA FOR BALLSCREW ACTUATORS

BALLSCREW ACTUATOR SELECTION GUIDE

Similar to ball screw selections, there is no instant way of selecting appropriate ballscrew actuators for various purposes. The following is an example of general procedures in actuator selection, with some considerations to be made on each step and pages to refer to.



LIFE EXPECTANCY

The shortest life expectancy of among guid-rail, ballscrew and support bearing can be defined as the life expectancy of ballscrew actuators, SE, SG, and SC series.
The following formula is used to calculate the life expectancy.

LIFE EXPECTANCY OF GUIDE

Calculate the life expectancy of guide using the following formula:

$$L_G = \left(\frac{f_C}{f_W} \cdot \frac{C}{P_T} \right)^3 \cdot 50 \quad \text{——— Formula (1)}$$

L_G : Life expectancy operational length (km)
f_C : Contact factor (see Table 1)
f_W : Load factor (see Table 2)
C : Basic dynamic load rating (N)
P_T : Calculated load per block (N)

Calculation of P_T

To calculate the life expectancy using Formula (1), you need to obtain the calculated load per block (P_T) in consideration of actual moment load.
If the acceleration is high or short-stroke operation is conducted, calculate P_T in consideration of acceleration. This acceleration calculation is made for a mass loaded on SG, SE, and SC.
Obtain the calculated load in uniform motion, accelerated motion, and decelerated motion, and its average figure is used as P_T.
For the calculation of P_T, select a calculation formula according to the installation conditions.
If acceleration needs not to be considered,
$P_T = P_{TC}$ (See Formula (2), (5) and (8)) can be used for calculation. However, you can calculate only the approximate value in this formula, therefore it is recommended that you calculate the life expectancy with an ample margin.

Table 1 Contact factor (f_C)

Number of blocks to be used in contact, when single axis module is used.	Contact factor (f_C)
1	1.0
2	0.81

Table 2 Load factor (f_W)

Operating condition		Load factor (f_W)
Vibration and shock	Speed	
Zero	250mm/s or less	1.0～1.5
Small	1000mm/s or less	1.0～2.0
Large	1000mm/s or more	2.0～3.5

Table 3 Moment equivalent factor

	Ep(E2p)	Ey(E2p)	Er(E2r)
SG20**A	2.25×10^{-1}	1.89×10^{-1}	7.84×10^{-2}
SG20**B	3.98×10^{-2}	3.34×10^{-2}	3.92×10^{-2}
SG26**A	1.51×10^{-1}	1.27×10^{-1}	5.88×10^{-2}
SG26**B	2.72×10^{-2}	2.28×10^{-2}	2.94×10^{-2}
SG33**A	1.26×10^{-1}	1.06×10^{-1}	4.55×10^{-2}
SG33**B	2.20×10^{-2}	1.84×10^{-2}	2.27×10^{-2}
SG33**C	2.31×10^{-1}	1.94×10^{-1}	4.55×10^{-2}
SG33**D	3.09×10^{-2}	2.59×10^{-2}	2.27×10^{-2}
SG46**A	8.39×10^{-2}	7.04×10^{-2}	3.17×10^{-2}
SG46**B	1.56×10^{-2}	1.31×10^{-2}	1.59×10^{-2}
SG46**C	1.39×10^{-1}	1.17×10^{-1}	3.17×10^{-2}
SG46**D	2.15×10^{-2}	1.18×10^{-2}	1.59×10^{-2}
SG55**A	6.80×10^{-2}	5.71×10^{-2}	2.74×10^{-2}
SG55**B	1.35×10^{-2}	1.14×10^{-2}	1.37×10^{-2}
SE15**A	2.70×10^{-1}	2.45×10^{-1}	9.64×10^{-2}
SE15**B	4.50×10^{-2}	3.80×10^{-2}	4.82×10^{-2}
SE23**A	1.52×10^{-1}	1.37×10^{-1}	5.22×10^{-2}
SE23**B	2.54×10^{-2}	2.29×10^{-2}	2.61×10^{-2}
SE30**A	1.17×10^{-1}	9.83×10^{-2}	4.54×10^{-2}
SE30**B	1.95×10^{-2}	1.64×10^{-2}	2.27×10^{-2}
SE45**A	8.39×10^{-2}	7.04×10^{-2}	3.17×10^{-2}
SE45**B	1.56×10^{-2}	1.31×10^{-2}	1.59×10^{-2}
SE45**C	1.26×10^{-1}	1.06×10^{-1}	3.17×10^{-2}
SE45**D	2.10×10^{-2}	1.76×10^{-2}	1.59×10^{-2}
SC23**A	1.52×10^{-1}	1.37×10^{-1}	5.22×10^{-2}
SC30**A	1.17×10^{-1}	9.83×10^{-2}	4.54×10^{-2}
SC45**A	8.39×10^{-2}	7.04×10^{-2}	3.17×10^{-2}

(Note) The specifications of a model with two blocks show factors when the two blocks are used in contact.

● P_T in the case of Horizontal Movement (Horizontal Installation)

① For uniform motion (P_{TC})

$$P_{TC}=\frac{1}{n}\cdot W+Ep\cdot M_{pL}+Ey\cdot M_{yL}+Er\cdot M_{rL} \quad \text{Formula (2)}$$

② For accelerated motion (P_{Ta})

$$P_{Ta}=\frac{1}{n}\cdot W+Ep\,(M_{pL}+m\cdot a_a\cdot Z)+Ey\,(M_{yL}+m\cdot a_a\cdot X)+Er\cdot M_{rL} \quad \text{Formula (3)}$$

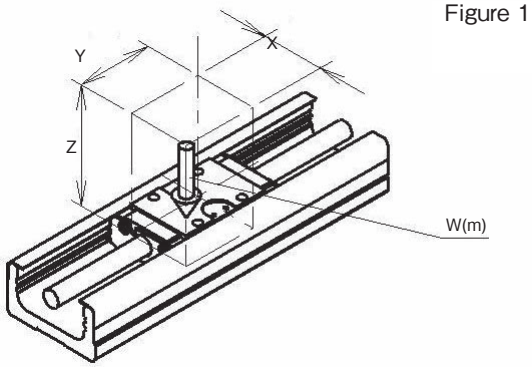
If item $(M_{pL}+m\cdot\alpha_a\cdot Z)$ or $(M_{yL}+m\cdot\alpha_a\cdot X)$ is a negative value, the value should be set to 0.

③ For decelerated motion (P_{Td})

$$P_{Td}=\frac{1}{n}\cdot W+Ep\,(M_{pL}+m\cdot\alpha_d\cdot Z)+Ey\,(M_{yL}+m\cdot\alpha_d\cdot X)+Er\cdot M_{rL} \quad \text{Formula (4)}$$

If item $(M_{pL}+m\cdot\alpha_d\cdot Z)$ or $(M_{yL}+m\cdot\alpha_d\cdot X)$ is a negative value, the value should be set to 0.

Figure 1



If a load is applied from a different direction other than W (m) in this figure, contact KURODA.

P_{TC} : Calculated load per block in uniform motion (N)
P_{Ta} : Calculated load per block in accelerated motion (N)
P_{Td} : Calculated load per block in decelerated motion (N)
n : Number of block of SG / SE / SC
W : Load (N)
m : Load mass (kg)
α_a : Acceleration in accelerated motion (m/sec²)
α_d : Acceleration in decelerated motion (m/sec²) (with a minus sign)
X : Distance from center of SG / SE / SC to center of gravity of loaded mass (mm)
Y : Distance from center of SG / SE / SC to center of gravity of loaded mass (mm)
Z : Distance from center of SG / SE / SC ballscrew to center of gravity of loaded mass (mm)

E_p : Moment equivalent factor in pitching direction (see Table 3)
E_y : Moment equivalent factor in yawing direction (see Table 3)
E_r : Moment equivalent factor in rolling direction (see Table 3)
M_{pL} : Load moment in pitching direction (N·mm)
$M_{pL} = W \cdot Y$
M_{yL} : Load moment in yawing direction (N·mm)
$M_{yL} = 0$ (The load moment is zero under this usage.)
M_{rL} : Load moment in rolling direction (N·mm)
$M_{rL} = W \cdot X$

(Note) For the moment directions, see Pages 3, 53 and 101.

● P_T in the Case of Horizontal Movement (Wall Installation)

① For uniform motion (P_{TC})

$$P_{TC}=\frac{1}{1.19\cdot n}\cdot W+Ep\cdot M_{pL}+Ey\cdot M_{yL}+Er\cdot M_{rL} \quad \text{Formula (5)}$$

② For accelerated motion (P_{Ta})

$$P_{Ta}=\frac{1}{1.19\cdot n}\cdot W+Ep\,(M_{pL}+m\cdot a_a\cdot Z)+Ey\,(M_{yL}+m\cdot a_a\cdot X)+Er\cdot M_{rL} \quad \text{Formula (6)}$$

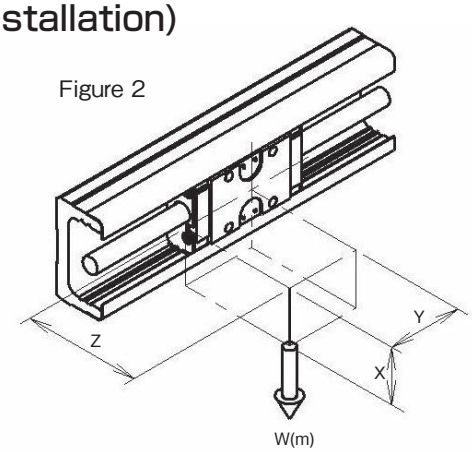
If item $(M_{pL}+m\cdot a_a\cdot Z)$ or $(M_{yL}+m\cdot a_a\cdot X)$ is a negative value, the value should be set to 0.

③ For decelerated motion (P_{Td})

$$P_{Td}=\frac{1}{1.19\cdot n}\cdot W+Ep\,(M_{pL}+m\cdot a_d\cdot Z)+Ey\,(M_{yL}+m\cdot a_d\cdot X)+Er\cdot M_{rL} \quad \text{Formula (7)}$$

If item $(M_{pL}+m\cdot\alpha_d\cdot Z)$ or $(M_{yL}+m\cdot\alpha_d\cdot X)$ is a negative value, the value should be set to 0.

Figure 2



If load is applied from a different direction other than W (m), contact KURODA.

P_{TC} : Calculated load per block in uniform motion (N)
P_{Ta} : Calculated load per block in accelerated motion (N)
P_{Td} : Calculated load per block in decelerated motion (N)
n : Number of block of SG / SE / SC
W : Load (N)
m : Load mass (kg)
α_a : Acceleration in accelerated motion (m/sec²)
α_d : Acceleration in decelerated motion (m/sec²) (with a minus sign)
X : Distance from center of SG / SE / SC to center of gravity of loaded mass (mm)
Y : Distance from center of SG / SE /SC to center of gravity of loaded mass (mm)
Z : Distance from center of SG / SE / SC ballscrew to center of gravity of loaded mass (mm)

E_p : Moment equivalent factor in pitching direction (see Table 3)
E_y : Moment equivalent factor in yawing direction (see Table 3)
E_r : Moment equivalent factor in rolling direction (see Table 3)
M_{pL} : Load moment in pitching direction (N·mm)
$M_{pL} = 0$ (The load moment is zero under this usage.)
M_{yL} : Load moment in yawing direction (N·mm)
$M_{yL} = W \cdot Y$
M_{rL} : Load moment in rolling direction (N·mm)
$M_{rL} = W \cdot Z$

(Note) For the moment directions, see Pages 3, 53 and 101.

● P_T in the Case of Vertical Movement

① For uniform motion (P_{TC})

$$P_{TC}=Ep\cdot M_{pL}+Ey\cdot M_{yL}+Er\cdot M_{rL}$$ ——— Formula (8)

② For accelerated motion (P_{Ta})

$$P_{Ta}=Ep\,(M_{pL}+m\cdot a_a\cdot Z)+Ey\,(M_{yL}+m\cdot a_a\cdot X)+Er\cdot M_{rL}$$ ——— Formula (9)

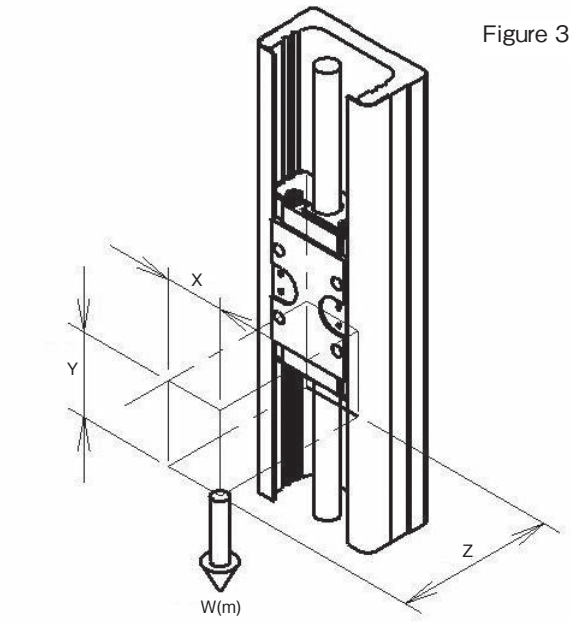
If item $(M_{pL}+m\cdot\alpha_a\cdot Z)$ or $(M_{yL}+m\cdot\alpha_a\cdot X)$ is a negative value, the value should be set to 0.

③ For decelerated motion (P_{Td})

$$P_{Td}=Ep\,(M_{pL}+m\cdot a_d\cdot Z)+Ey\,(M_{yL}+m\cdot a_d\cdot X)+Er\cdot M_{rL}$$ ——— Formula (10)

If item $(M_{pL}+m\cdot\alpha_d\cdot Z)$ or $(M_{yL}+m\cdot\alpha_d\cdot X)$ is a negative value, the value should be set to 0.

Figure 3



If load is applied from a different direction other than W (m) in this figure, contact KURODA.

P_{TC} : Calculated load per block in uniform motion (N)
P_{Ta} : Calculated load per block in accelerated motion (N)
P_{Td} : Calculated load per block in decelerated motion (N)
n : Number of block of SG / SE / SC
W : Load (N)
m : Load mass (kg)
α_a : Acceleration in accelerated motion (m/sec^2)
α_d : Acceleration in decelerated motion (m/sec^2) (with a minus sign)
X : Distance from center of SG / SE / SC to center of gravity of loaded mass (mm)
Y : Distance from center of SG / SE / SC to center of gravity of loaded mass (mm)
Z : Distance from center of SG / SE / SC ballscrew to center of gravity of loaded mass (mm)

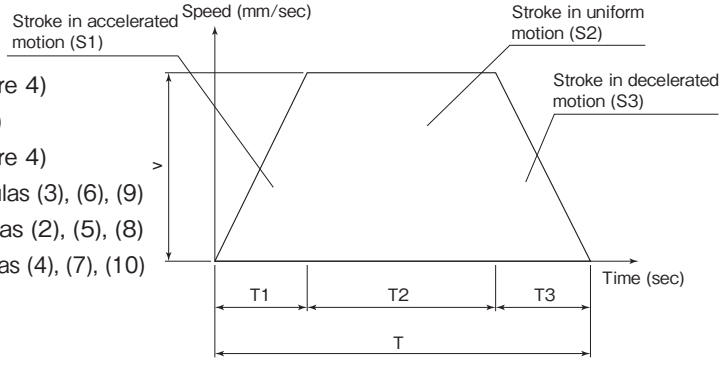
E_p : Moment equivalent factor in pitching direction (see Table 3)
E_y : Moment equivalent factor in yawing direction (see Table 3)
E_r : Moment equivalent factor in rolling direction (see Table 3)
M_{pL} : Load moment in pitching direction (N·mm)
$M_{pL} = W \cdot Z$
M_{yL} : Load moment in yawing direction (N·mm)
$M_{rL} = W \cdot X$
M_{rL} : Load moment in rolling direction (N·mm)
$M_{yL} = 0$ (The load moment is zero under this usage.)

(Note) For the moment directions, see Pages 3, 53 and 101.

● Using one of the above calculation formulas according to your usage, calculate average load in each motion to obtain calculated load per block (P_T).

$$P_T=\sqrt[3]{\frac{1}{(S1+S2+S3)}\left(P_{Ta}^{\,3}\cdot S1+P_{TC}^{\,3}\cdot S2+P_{Td}^{\,3}\cdot S3\right)}$$ ——— Formula (11)

Formula 4



P_T : Calculated load per block (N)
S1 : Traveling distance in accelerated motion (mm) (see Figure 4)
S2 : Traveling distance in uniform motion (mm) (see Figure 4)
S3 : Traveling distance in decelerated motion (mm) (see Figure 4)
P_{Ta} : Calculated load per block in accelerated motion (N) - Formulas (3), (6), (9)
P_{TC} : Calculated load per block in uniform motion (N) - Formulas (2), (5), (8)
P_{Td} : Calculated load per block in decelerated motion (N) - Formulas (4), (7), (10)

● LIFE EXPECTANCIES OF BALL SCREW AND SUPPORT BEARING

The life expectancies of the ball screw and the support bearing can be calculated using the following common calculation formula shown as below. Therefore, compare the dynamic load ratings of the ball screw and the support bearing and substitute a smaller value in the formula for calculation.

$$L_a = \left(\frac{1}{f_W} \cdot \frac{C_a \text{ or } C_b}{P_a} \right)^3 \cdot \ell \quad \text{——Formula (12)}$$

L_a : Life expectancy operational length (km)
f_W : Load factor (see Table 2)
C_a : Basic dynamic load rating of ball screw (N)
C_b : Basic dynamic load rating of support bearing (N)
P_a : Ave. Axial load (N)
ℓ : Ball screw lead (mm)

● Calculation of Pa

To calculate the life expectancy using Formula (6), calculate Pa in consideration of acceleration. Calculate the axial load in uniform, accelerated, and decelerated motions and its average figure is used as Pa.

● In the Case of Horizontal Movement

① For uniform motion (P_{ac})

$$P_{ac} = m \cdot W + F + F_b \cdot n \quad \text{——Formula (13)}$$

② For accelerated motion (P_{aa})

$$P_{aa} = m \cdot W + F + f_b \cdot n + (m + m_b \cdot n)\, \alpha_a \quad \text{——Formula (14)}$$

③ For decelerated motion (P_{ad})

$$P_{ad} = m \cdot W + F + f_b \cdot n - (m + m_b \cdot n)\, \alpha_d \quad \text{——Formula (15)}$$

P_{ac} : Axial load in uniform motion (N)
P_{aa} : Axial load in accelerated motion (N)
P_{ad} : Axial load in decelerated motion (N)
μ : Friction factor (0.006)
W : Load on block (N)
F : External force (load) in axial direction (N)
f_b : Slide resistance per block (N) (see Table 4)
n : Number of blocks of SG / SE
m : Load mass (kg)
m_b : Block mass of SG / SE (kg)
g : Gravitational acceleration (9.8 m / sec^2)
α_a : Acceleration in accelerated motion (m / sec^2)
α_d : Acceleration in decelerated motion (m / sec^2)

● In the Case of Vertical Movement

① For uniform motion (P_{ac})

$$P_{ac} = (m + m_b \cdot n)\, g + F + f_b \cdot n \quad \text{——Formula (16)}$$

② For accelerated motion (P_{aa})

$$P_{aa} = (m + m_b \cdot n) \cdot (g + \alpha_a) + F + f_b \cdot n_a \quad \text{——Formula (17)}$$

③ For decelerated motion (P_{ad})

$$P_{ad} = (m + m_b \cdot n) \cdot (g - \alpha_d) + F + f_b \cdot n_d \quad \text{——Formula (18)}$$

● Using one of the above calculation formulas according to your usage, calculate an average axial load (Pa).

$$P_a = \sqrt[3]{\frac{1}{(S1+S2+S3)} \left(P_{aa}^{\,3} \cdot S1 + P_{ac}^{\,3} \cdot S2 + P_{ad}^{\,3} \cdot S3 \right)} \quad \text{——Formula (19)}$$

P_a : Average axial load (N)
S1 : Traveling distance in accelerated motion (mm) (see Figure 4)
S2 : Traveling distance in uniform motion (mm) (see Figure 4)
S3 : Traveling distance in decelerated motion (mm) (see Figure 4)
P_{aa} : Axial load in accelerated motion (N) - Formulas (14), (17)
P_{ac} : Axial load in uniform motion (N) - Formulas (13), (16)
P_{ad} : Axial load in decelerated motion (N) - Formulas (15), (18)

Table 4 Slide resistance per block (f_b) (seal resistance)

(Unit: N)

Model No.	Accuracy grade	
	H	P
SG20	2.3	4.9
SG26	5.4	9.8
SG33	4.4	10.2
SG46	7.4	13.3
SG55	9	16

(Unit: N)

Model No.	Accuracy grade
	H/U/W
SE15	2.0
SE23, SC23	2.5
SE30, SC30	2.5
SE45, SC45	7.5

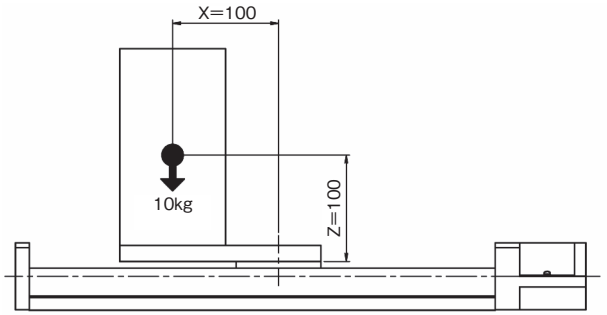
EXAMPLE OF BALLSCREW ACTUATOR SELECTION

● Linear motion robot - X-axis

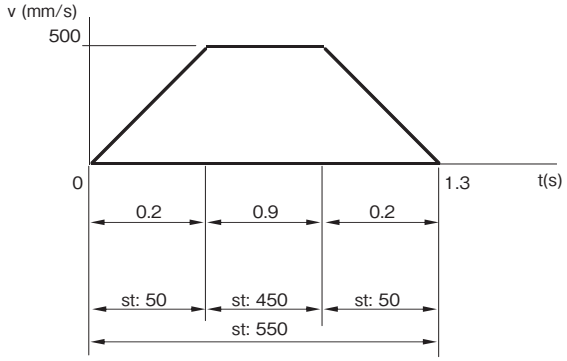
<Specifications>

Mass of work and table: M	10kg
Load distribution	See right side diagram.
Maximum stroke: st	550mm
Fast-feed speed: v	500mm/s
Acceleration/deceleration time constant: t	0.2 s
Maximum motor speed	6000min^{-1}
Orientating orientation	Horizontal
Repeated positioning accuracy	±0.01 mm or less
Expected life	30,000h

Load distribution diagram



Duty cycle model diagram



① Tentatively select SE4510A-740W-A1NN-NN in SE series, based on the conditions such as stroke and speed.

② Calculation of life expectancy

②-1. Calculating life expectancy of guide

Considering the usage with moment being loaded, average load and life expectancy were calculated in accordance with "LIFE EXPECTANCY OF GUIDE" on page 127, and they resulted in 1,274 N and 39,030 hours, respectively. The load coefficient for the above calculation was determined to be 2, based on the conditions of use.

②-2. Calculating expected life of ball screw and support bearings

Average axial load and life expectancy were calculated in accordance with "LIFE EXPECTANCIES OF BALL SCREW AND SUPPORT BEARING" on page 130, and the axial load resulted in 14.9 N and expected life of both ball screw and support bearing in over a million hours. The load coefficient for the above calculation was determined to be 2, based on the conditions of use.

③ Results of the selection

The above calculation results of life expectancies confirmed that the tentatively selected model would satisfy the required specifications. Since there is no other particular specification to be further considered, the model is selected officially.

Selected model of ballscrew actuator: SE4510A-740W-A1NN-NN

If longer life expectancy than the calculated life is preferred, make re-calculation after changing specifications, such as upgrading model size or adding extra slide block.

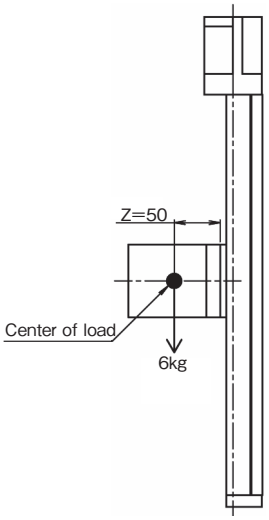
EXAMPLE OF BALLSCREW ACTUATOR SELECTION

● Lift - Z-axis

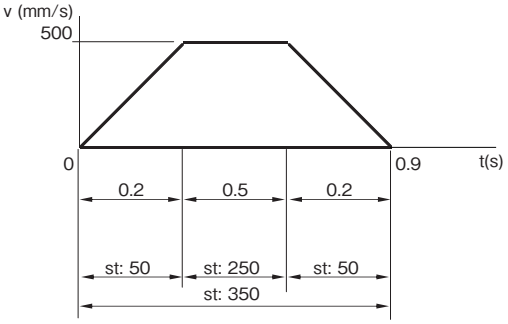
<Specifications>

Mass of work and table: M	6kg
Load distribution	See right side diagram.
Maximum stroke: st	350mm
Fast-feed speed: v	500mm/s
Acceleration/deceleration time constant: t	0.2 s
Maximum motor speed	6000min^{-1}
Orientating orientation	Vertical
Repeated positioning accuracy	±0.003 mm or less
Life expectancy	40,000h

Load distribution diagram



Duty cycle model diagram



① Tentative selection of ballscrew actuator

Tentatively select SG3310A-500H-A0NN-NN in SG series, based on the conditions such as strokes and speed.

② Calculation of life expectancy

②-1. Calculating life expectancy of guide

Considering the usage with moment being loaded, average load and life expectancy were calculated in accordance with "LIFE EXPECTANCY OF GUIDE" on page 127, and they resulted in 805 N and 17,166 hours, respectively. The load coefficient for the above calculation was determined to be 2, based on the conditions of use.

②-2. Calculating expected life of ball screw and support bearing

Average axial load and life expectancy were calculated in accordance with "LIFE EXPECTANCIES OF BALL SCREW AND SUPPORT BEARING "on page 130, and the axial load resulted in 60N and expected life of ball screw and support bearing in 44,202 and 353,620 house, respectively. The load coefficient for the above calculation was determined to be 2, based on the conditions of use.

③ Results of the selection

According to the above results of life expectancies, the life of the guide does not satisfy the life expectancy requirement. Since the ball screw and support bearing have satisfactory life expectancies, make re-calculation after changing the block on the guide. Leaving the guide rail length and required stroke as they are, change the model to SG3310D-500H-A0NN-NN.

④ Re-calculation of life

As in the previous step, average load and life expectancy were calculated in accordance with "LIFE EXPECTANCY OF GUIDE" on page 127, and they resulted in 198 N (load per block) and 146,740 hours, respectively.

⑤ Results of the re-selection

The results of re-calculation of life expectancy of the guide confirmed that the selected model would satisfy required hours of life expectancy.

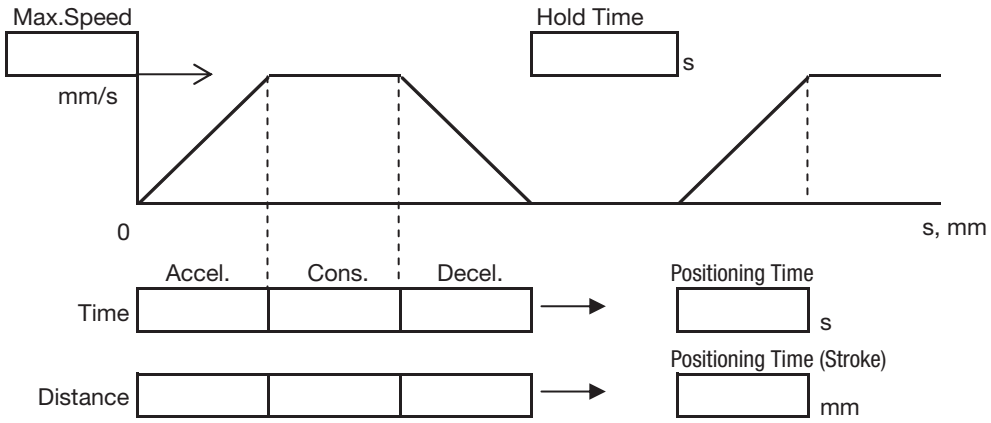
BALLSCREW ACTUATOR SPECIFICATION DATA SHEET

Company Name		Date	
Department		Contact personnel	
Adress		Tel / Fax	
Name of Equipment/machine used		Location of use	
Drawing/conceptual drawing attached?	☐Yes pieces of pages	☐No	

Conditions of Use (Either unit system may be used.)

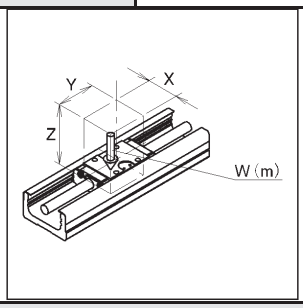
Mass of work and table (kg)			
Operating orientation	☐Horizontal ☐Vertical ☐Wall installation		
Maximum table speed (mm/s)		Maximum table stroke (mm)	
Expected life (h)			

Operating conditions

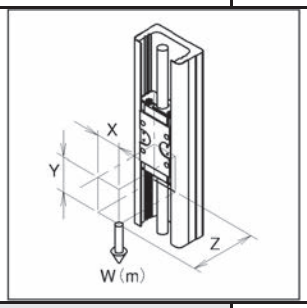


Load distribution (see below)	X = mm	Y = mm	Z = mm	

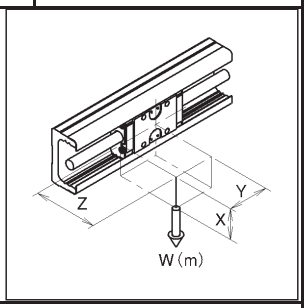
Horizontal



Vertical



Wall installation



Grease (brand) / Unless otherwise specified, Multemp PS No. 2 Grease (KYODO YUSHI CO.,LTD.) will be used as lubricant.								
Environmental conditions	Temp.	Dust	Humidity	Gas	Liquid	Clean room	Vacuum	Others
			%					
Name of motor					Parallel motor mounting		☐Required	☐Not required
Actuator quantity per a machine				Quantity for prototype				
Quantity of mass production			Change control		☐Yes		☐No	

Ballscrew actuator specifications

Size		Lead		Slide block		Guide rail length	Precision grade	
Dust-preventive cover		Sensor	Type:		Qty:		Surface treatment	

Additional description / request

*KURODA office		*Contact personnel	